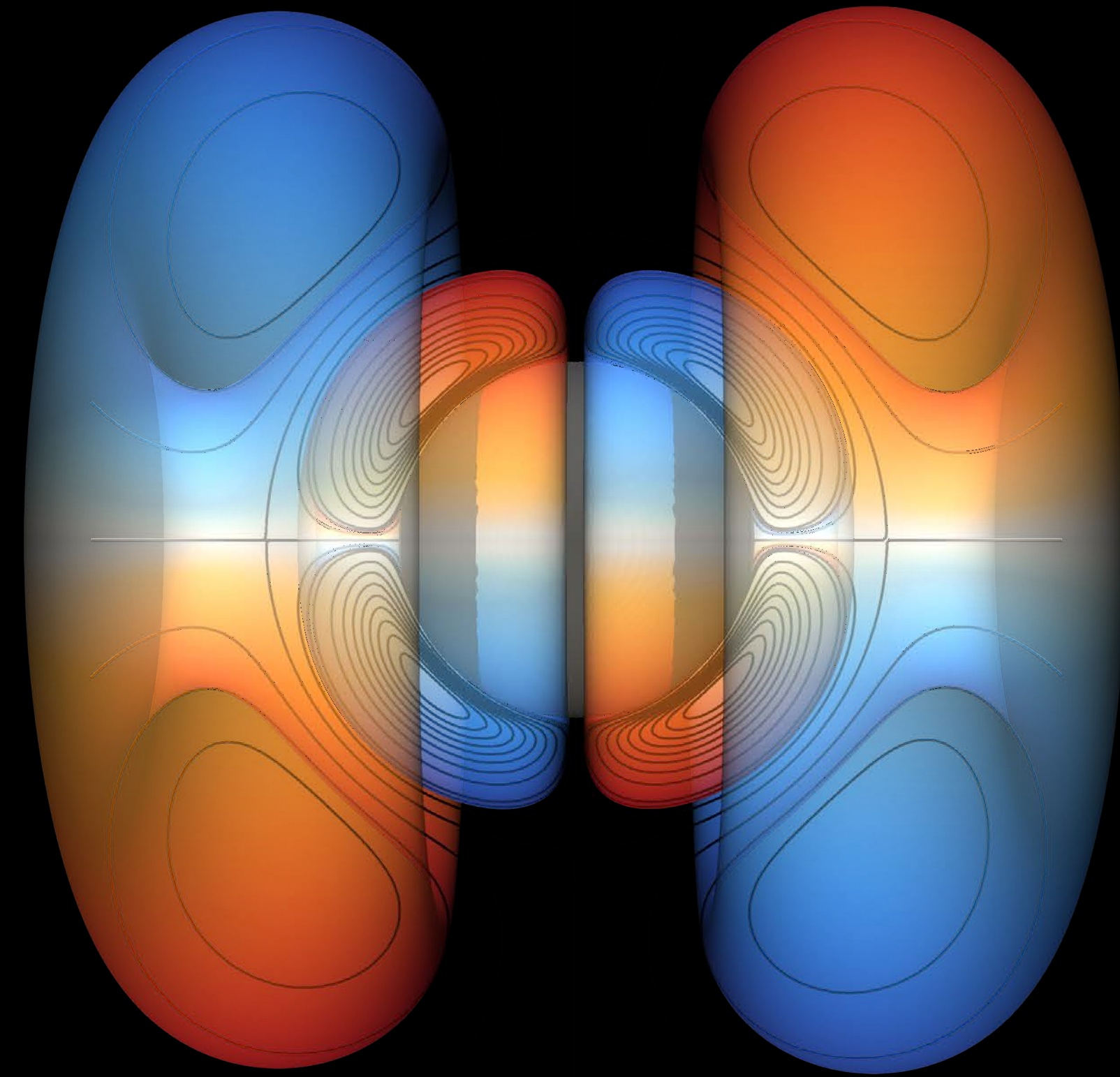


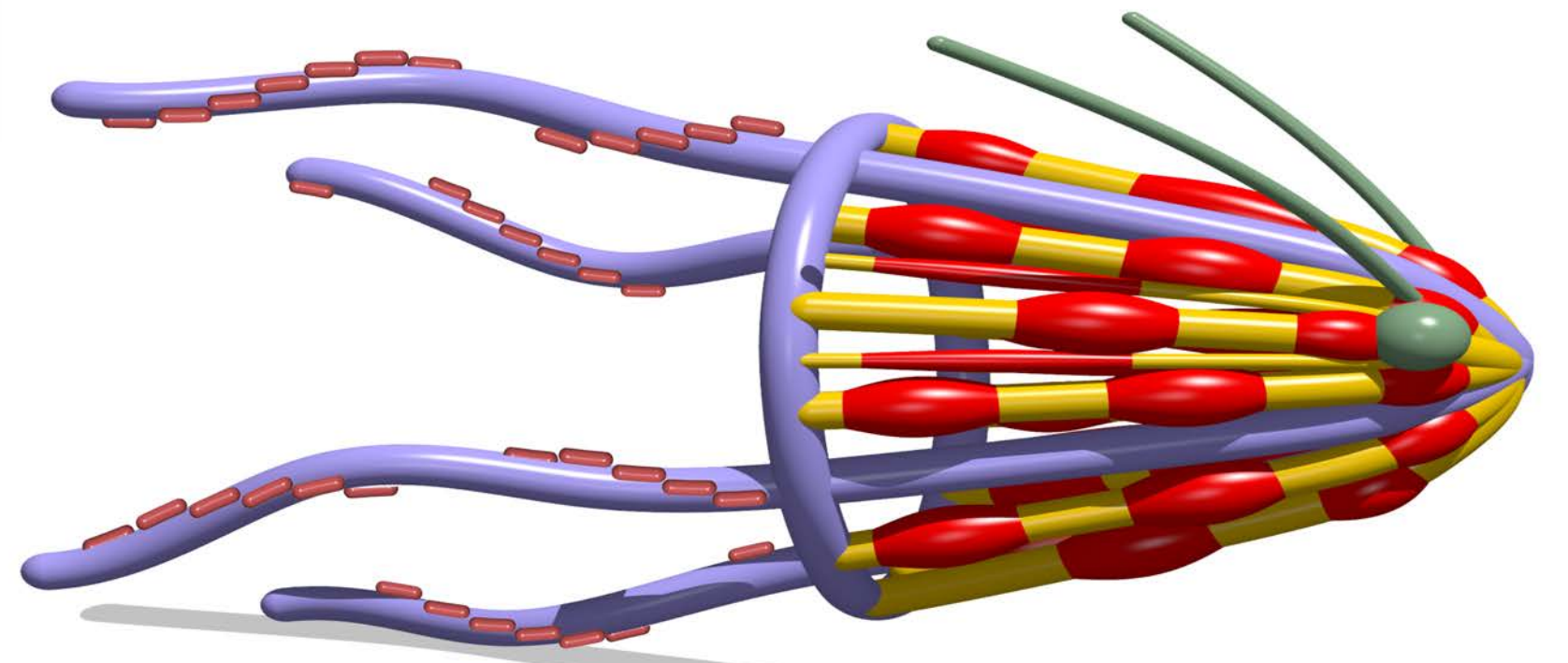
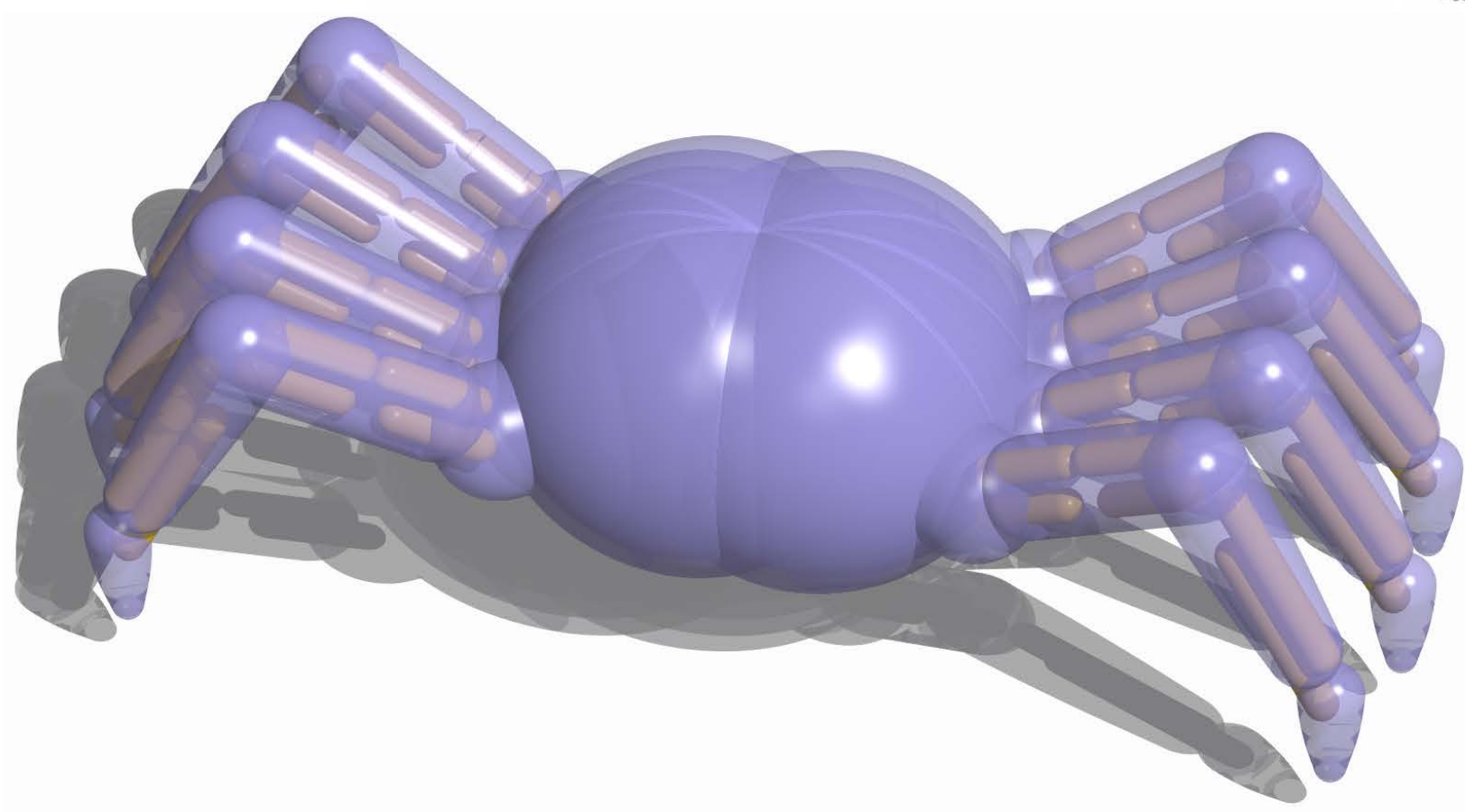
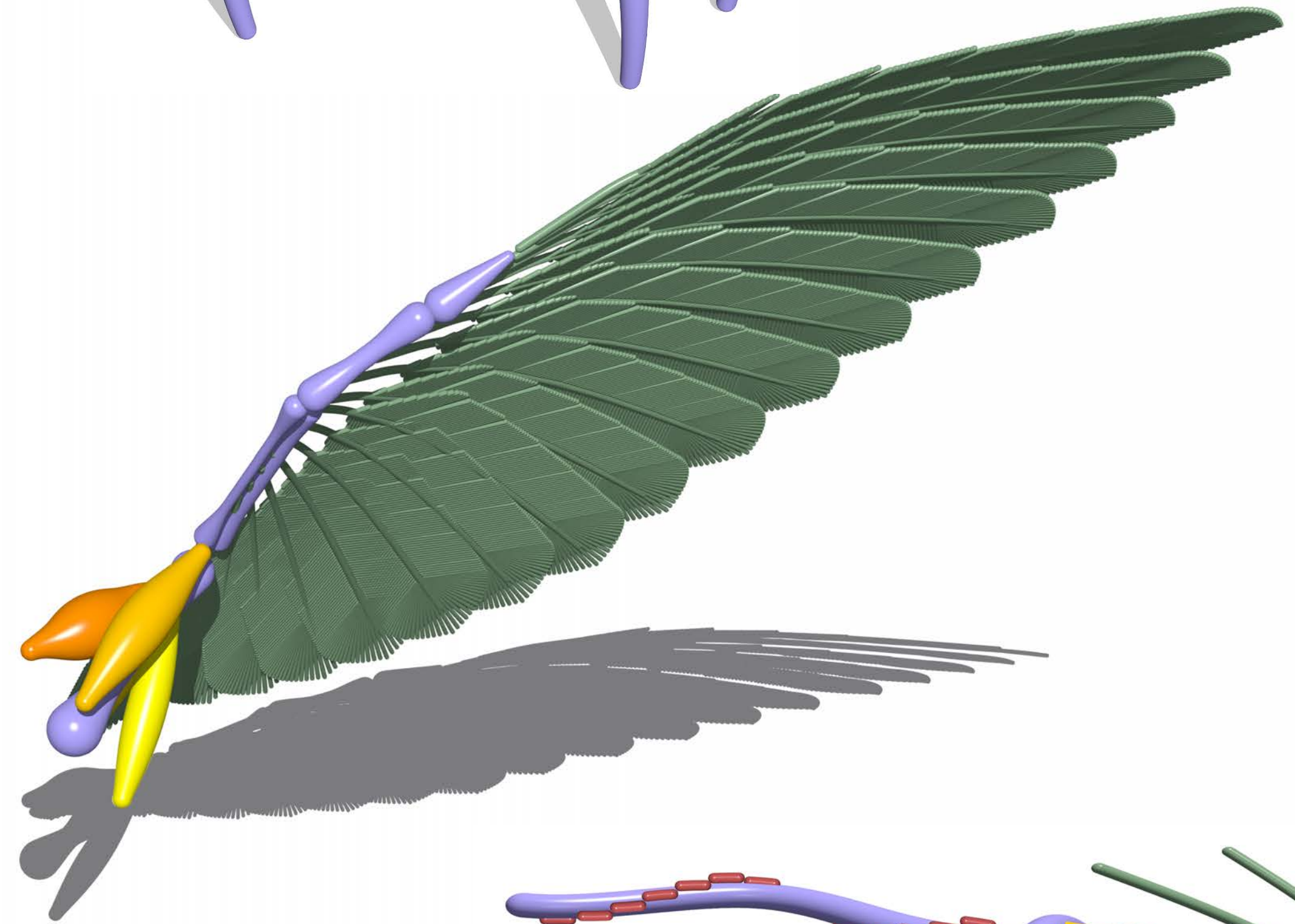
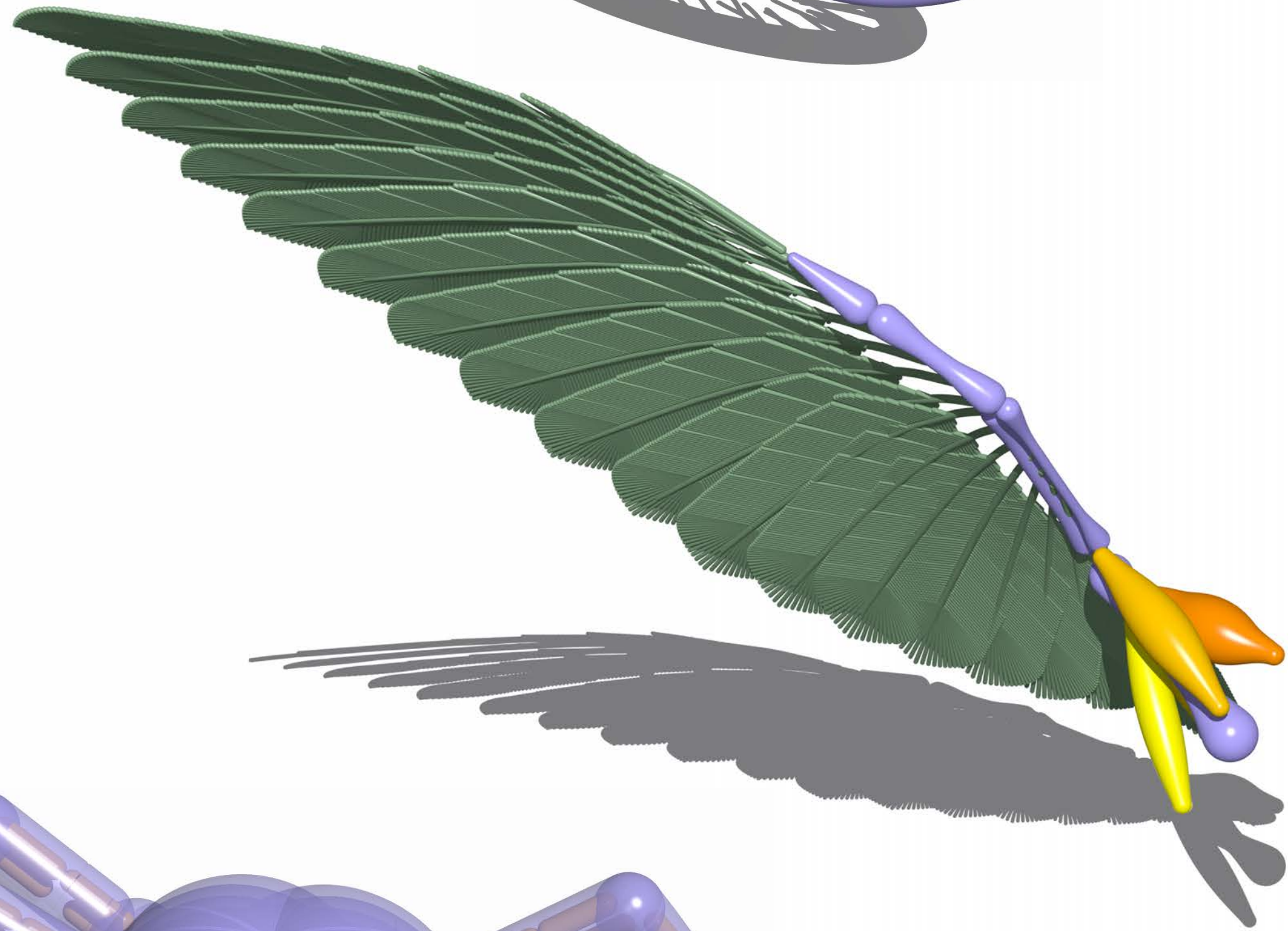
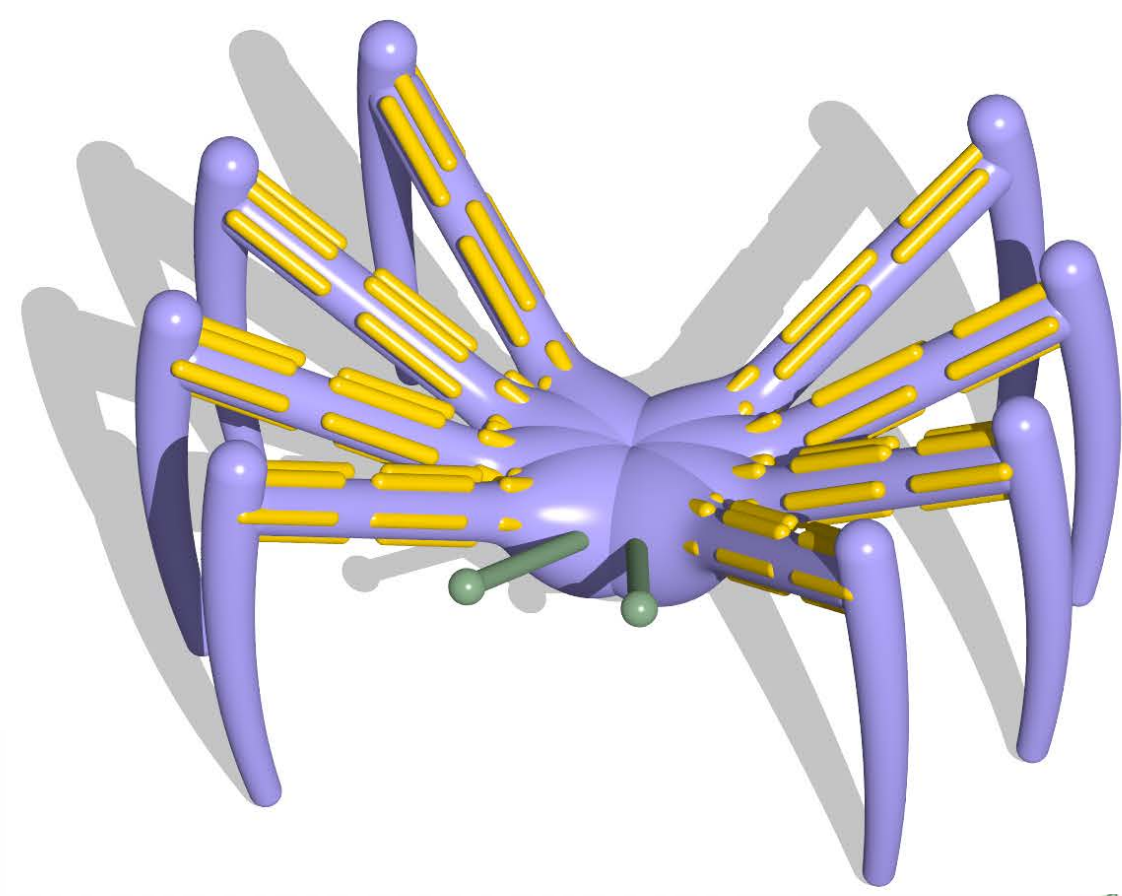
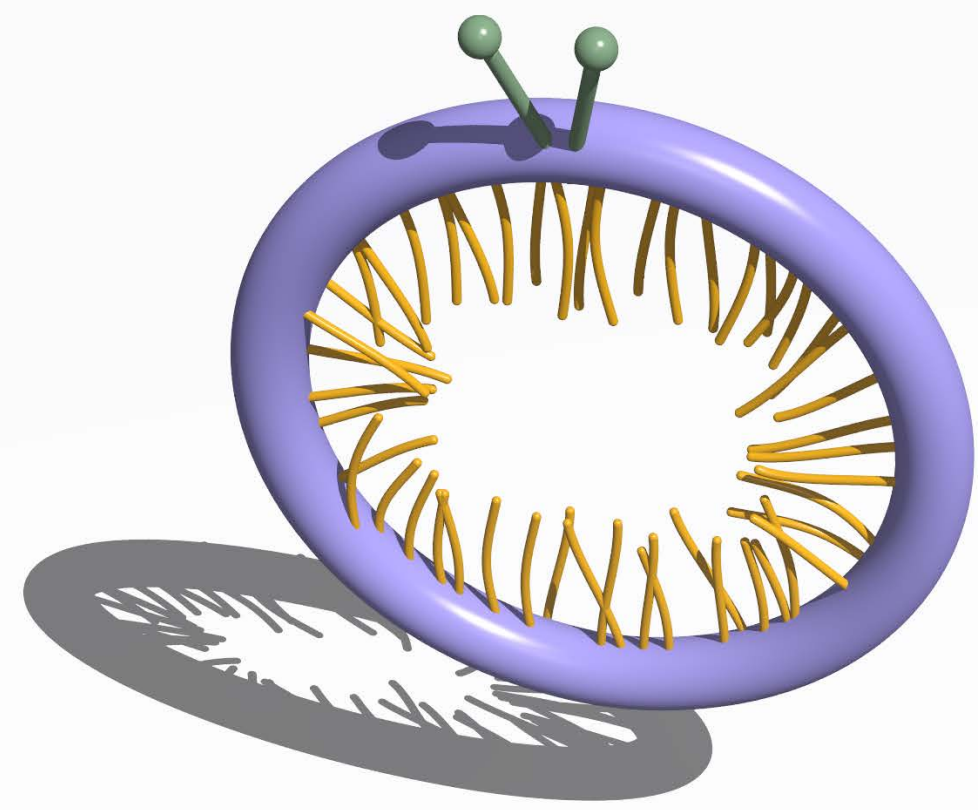


# Harnessing viscous streaming in complex active systems

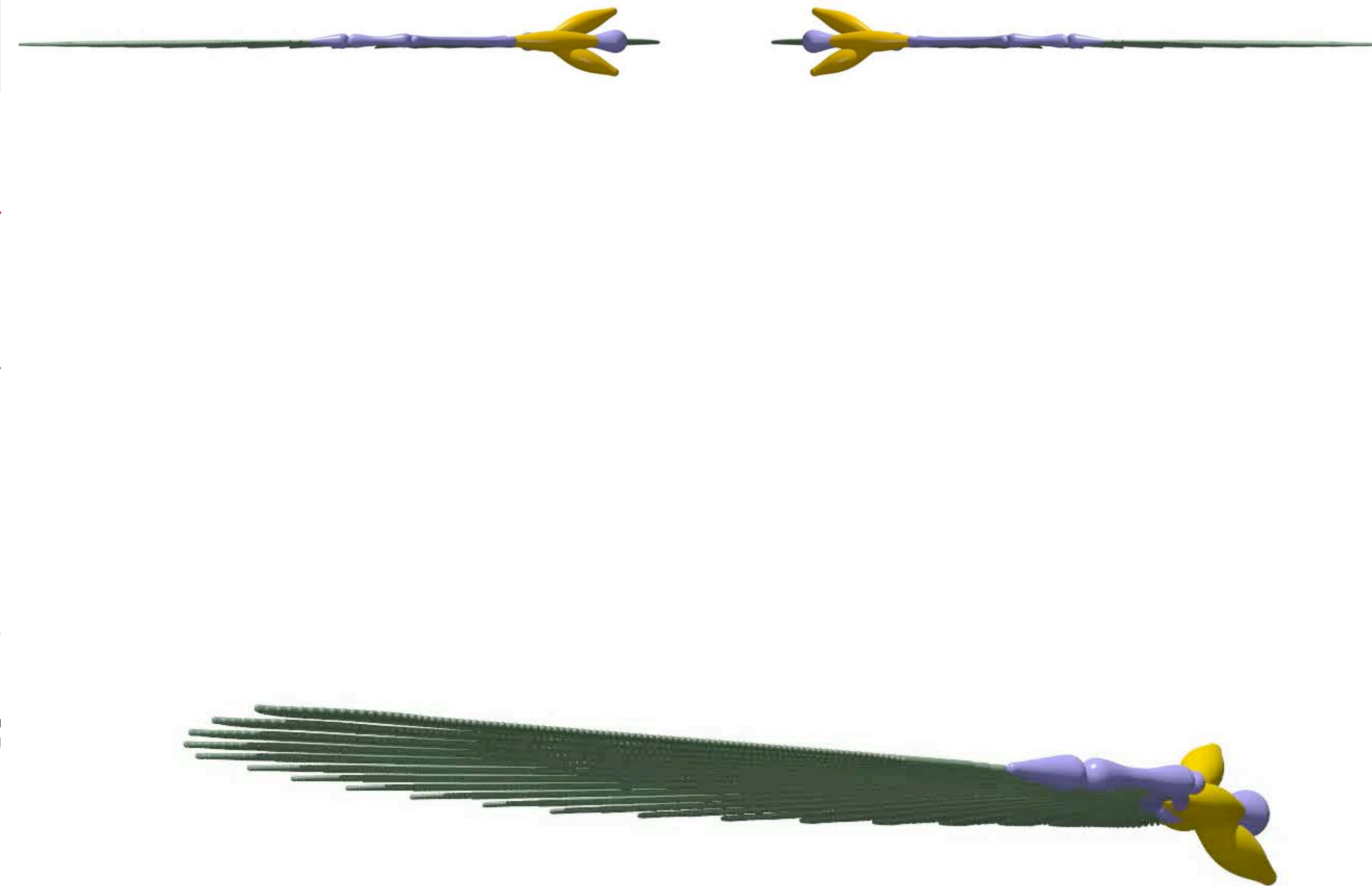
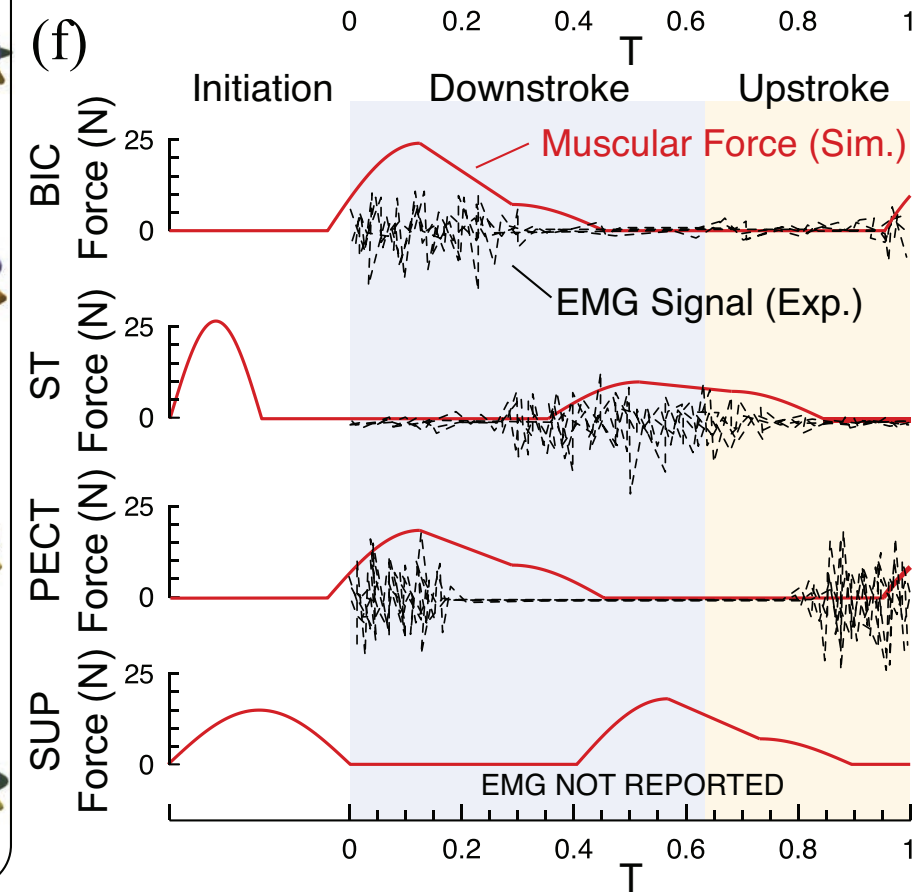
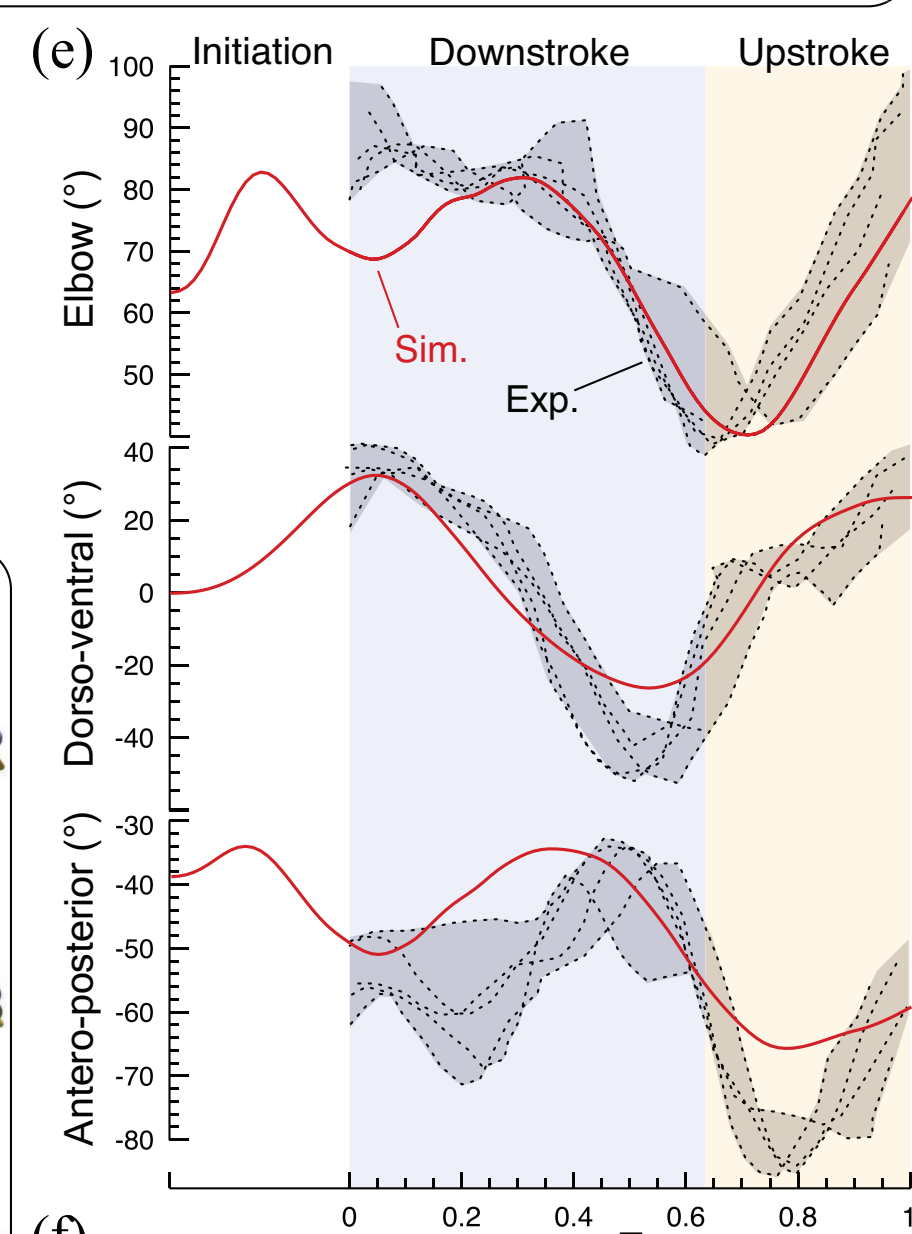
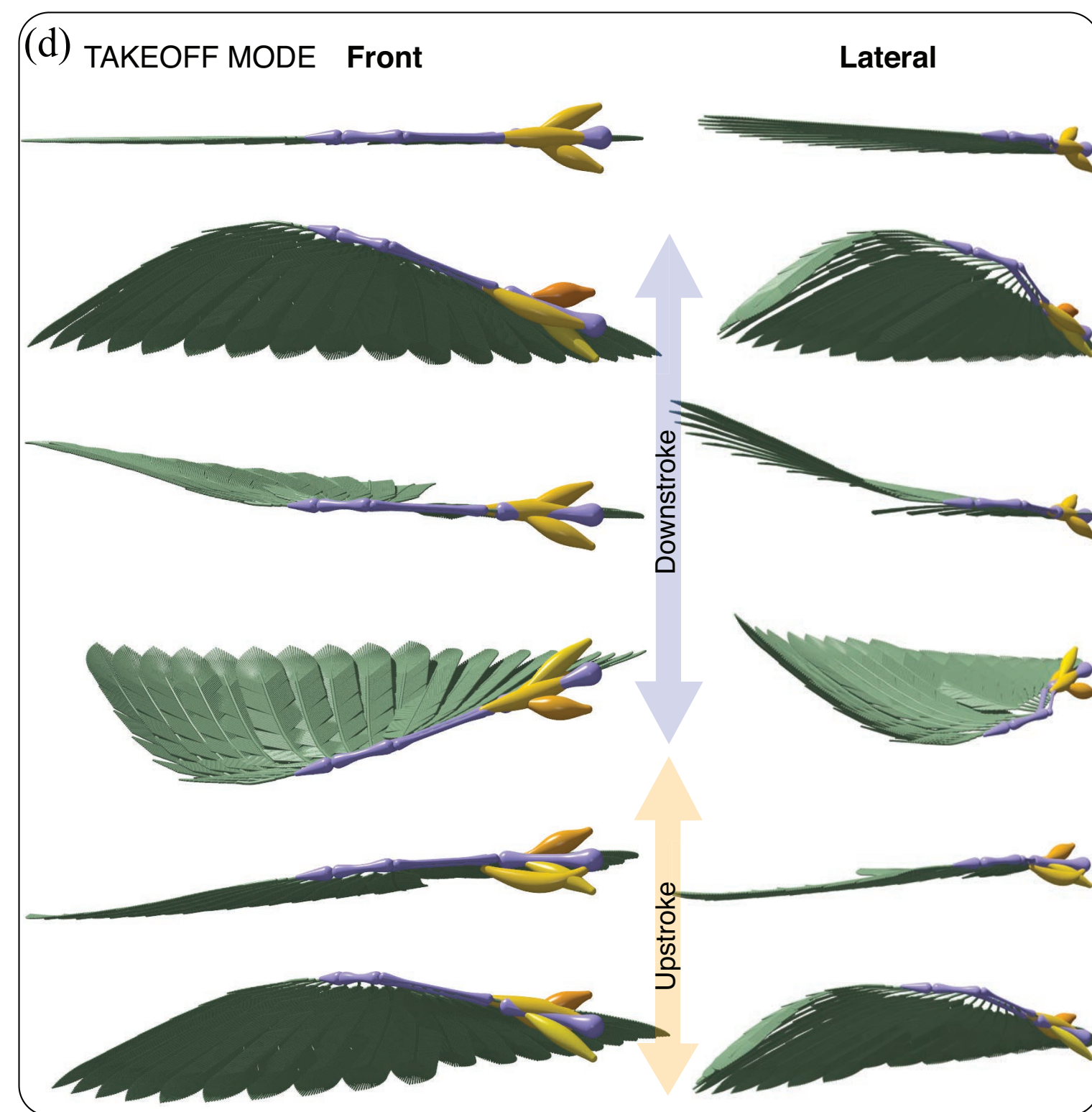
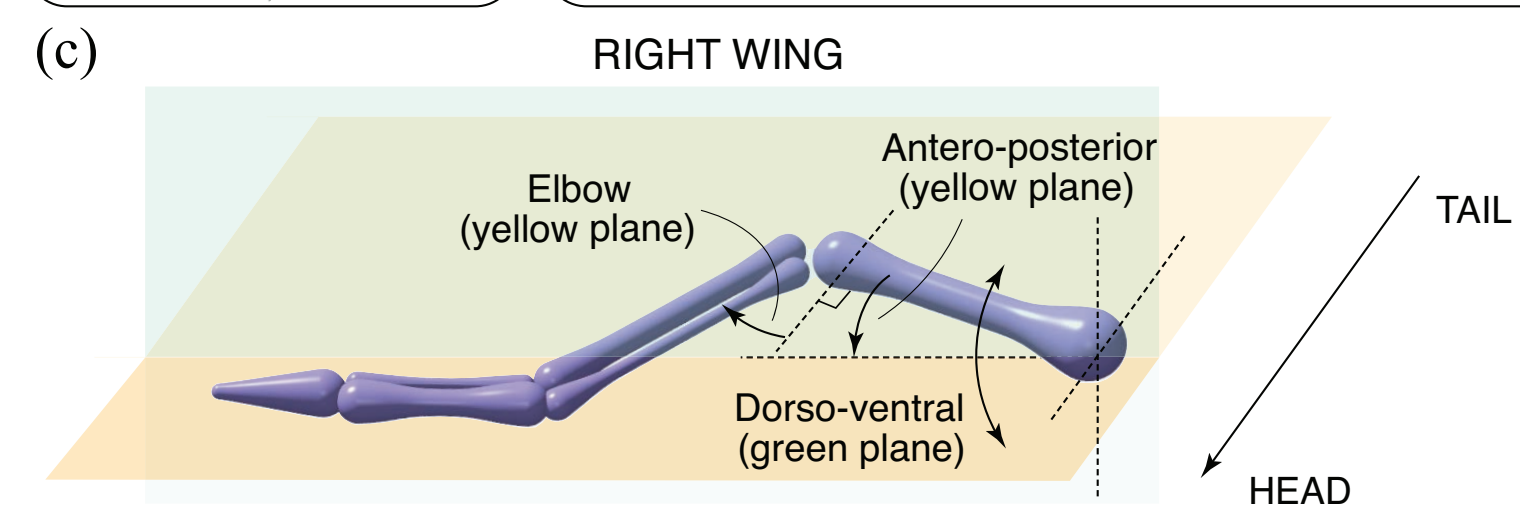
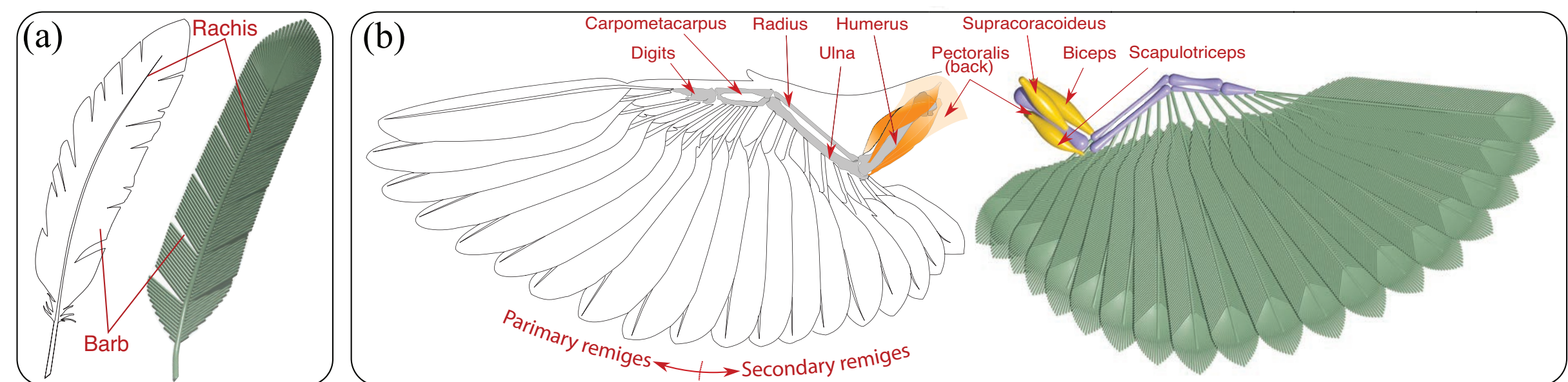


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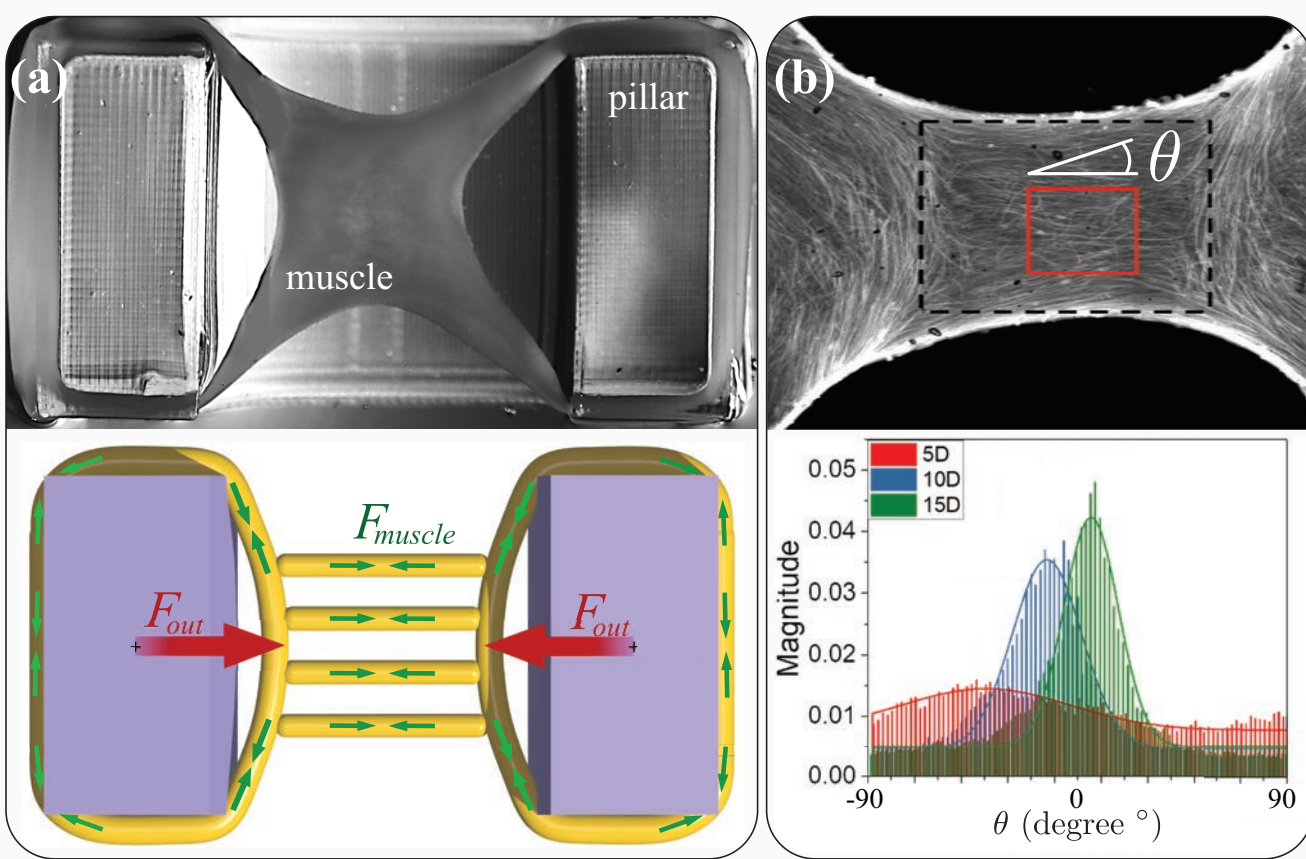




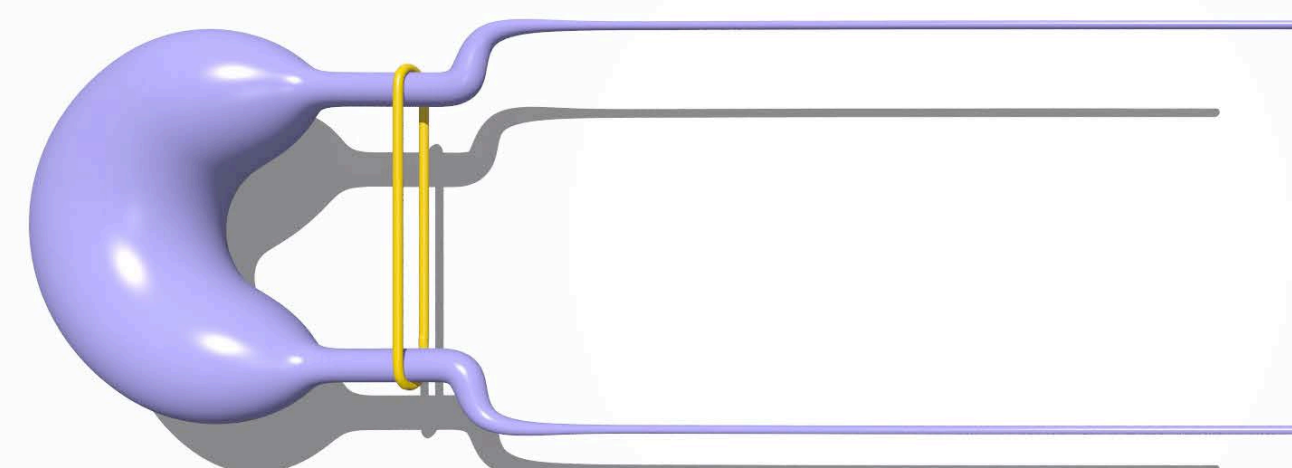
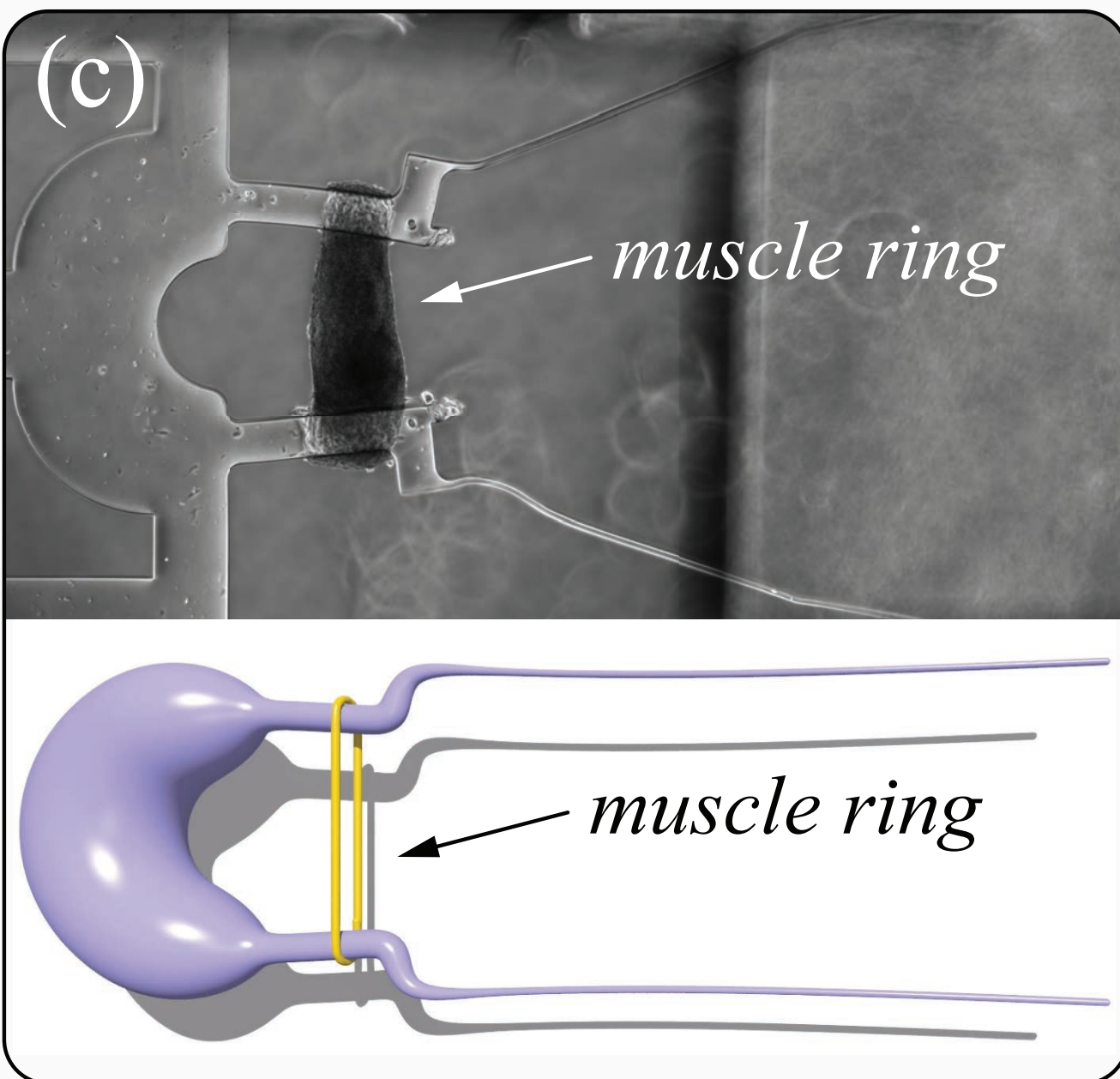
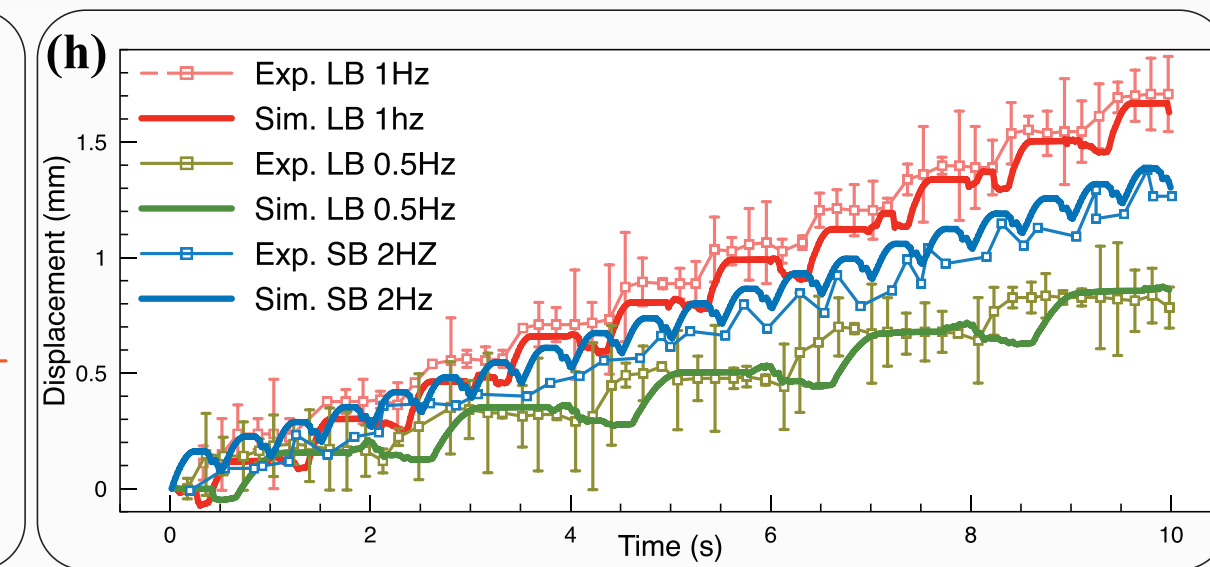
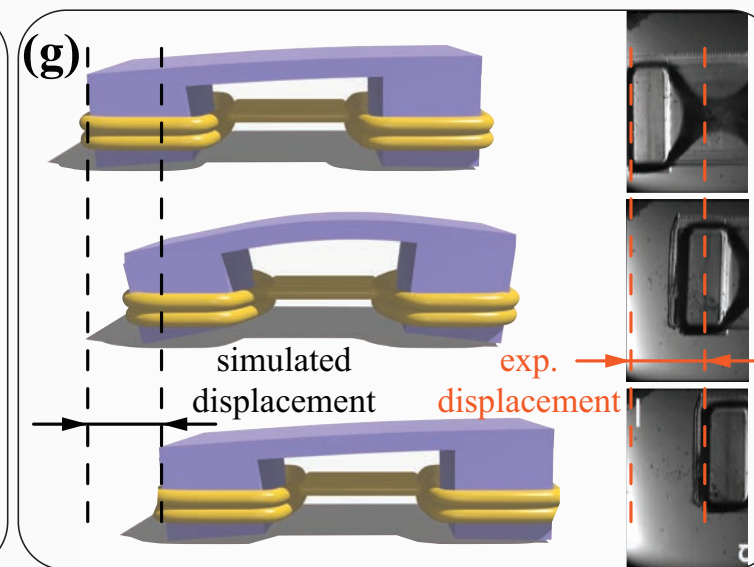
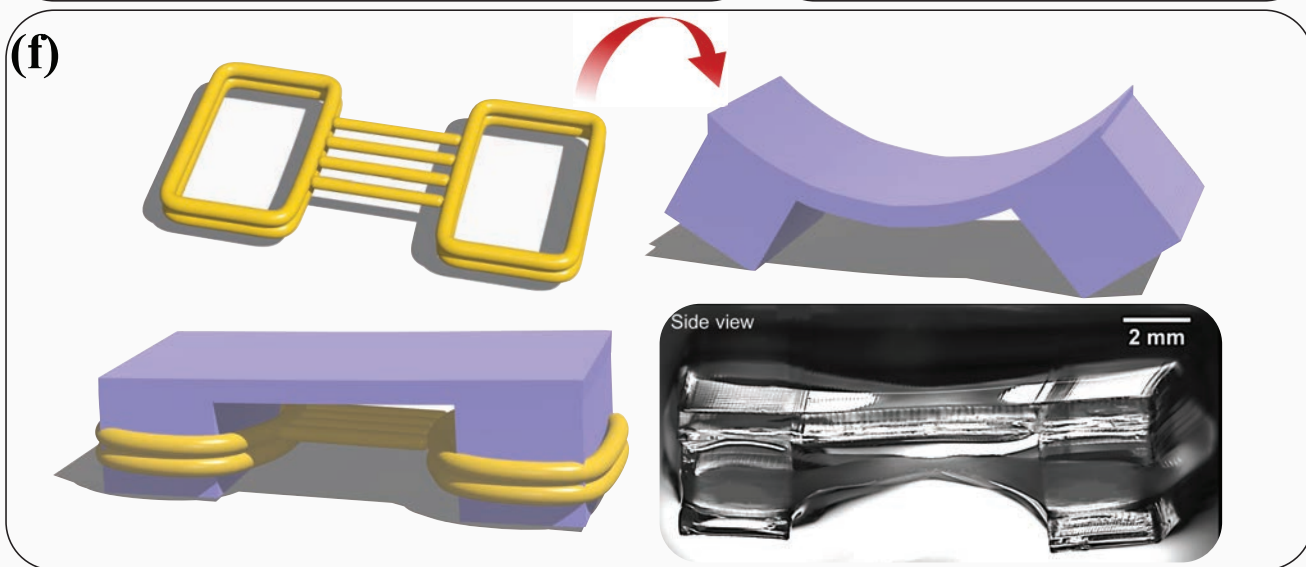




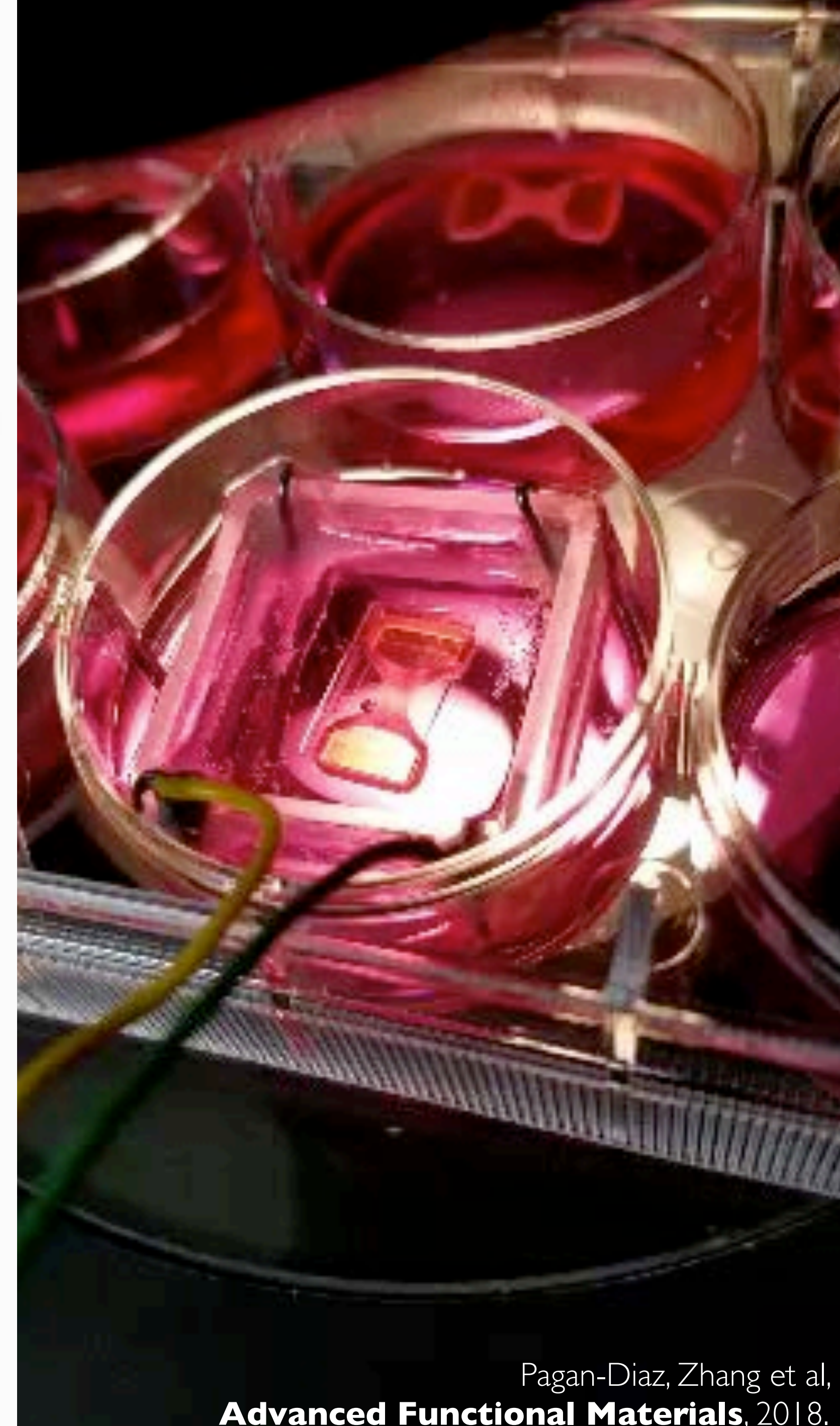
CHARACTERIZATION & MODELING



PREDICTIVE DESIGN



Aydin, Zhang et al. **Under revision PNAS**, 2019.

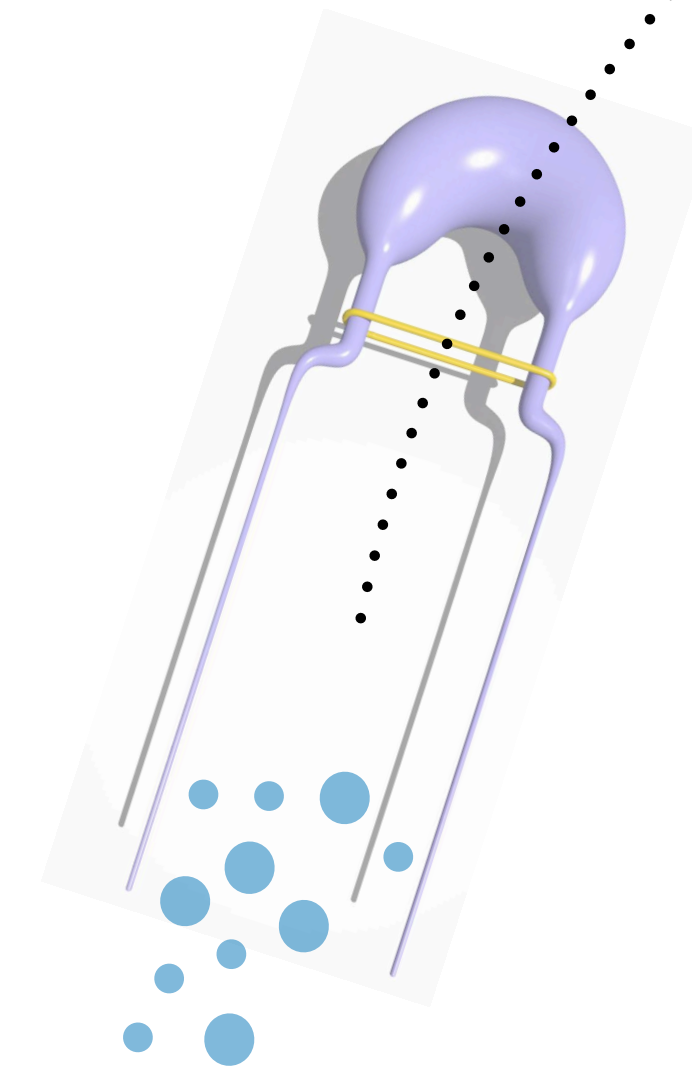
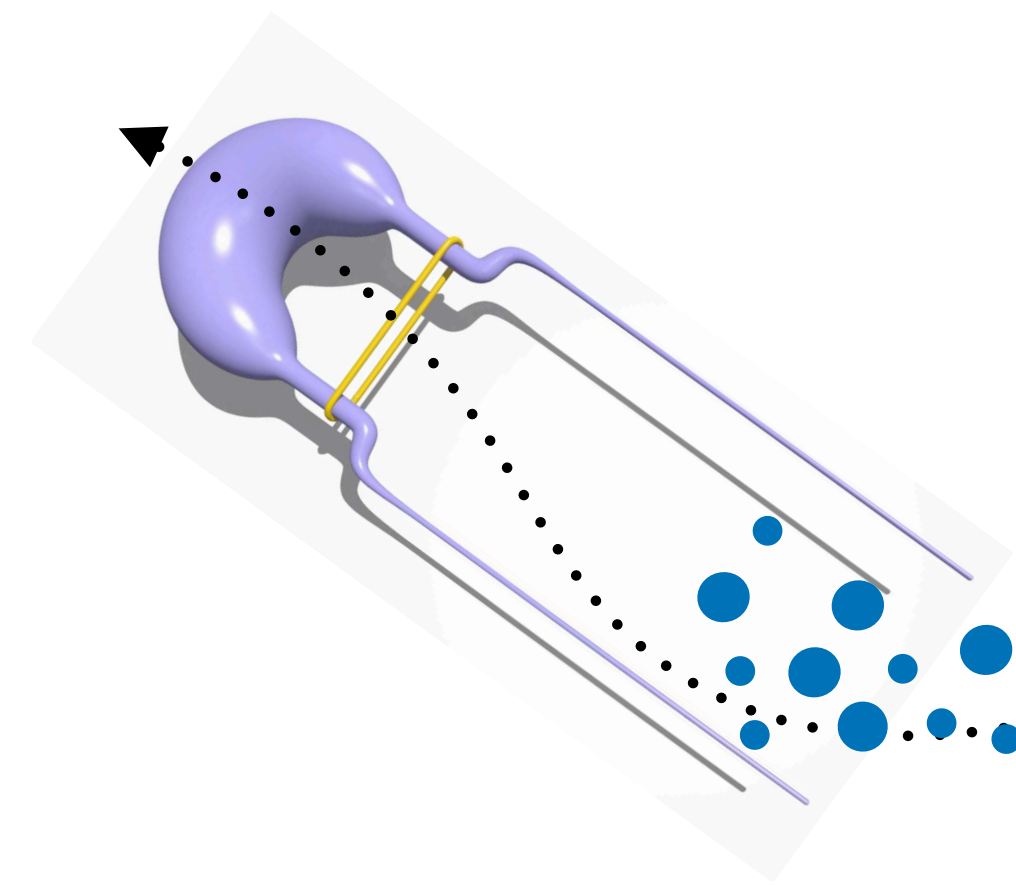


Pagan-Diaz, Zhang et al. **Advanced Functional Materials**, 2018.





Van Dyke '82



FLOW  
CONTROL

CONTROL



Streamfunction

$\nu$

DF Layer

$2a$

$\omega, \epsilon a$

$$X = X_{cm} + \epsilon a \sin(\omega t)$$

$$U_o = \epsilon \omega a$$

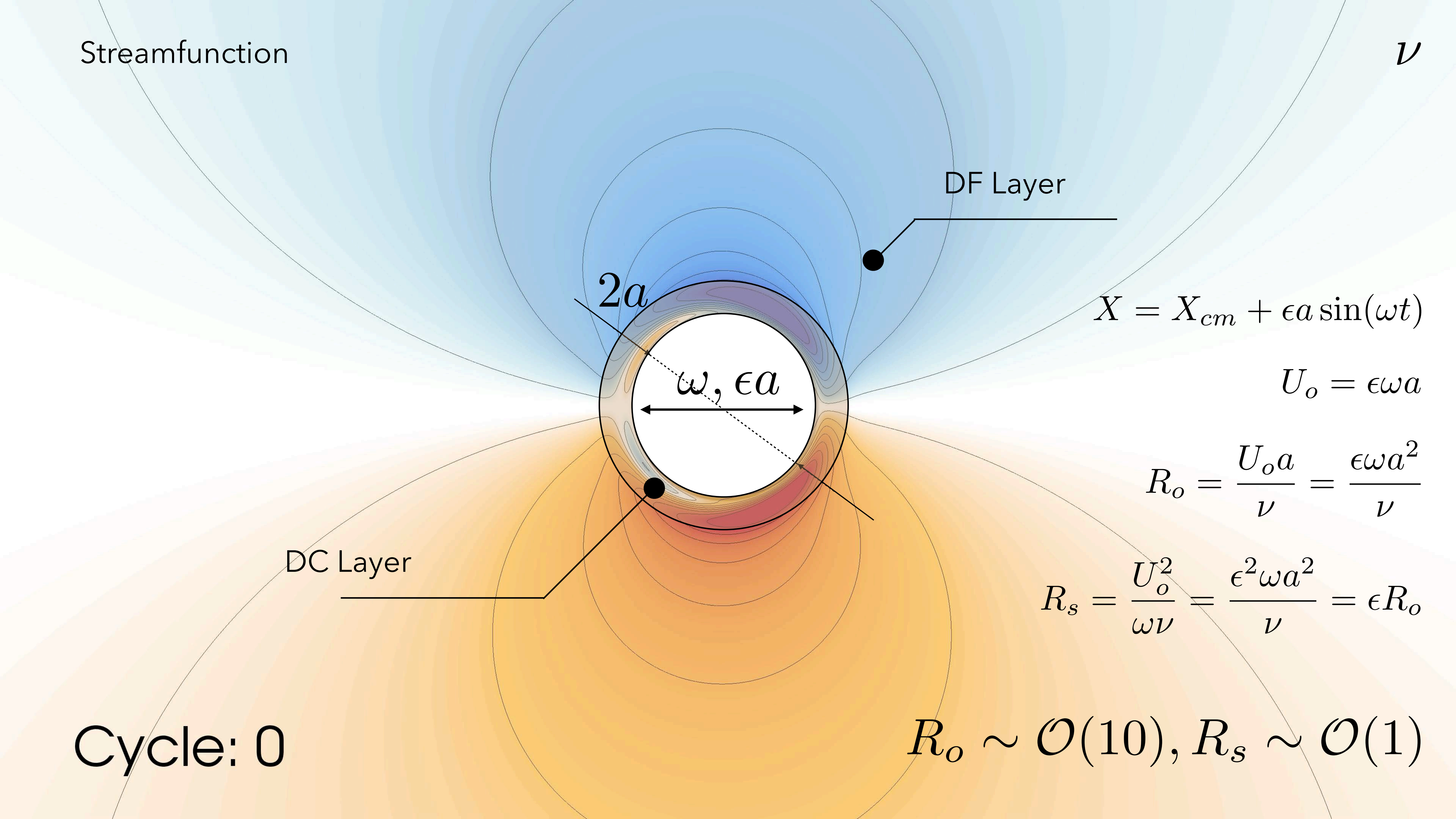
$$R_o = \frac{U_o a}{\nu} = \frac{\epsilon \omega a^2}{\nu}$$

$$R_s = \frac{U_o^2}{\omega \nu} = \frac{\epsilon^2 \omega a^2}{\nu} = \epsilon R_o$$

DC Layer

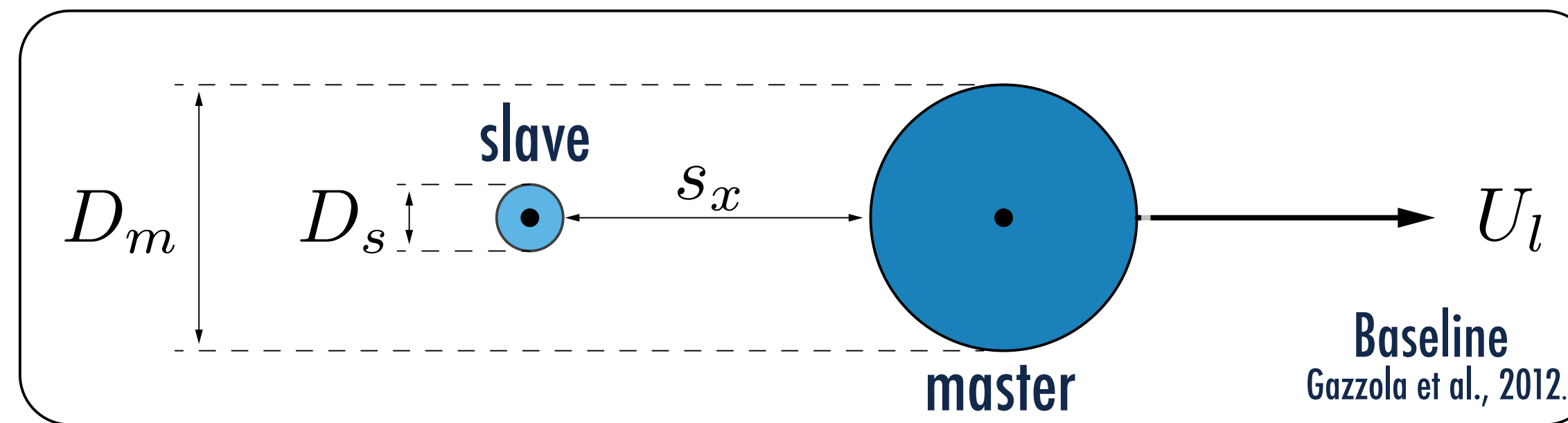
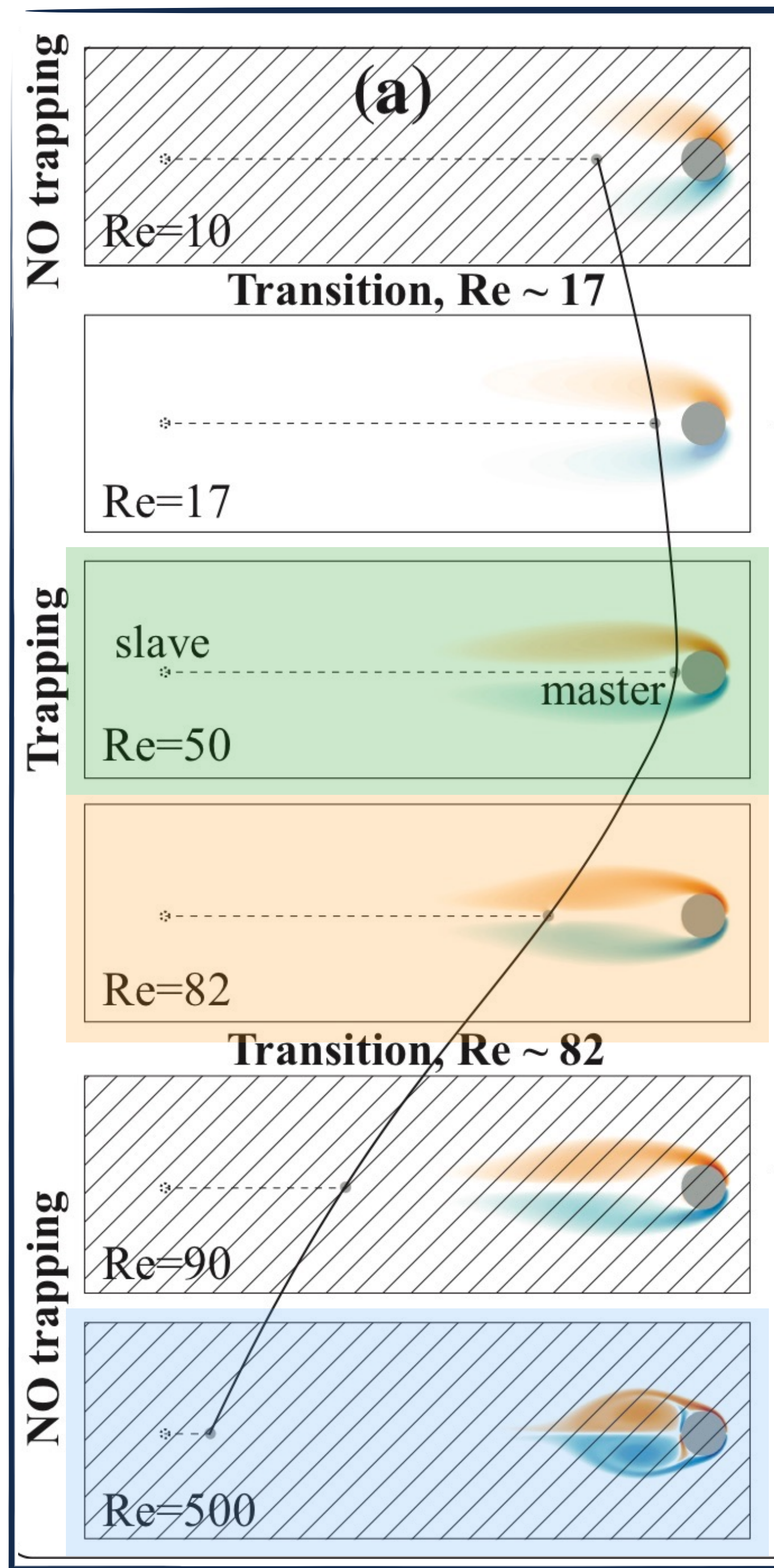
Cycle: 0

$$R_o \sim \mathcal{O}(10), R_s \sim \mathcal{O}(1)$$

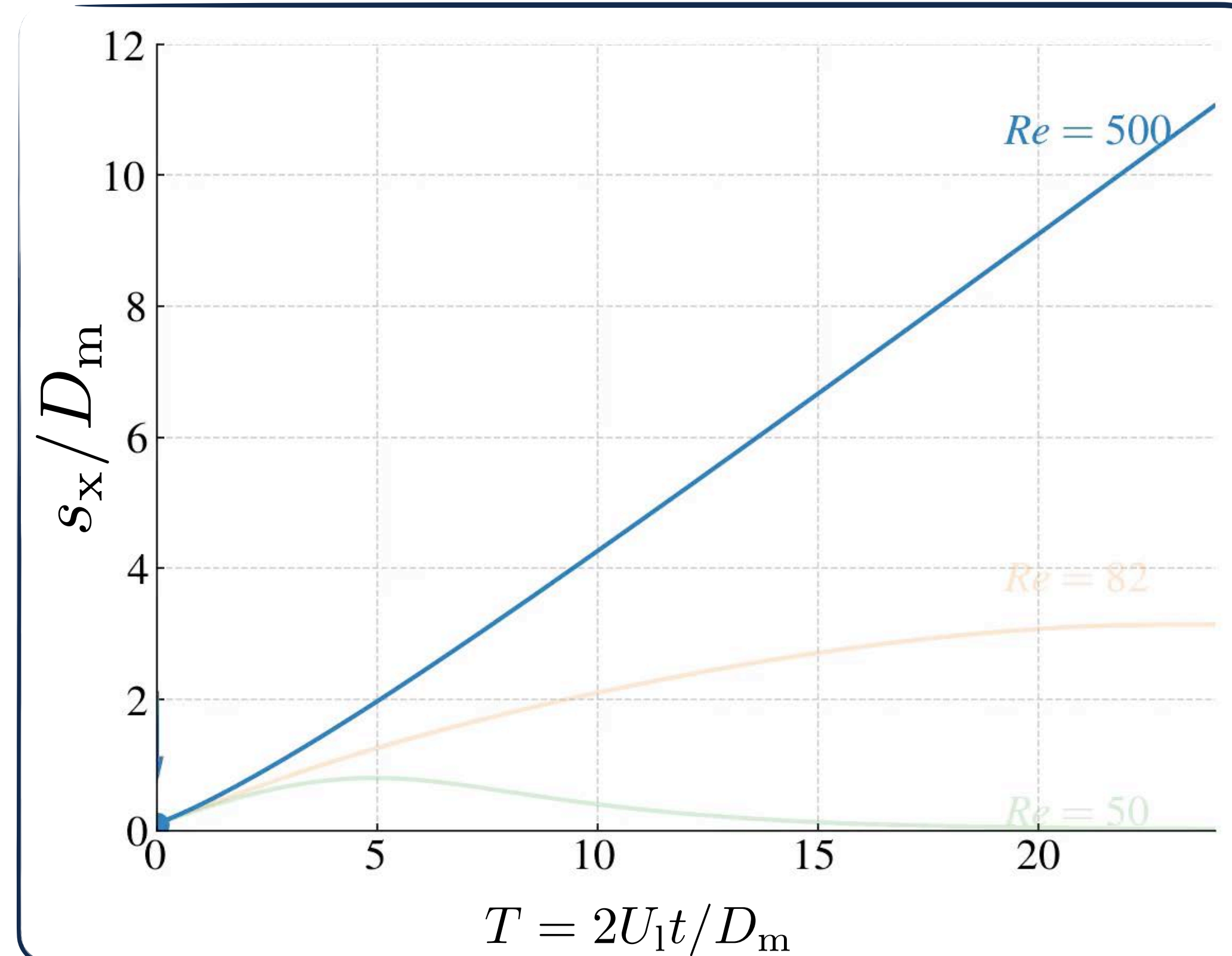
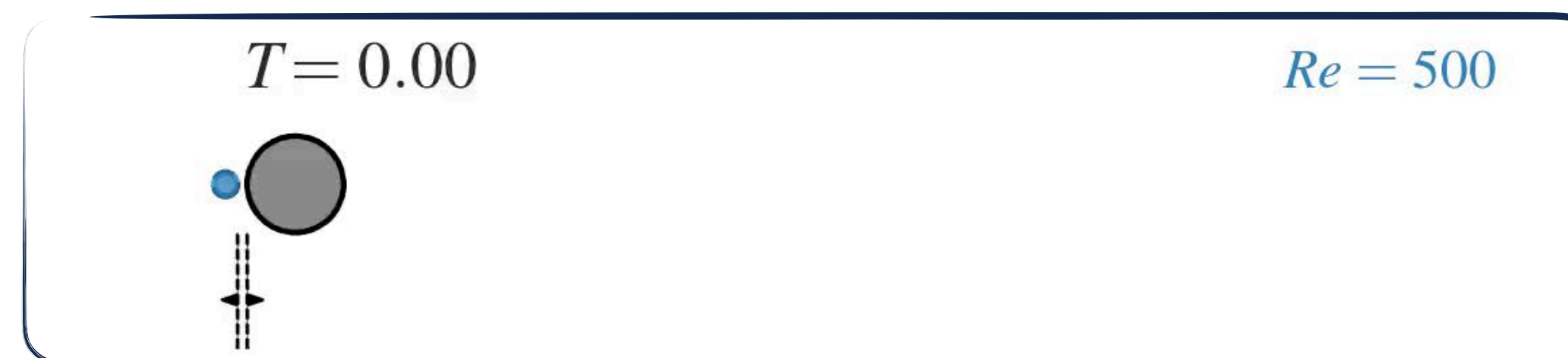




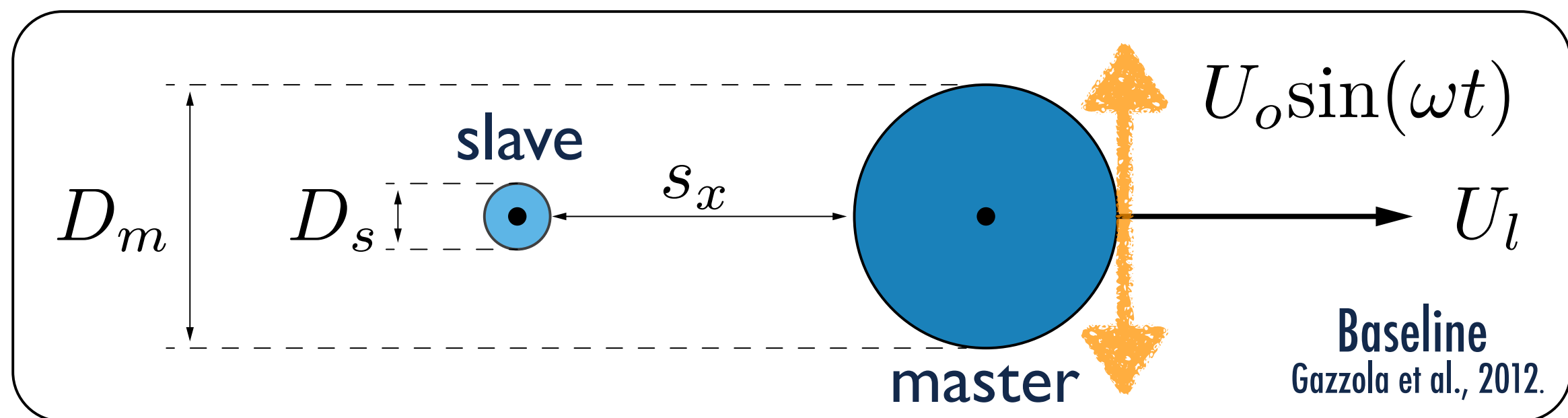
$Re$



$$Re = \frac{U_l D_m}{\nu}$$







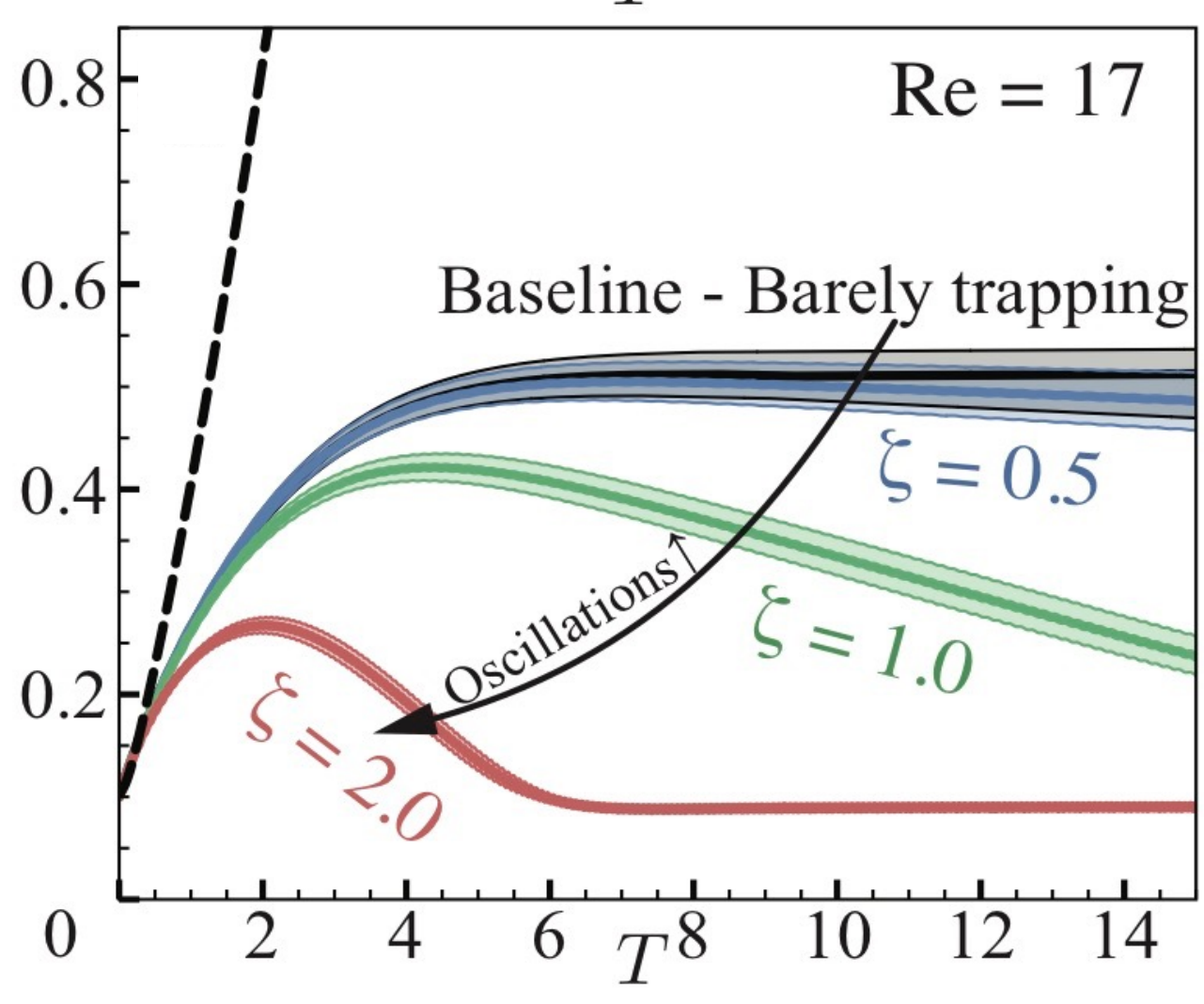
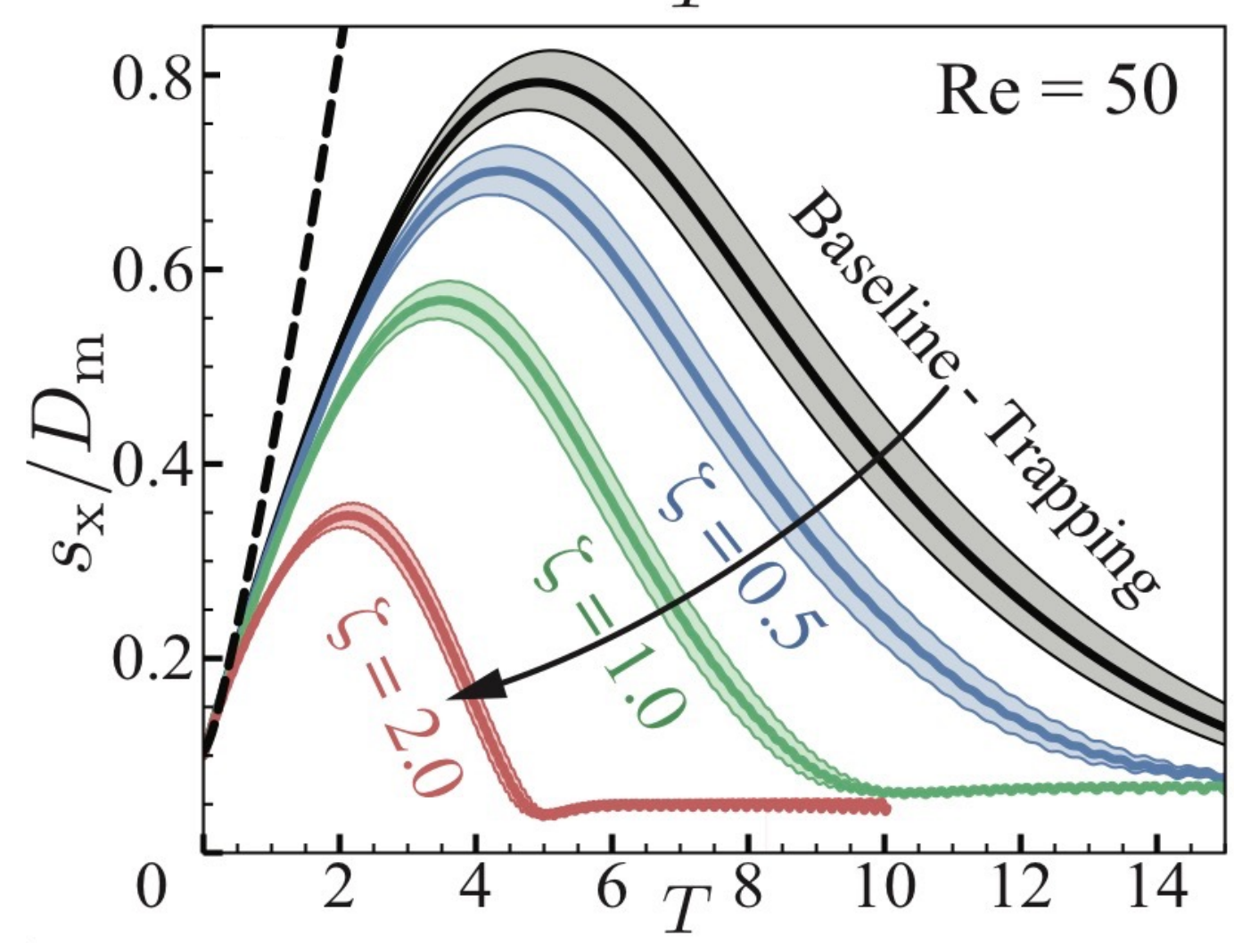
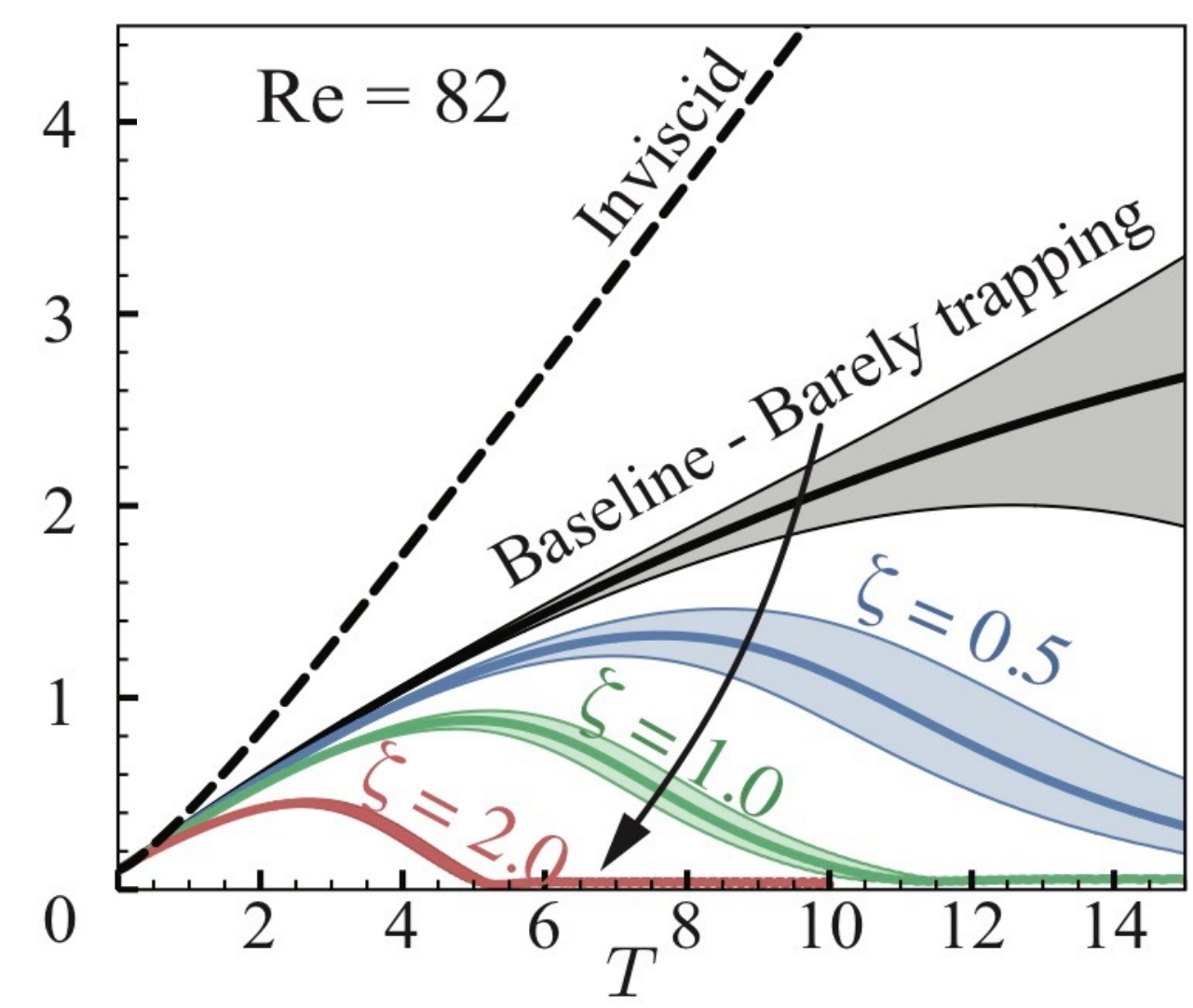
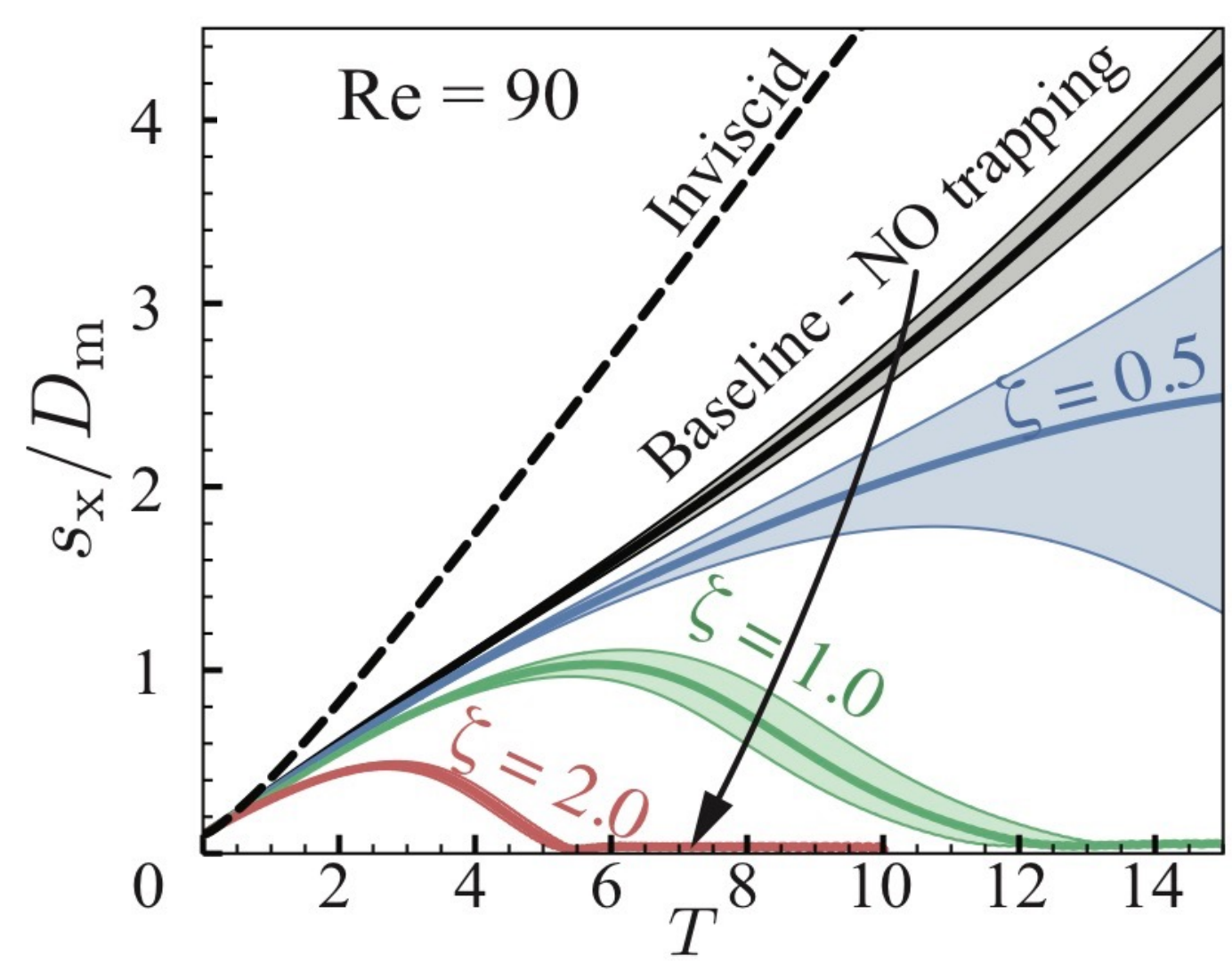
$$Re = \frac{U_l D_m}{\nu}$$

$$Ro = \frac{U_o D_m}{2\nu}$$

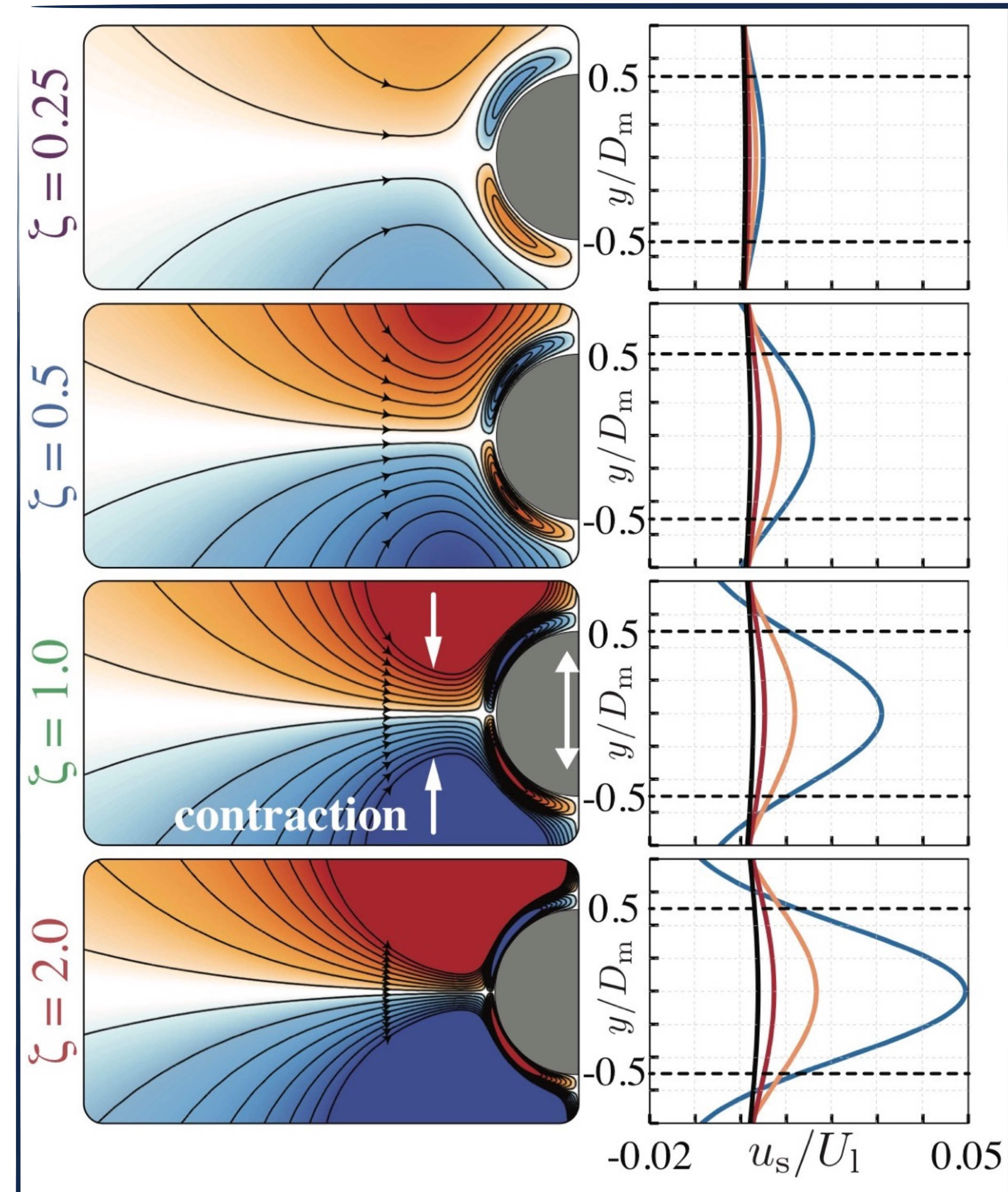
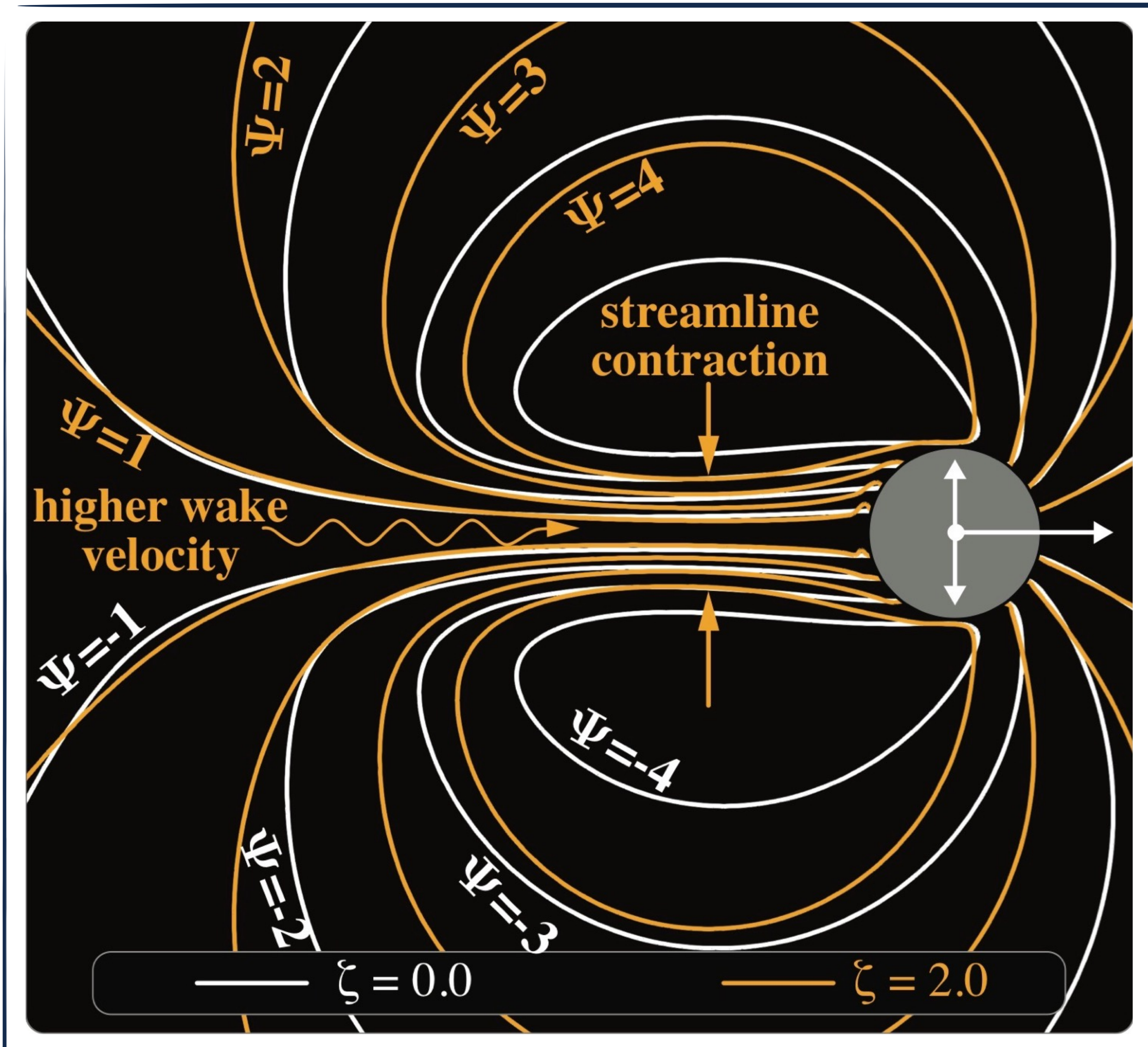
$$\zeta = \frac{Ro}{Re}$$

Scaled  
Strouhal number

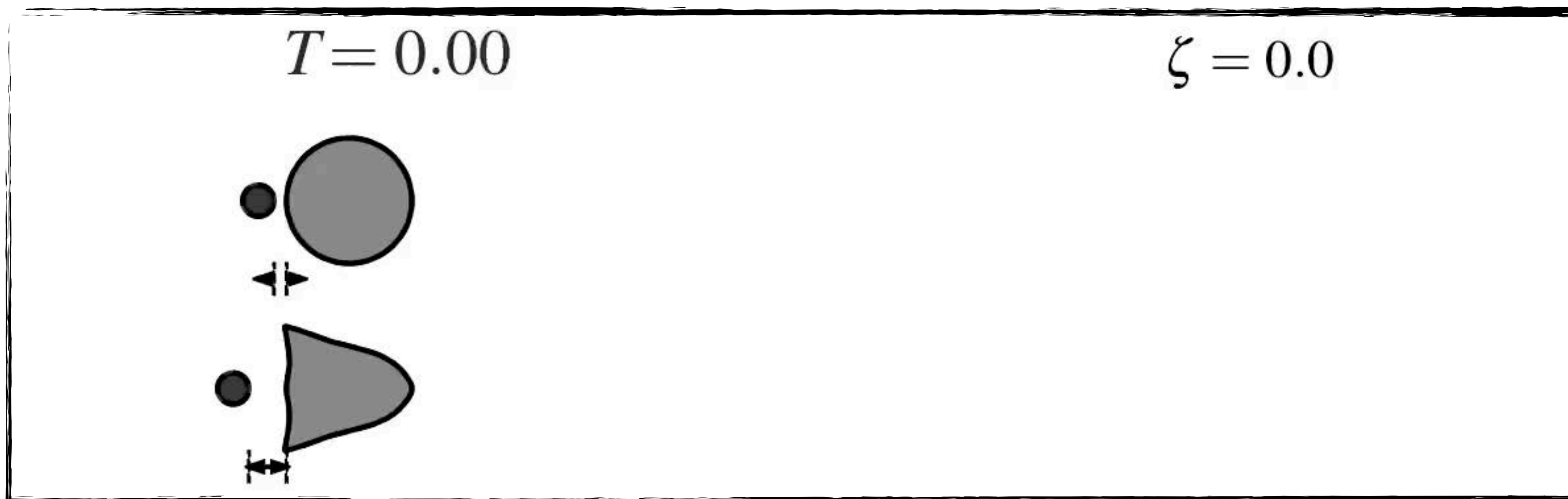
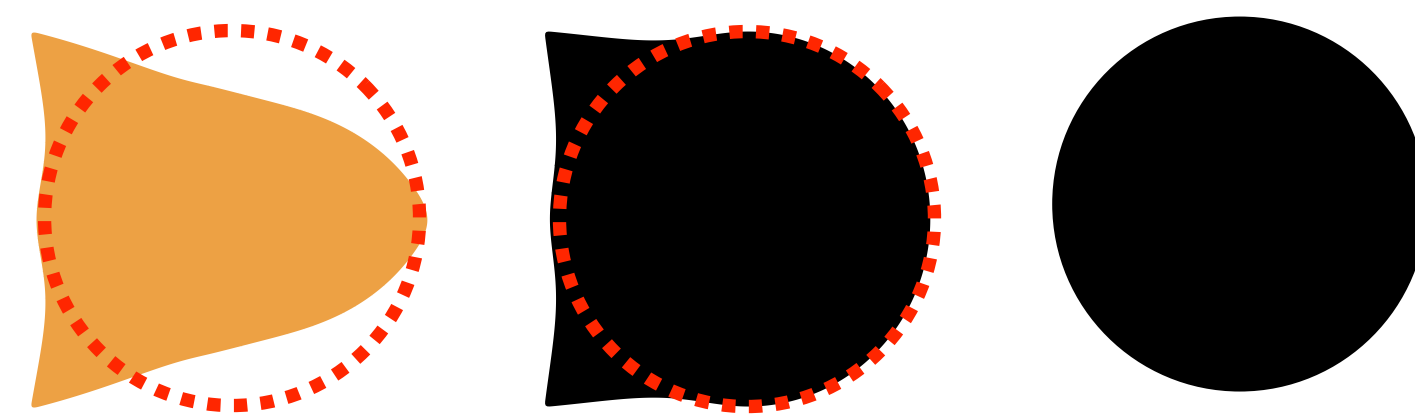
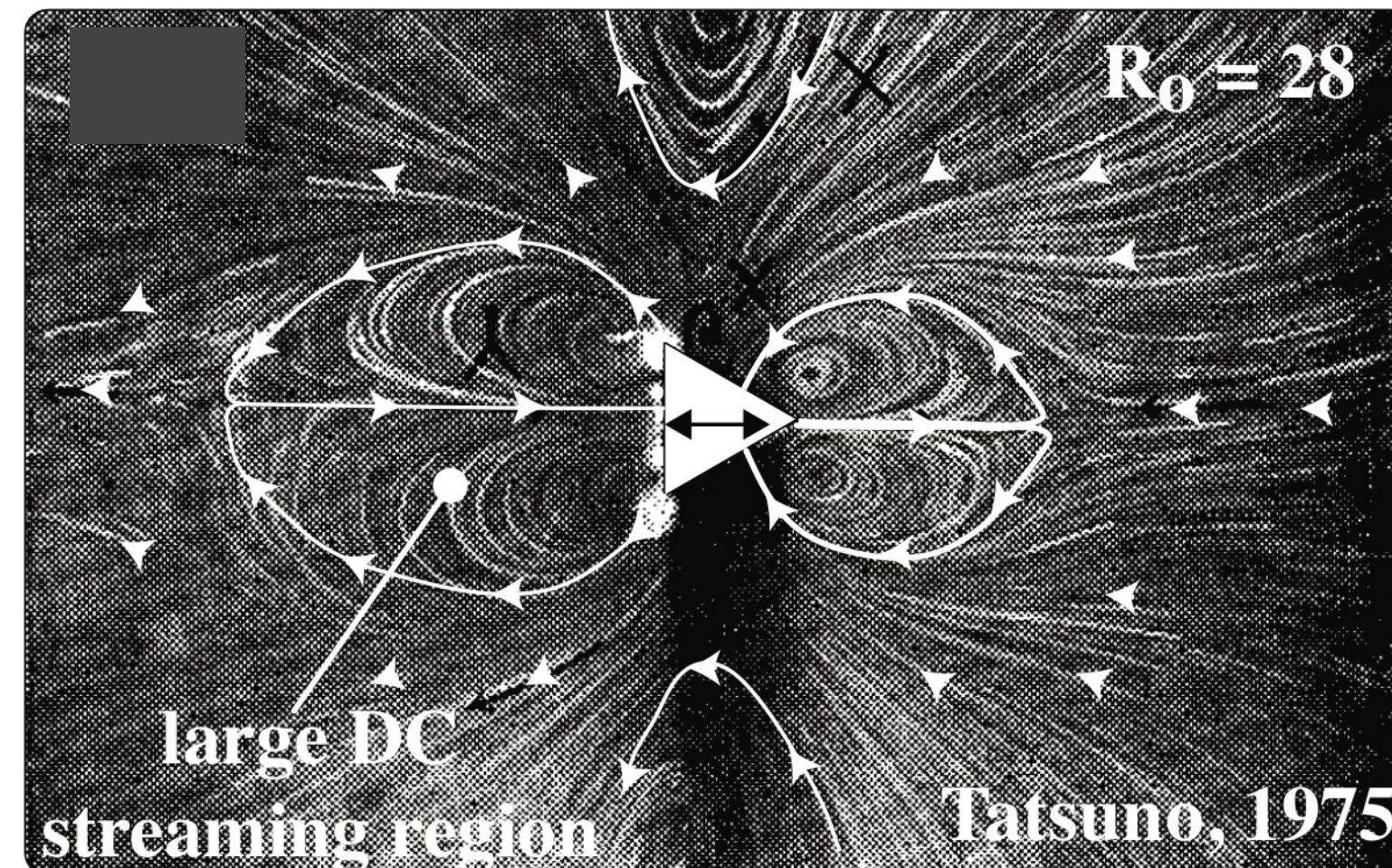
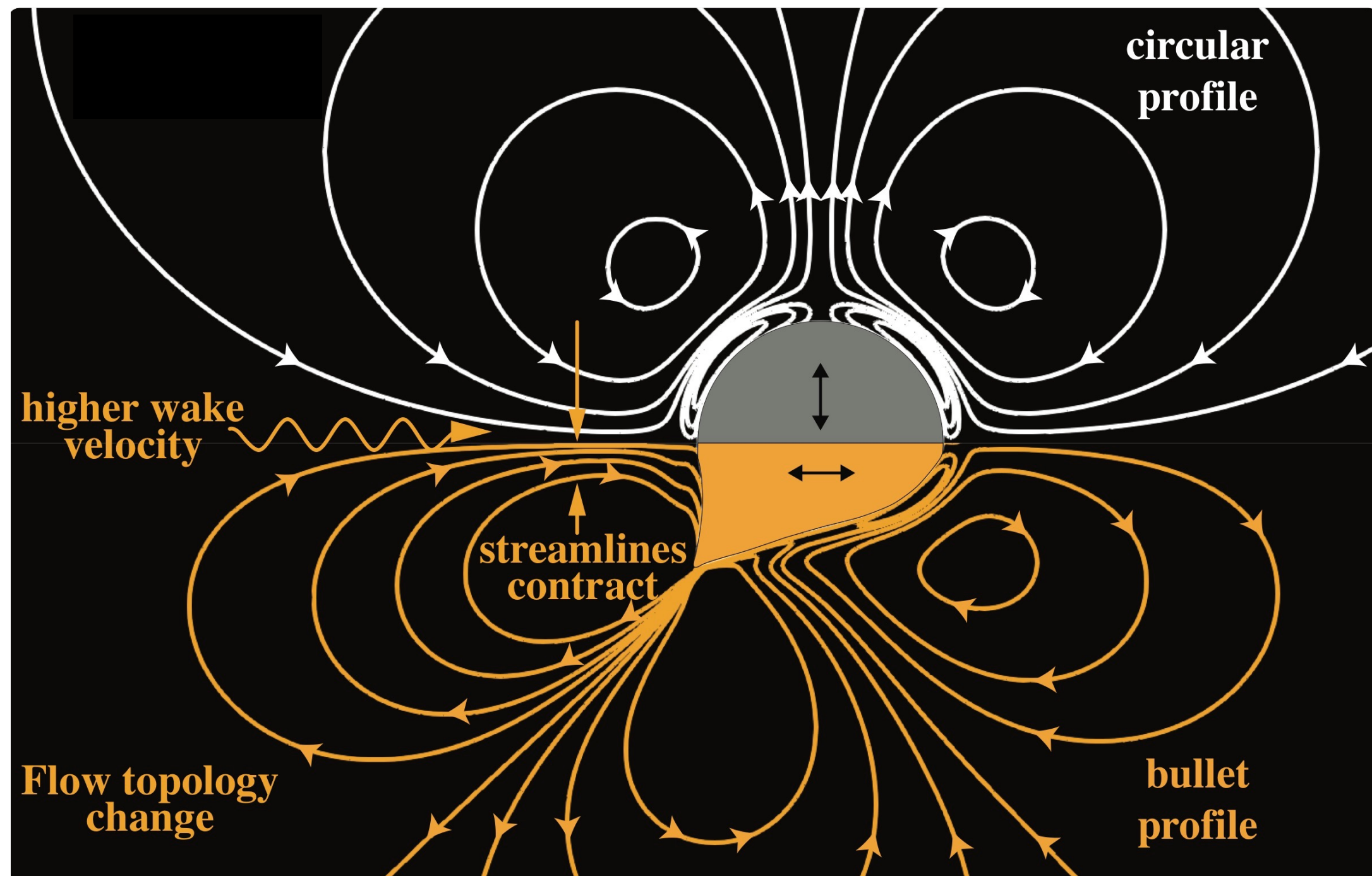
Oscillatory  
versus  
translation  
timescales







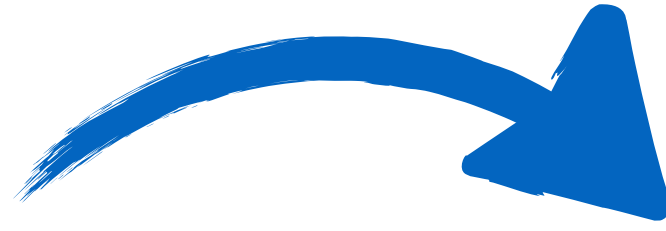




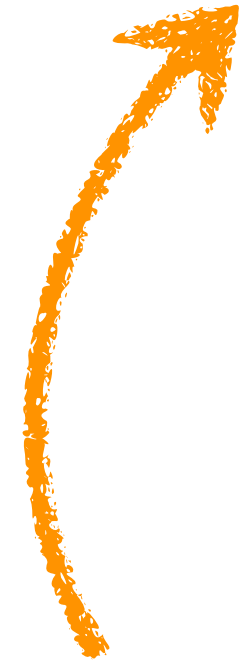




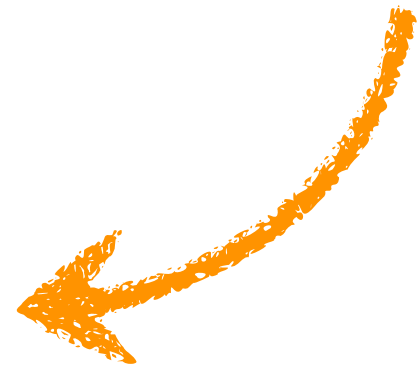
Genus 0



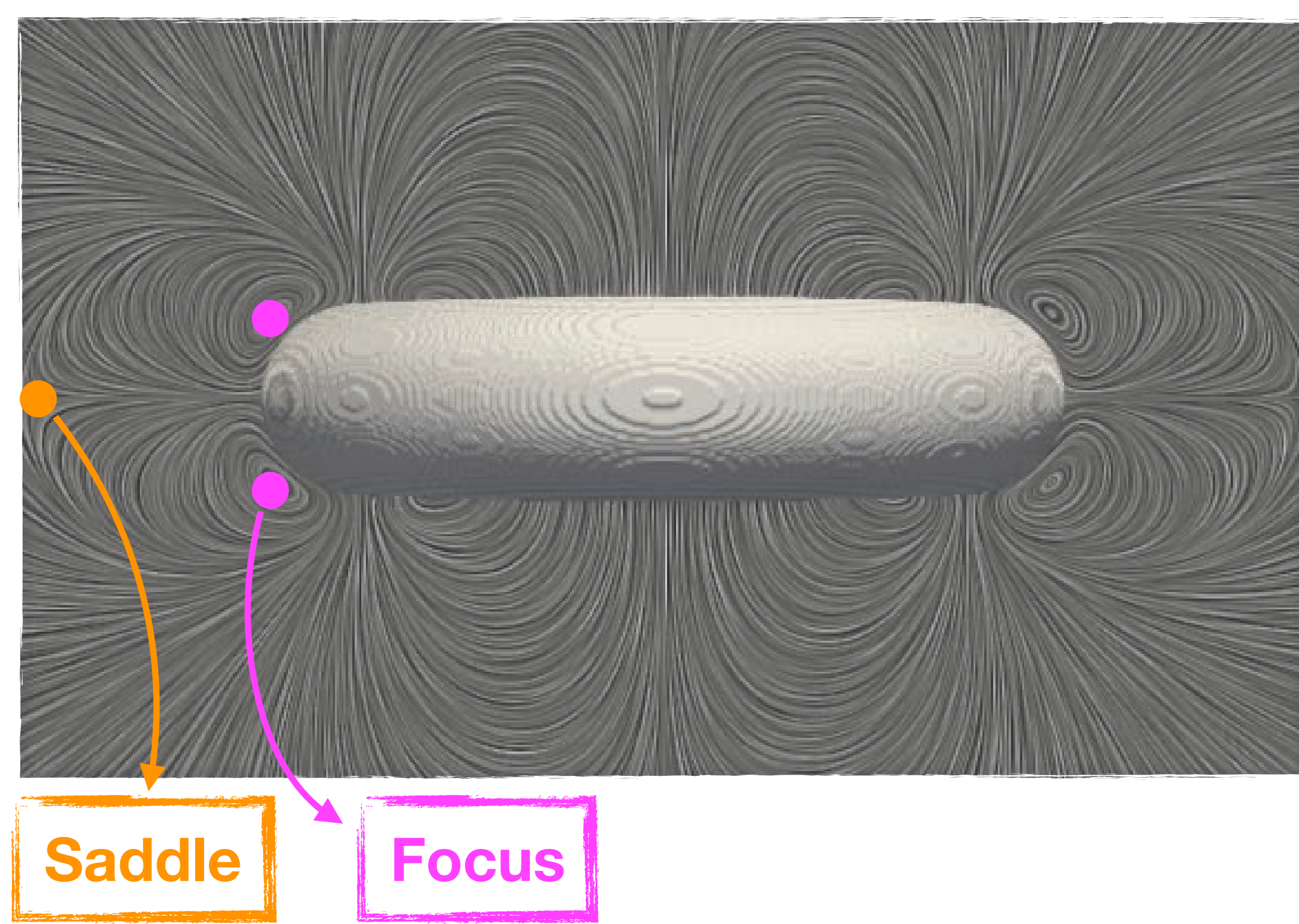
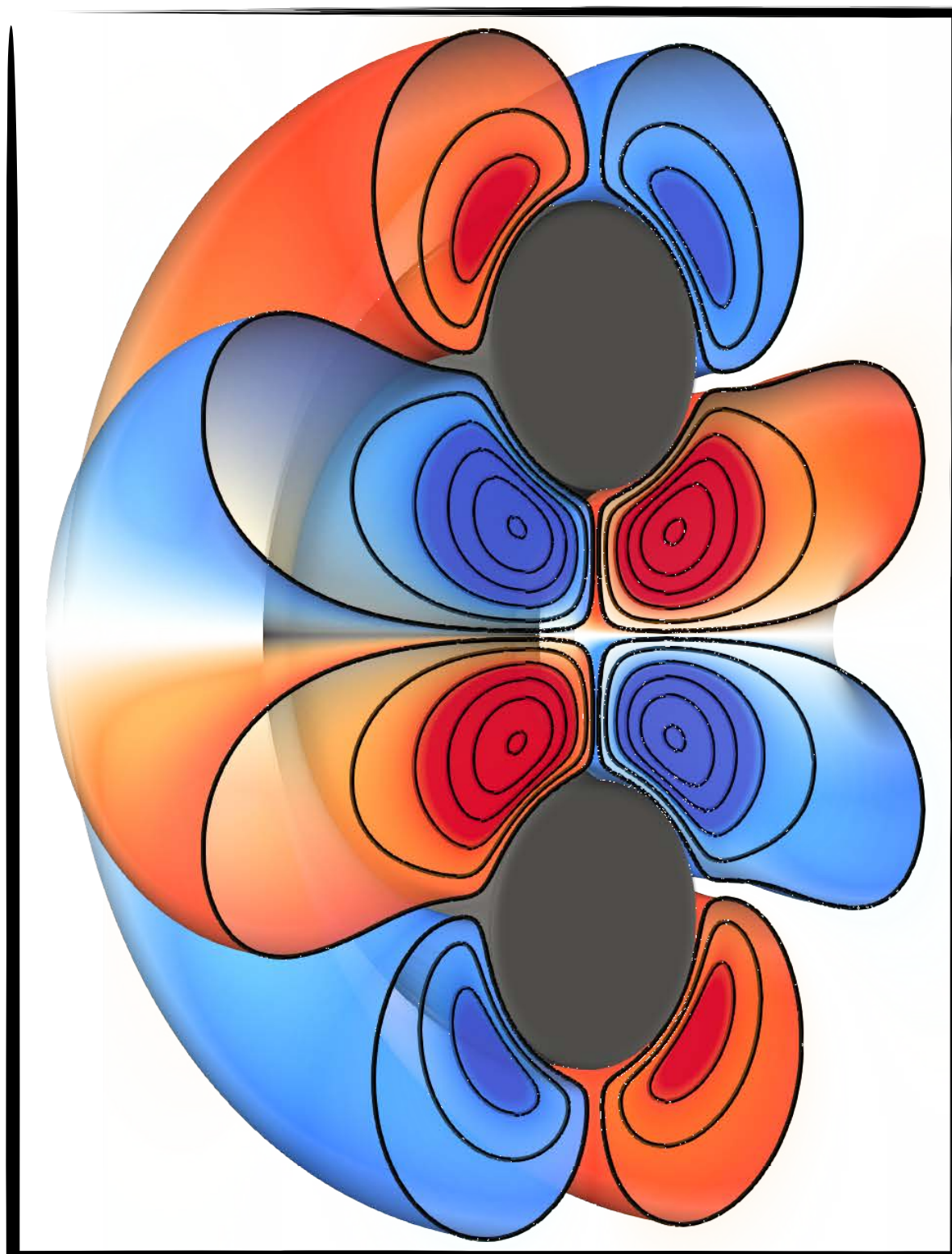
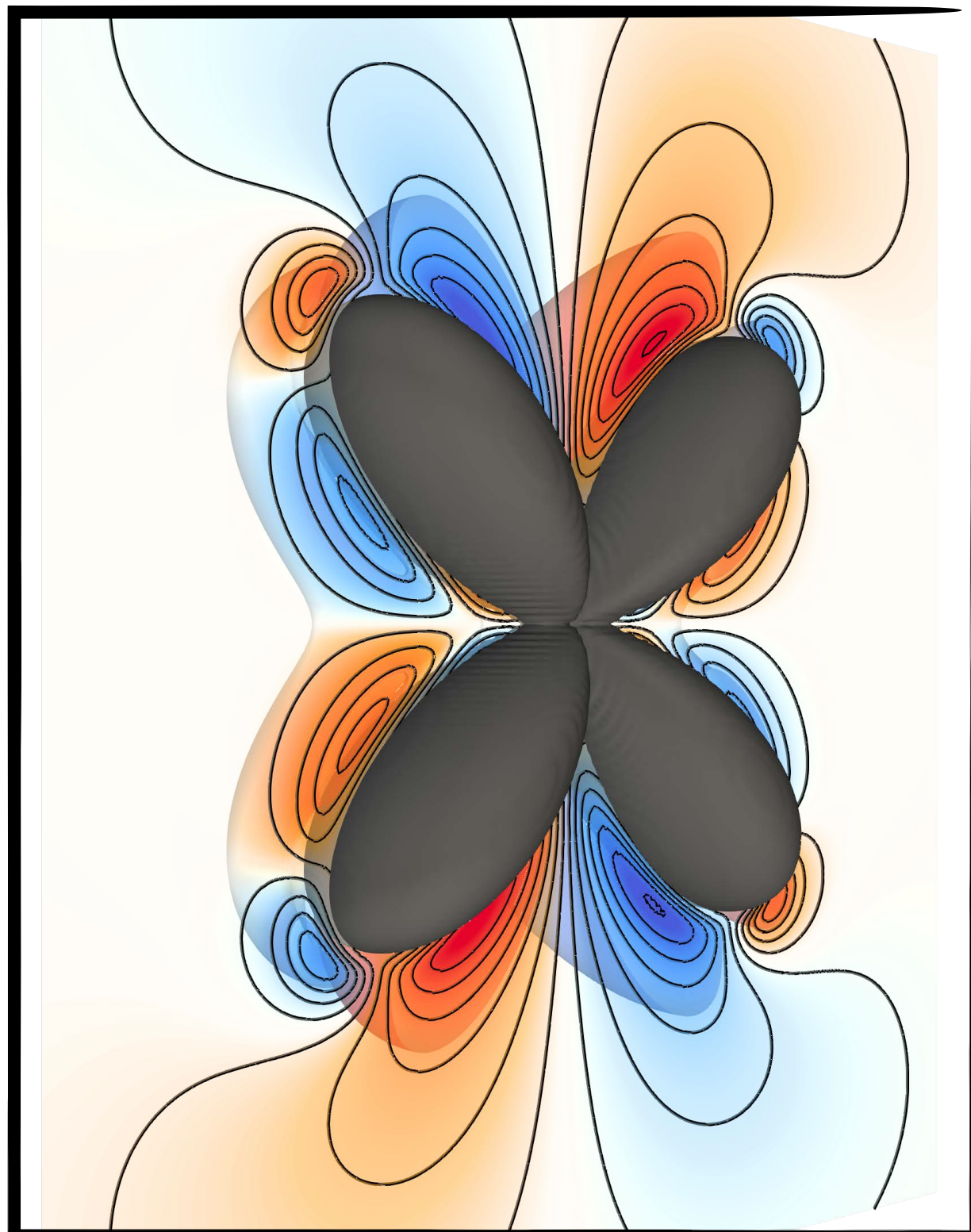
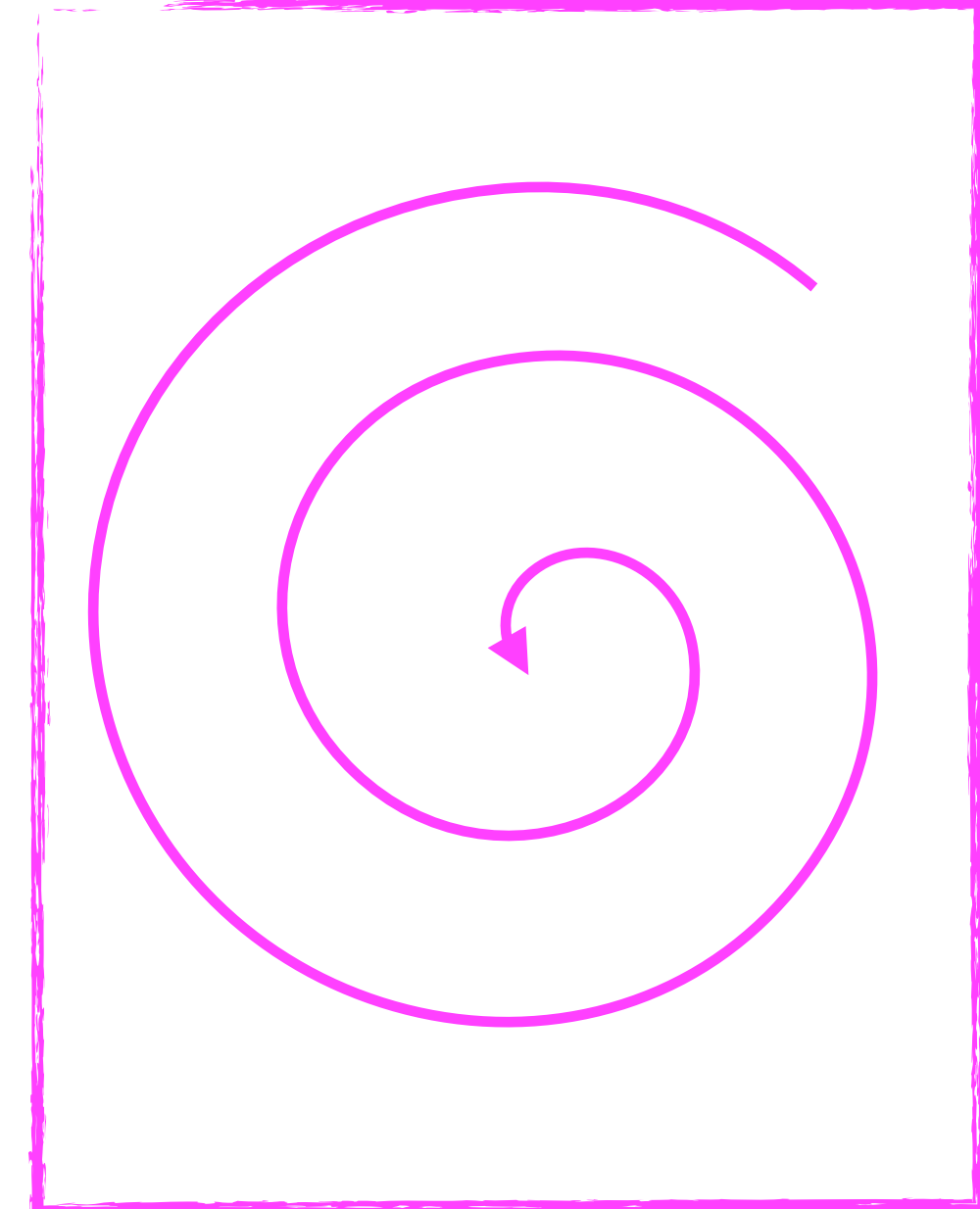
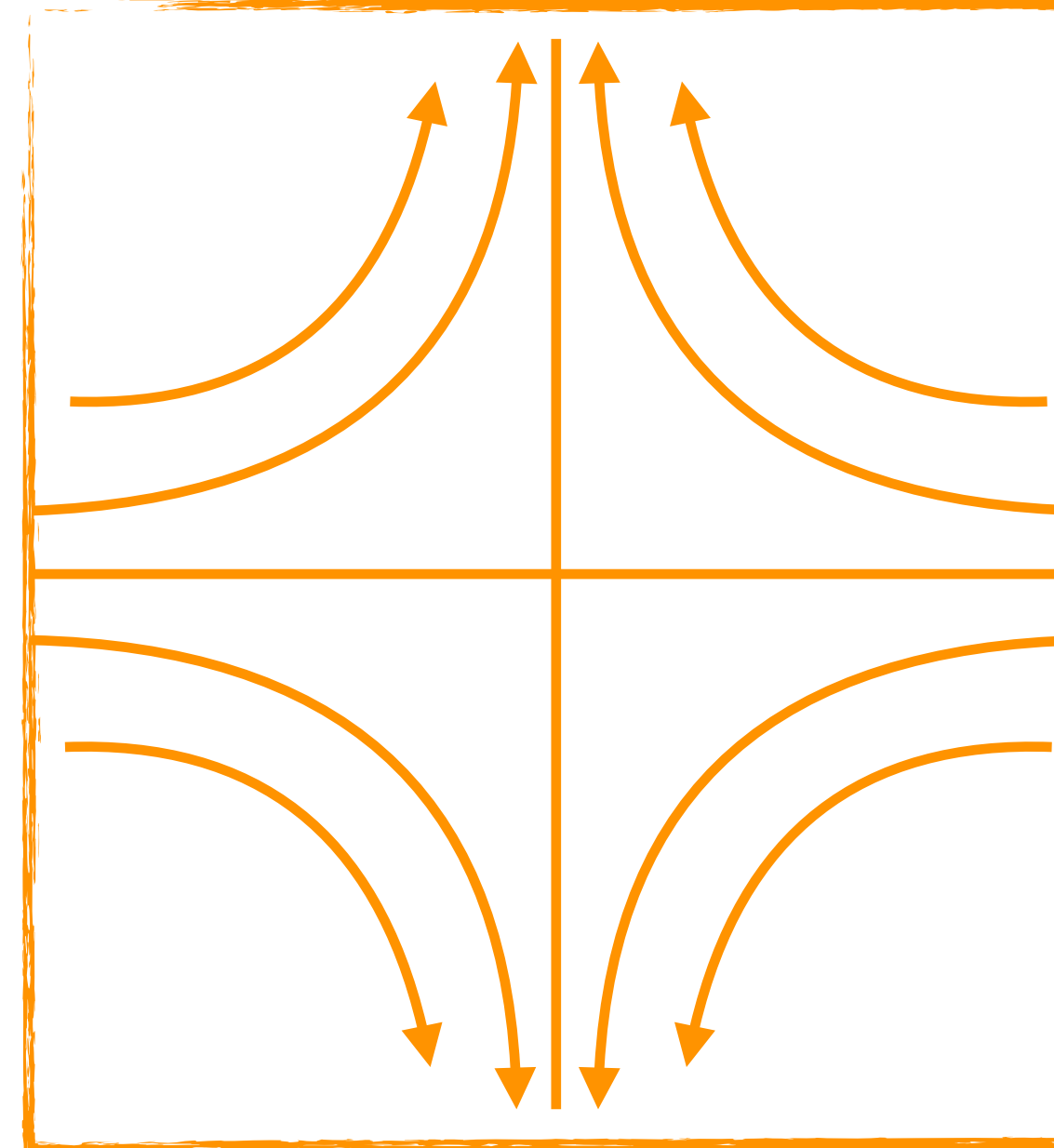
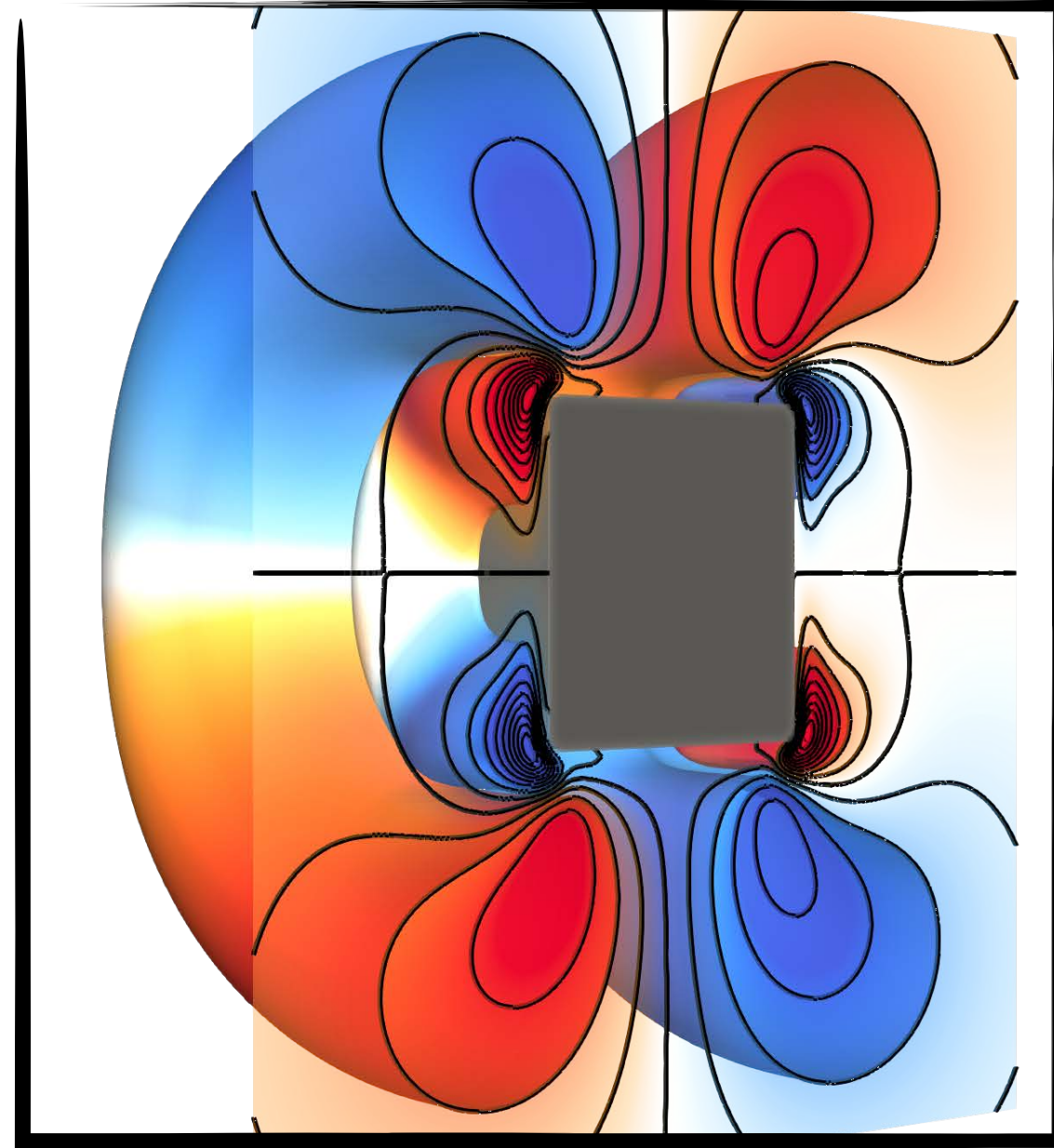
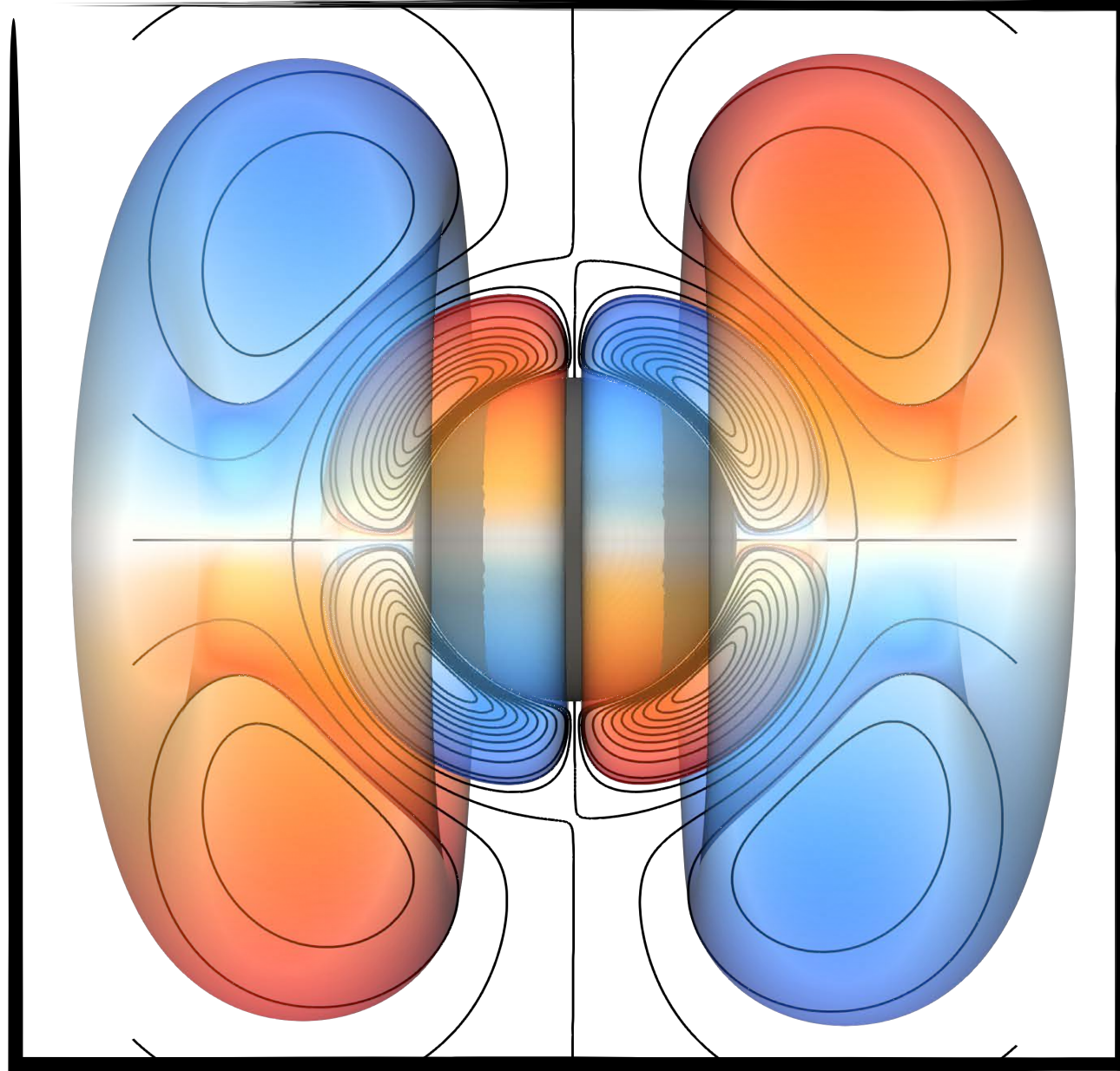
Genus 1



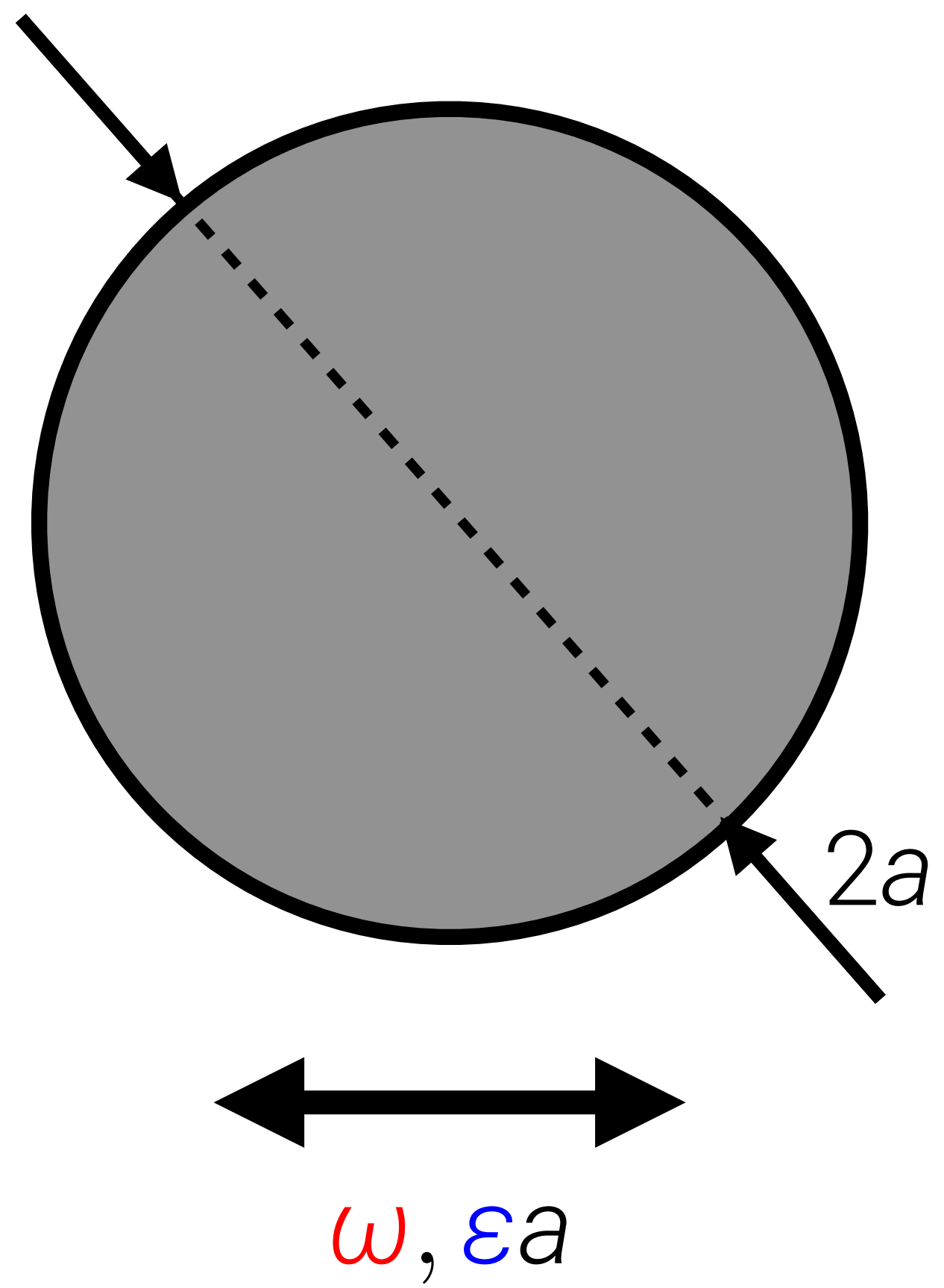
Different geometry



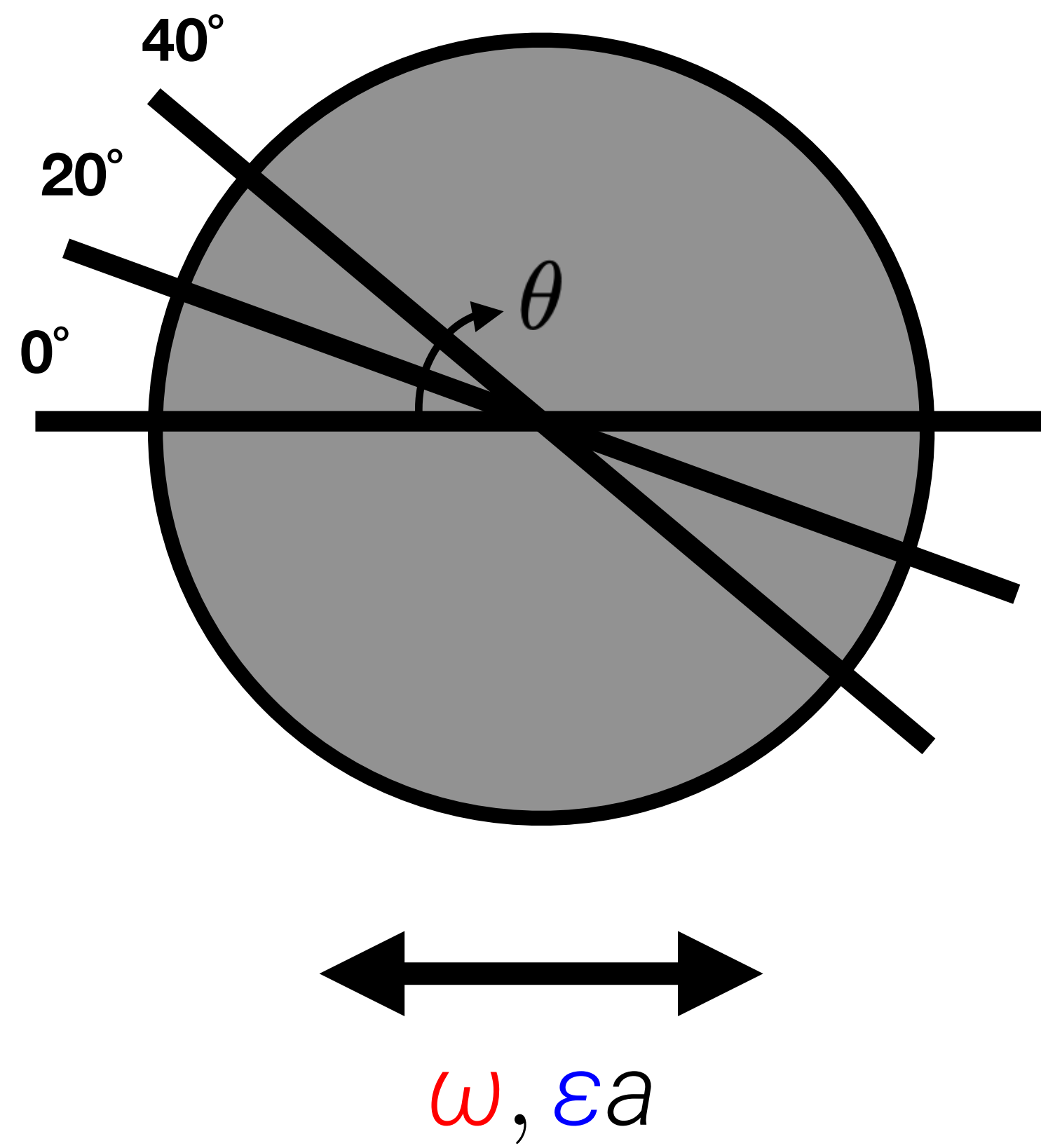




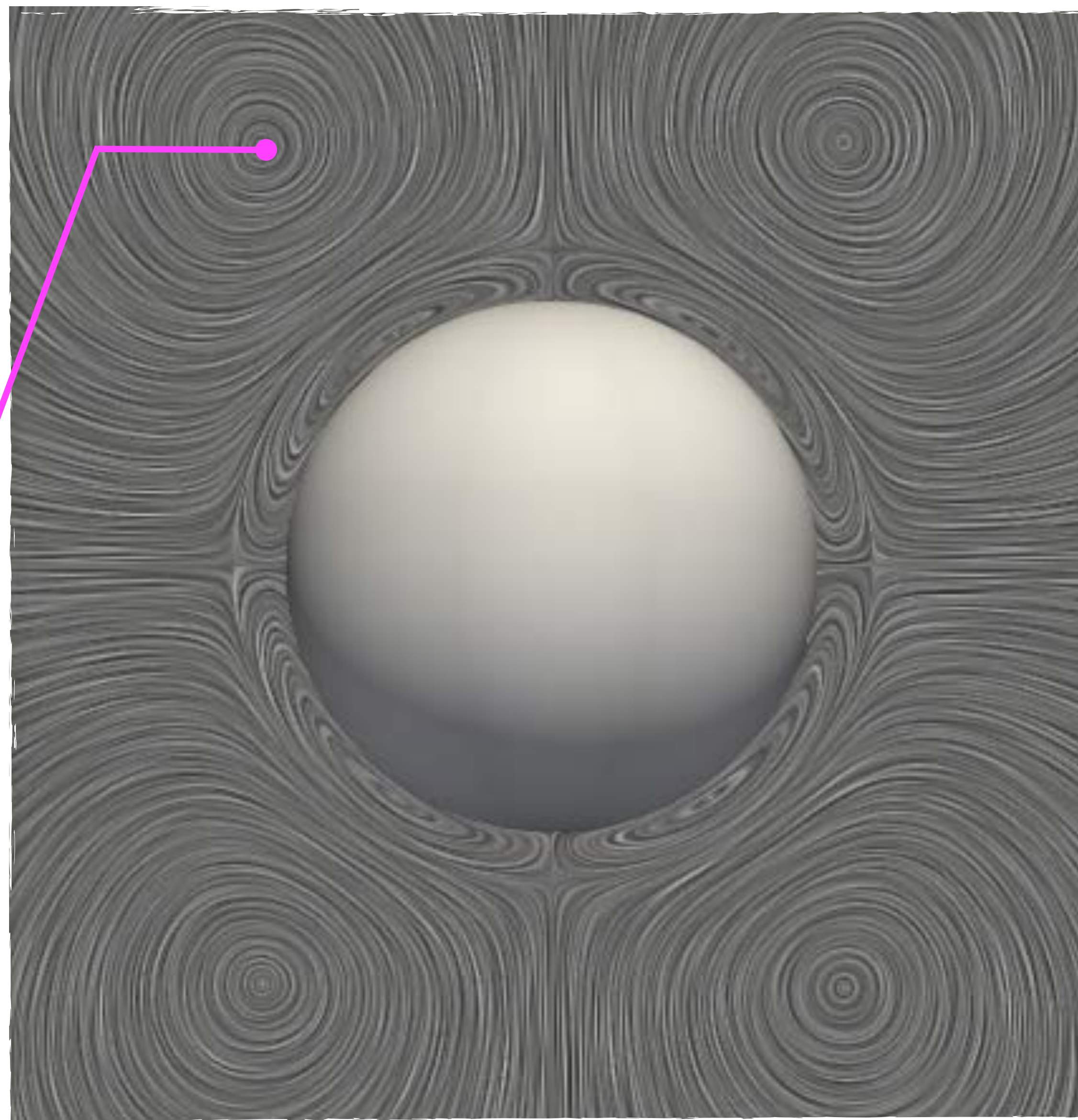
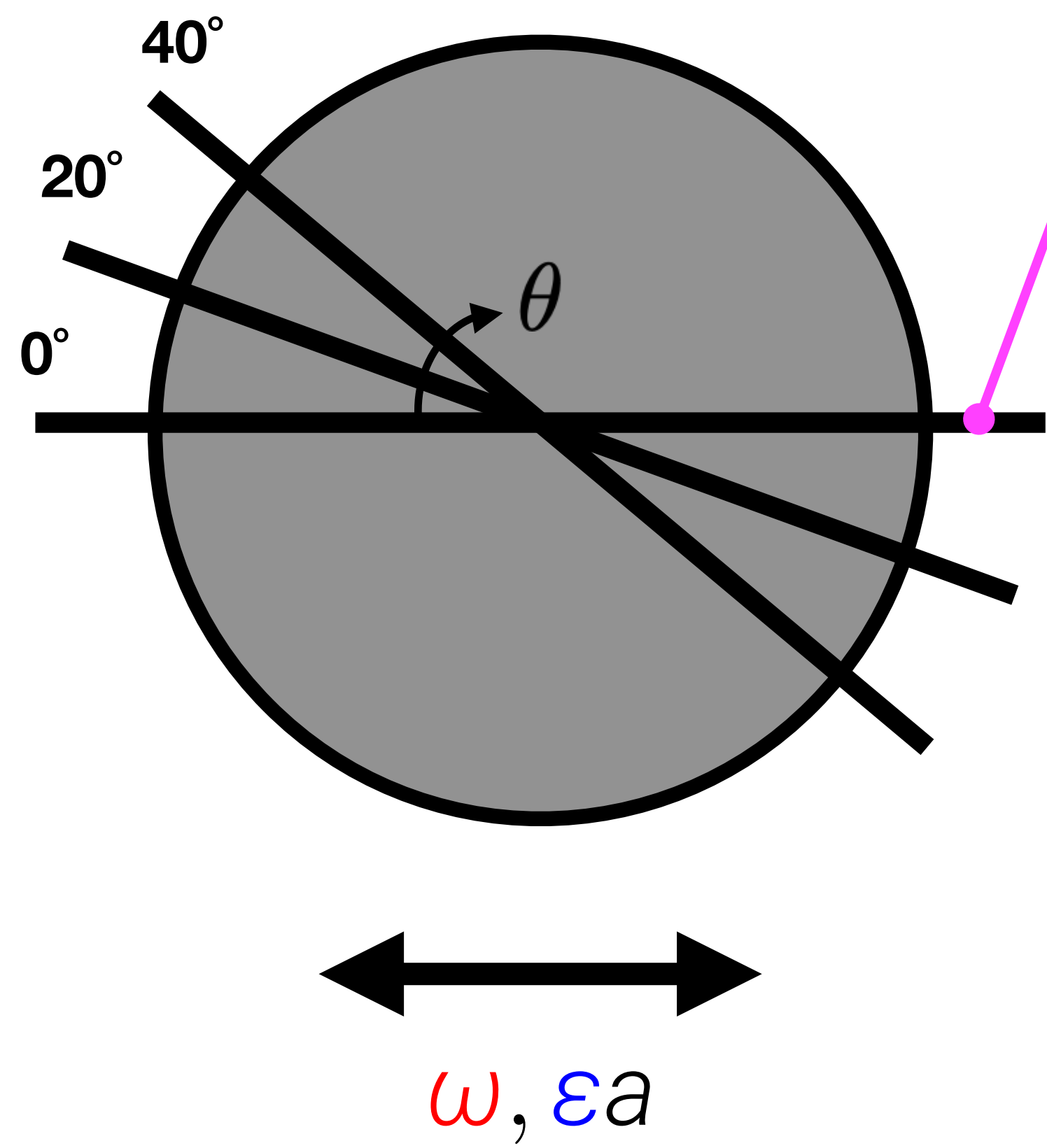




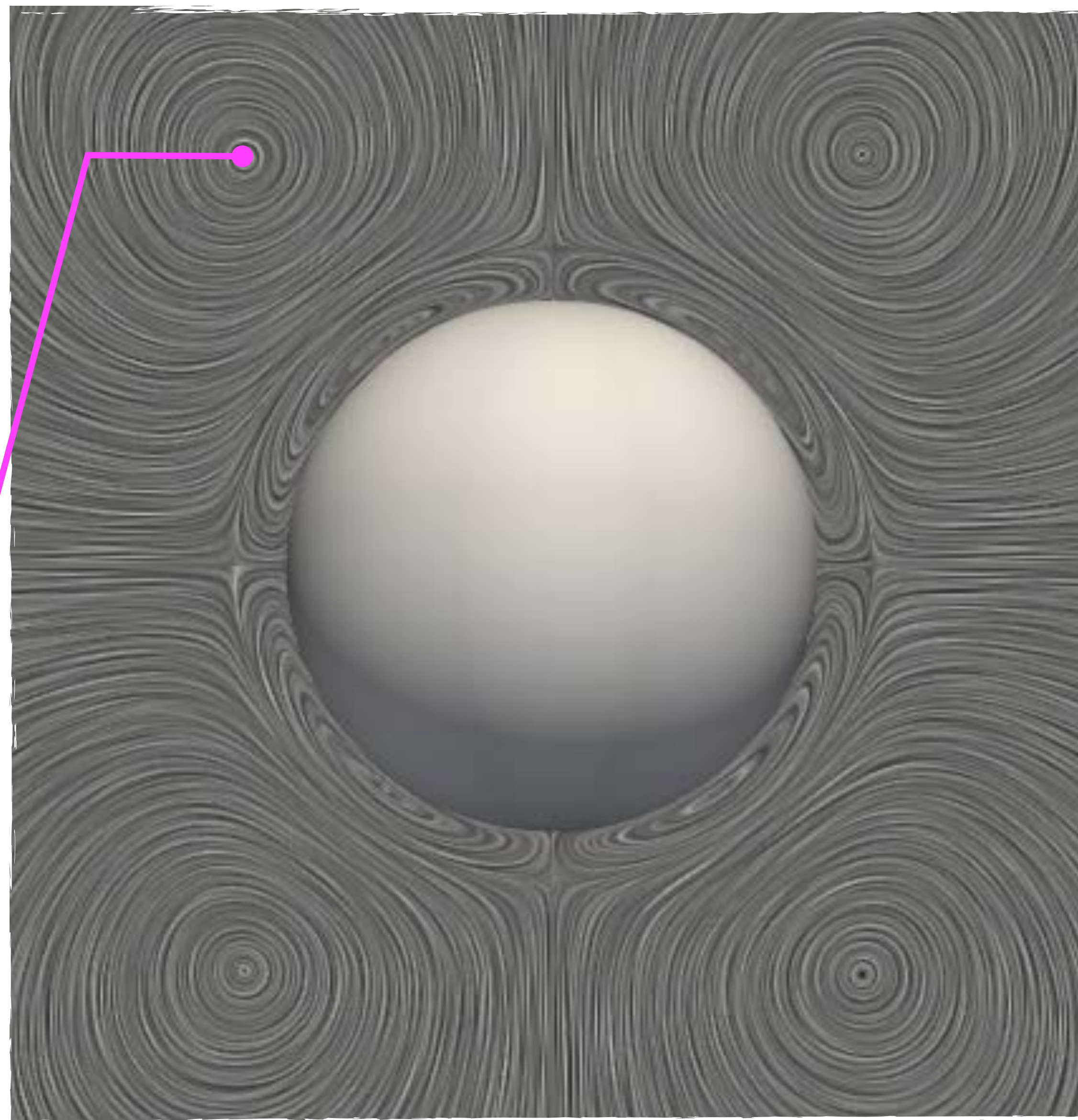
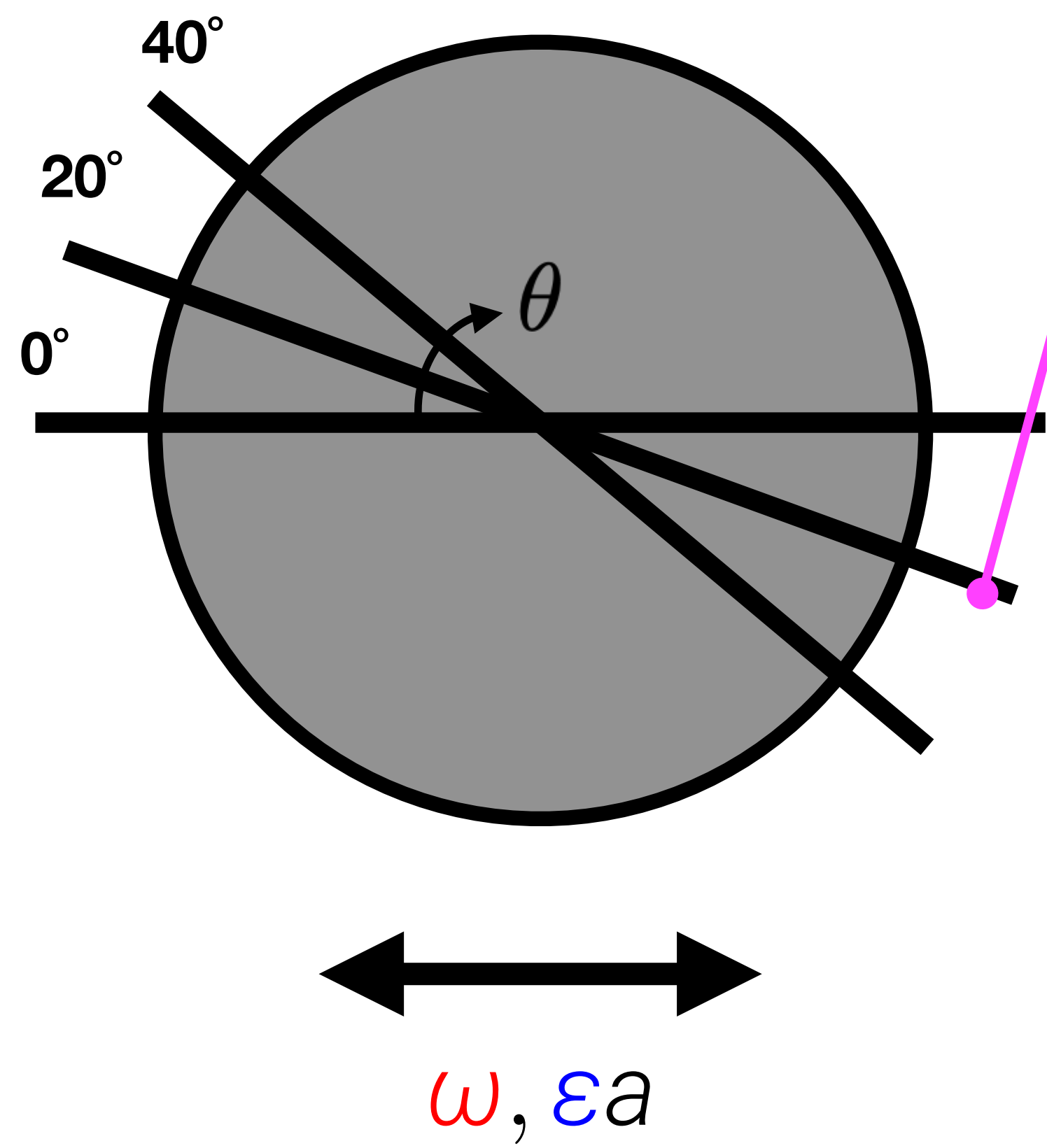




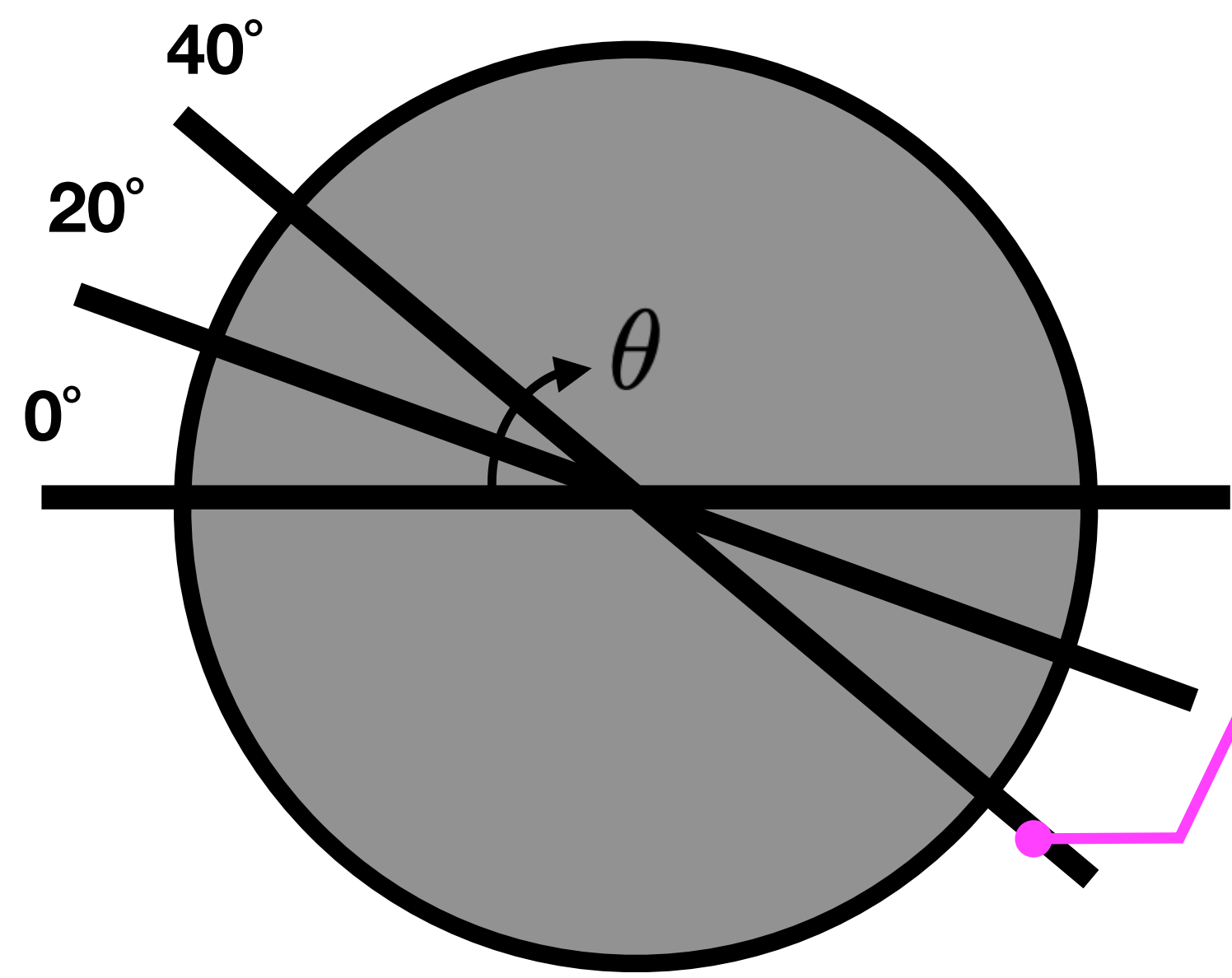




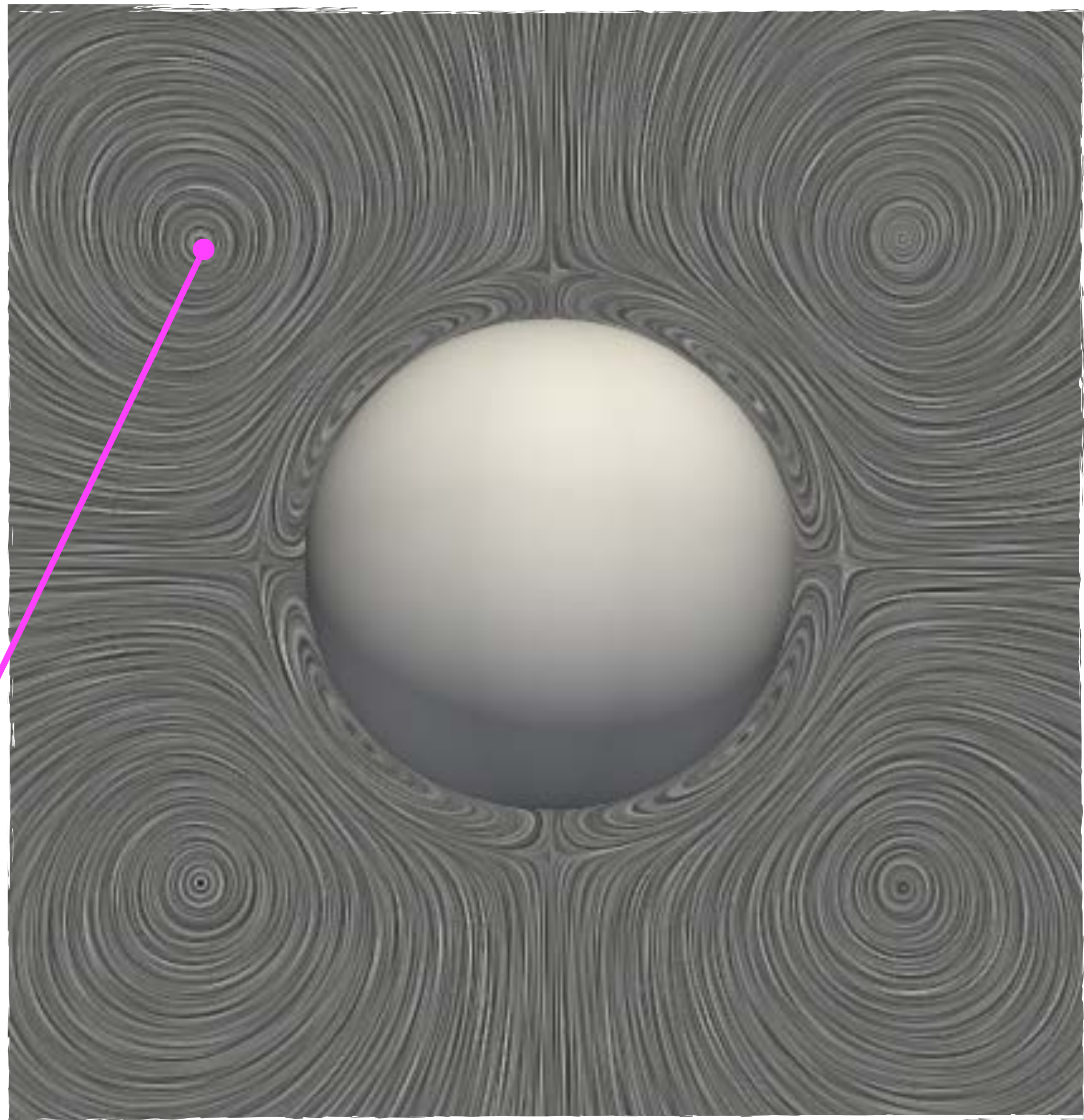




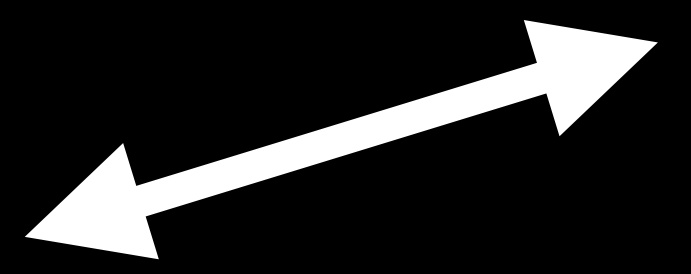
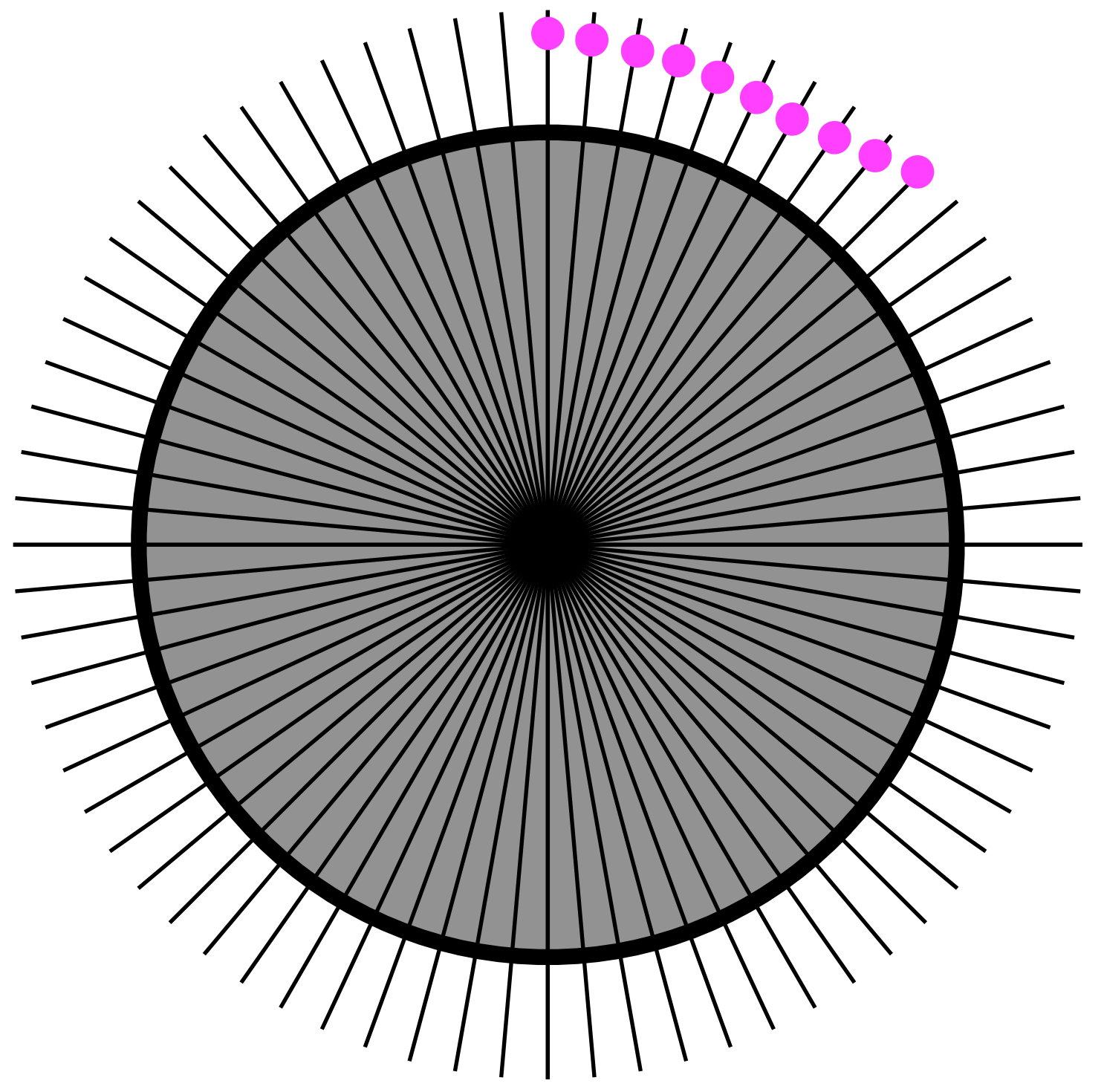




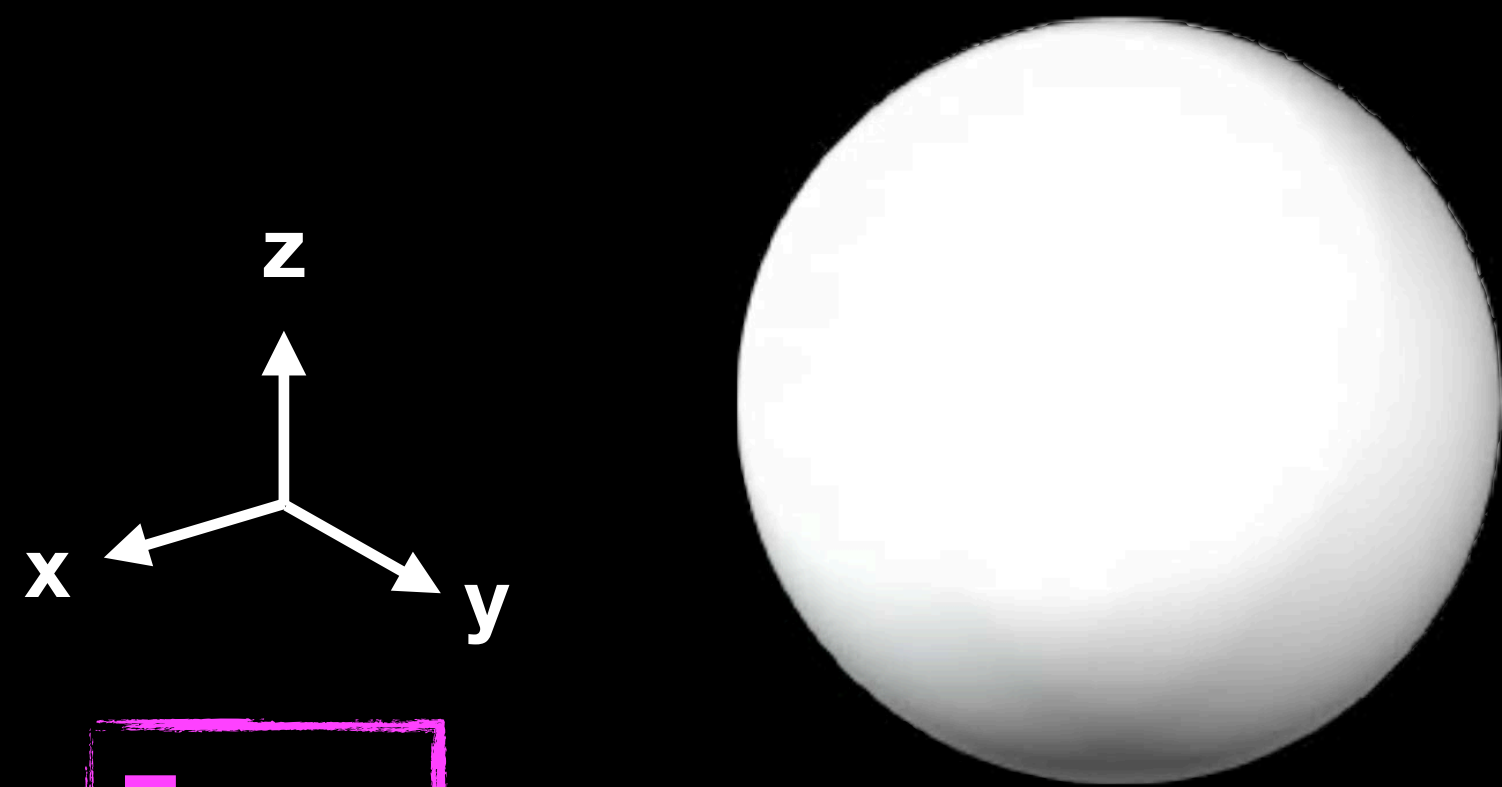
$\omega, \epsilon a$





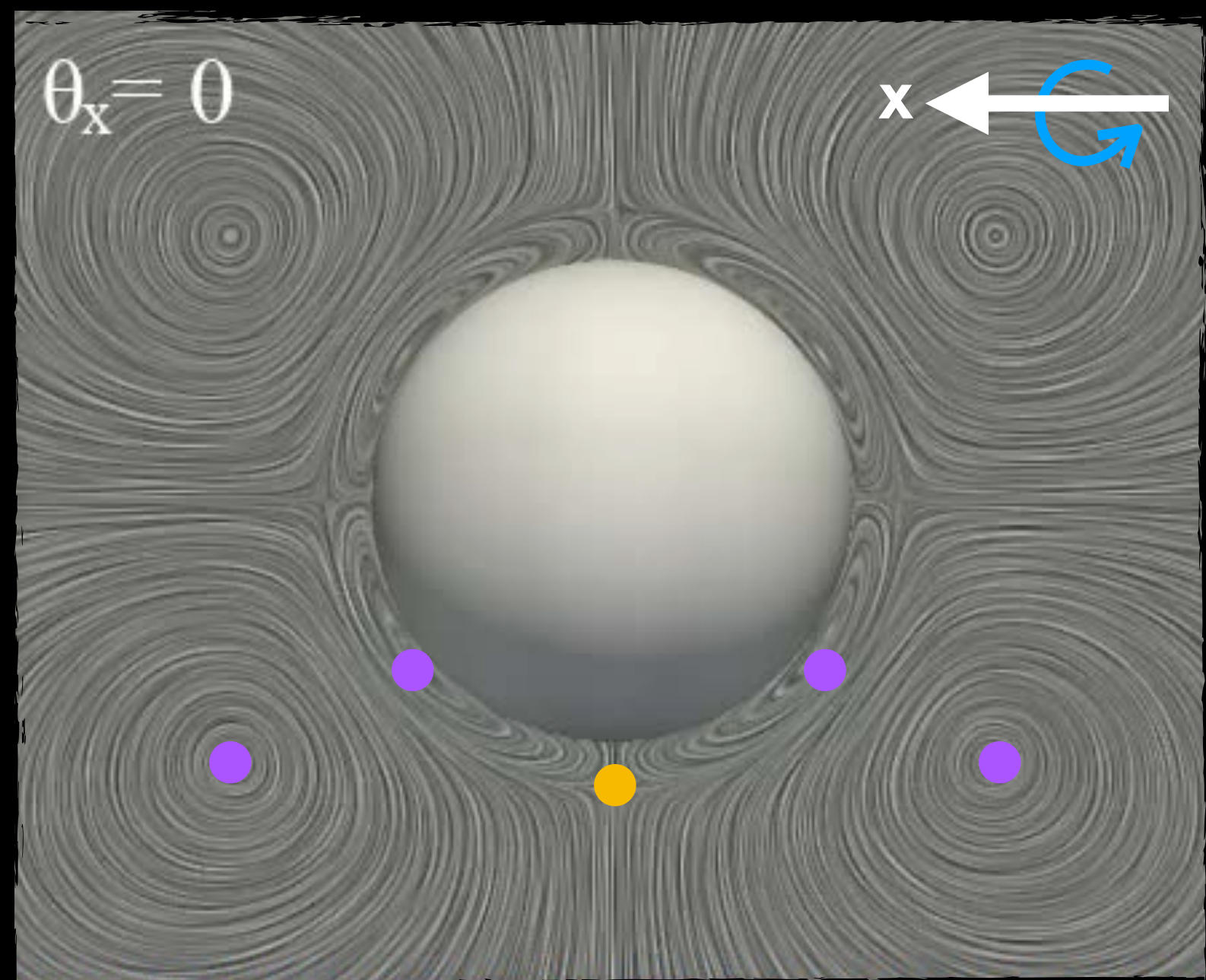
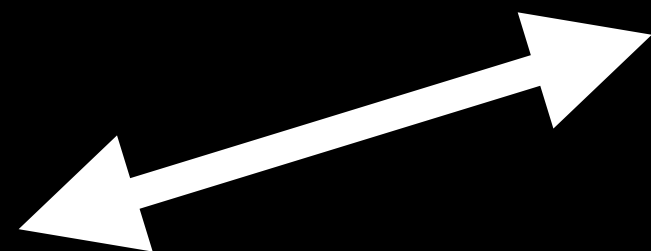




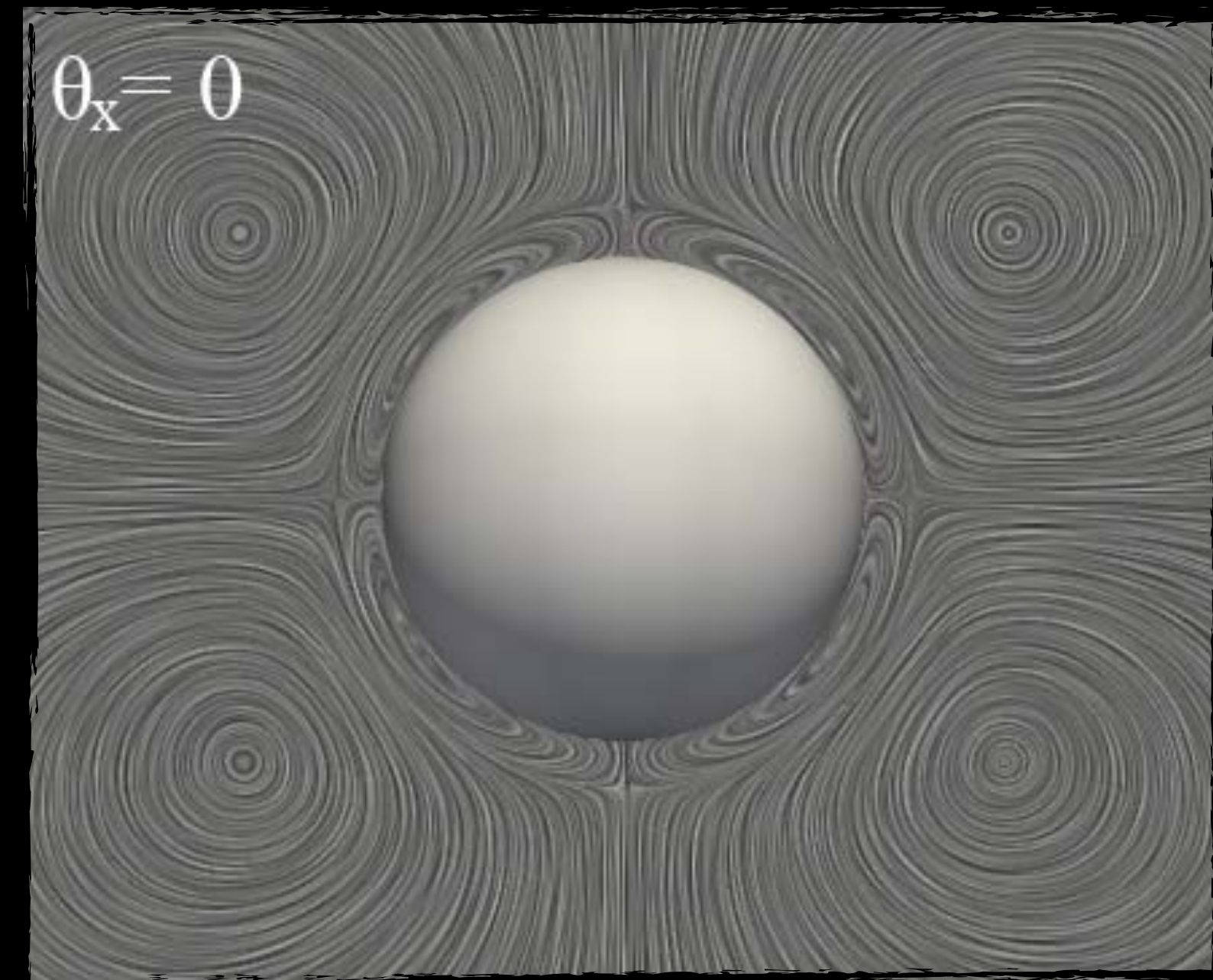
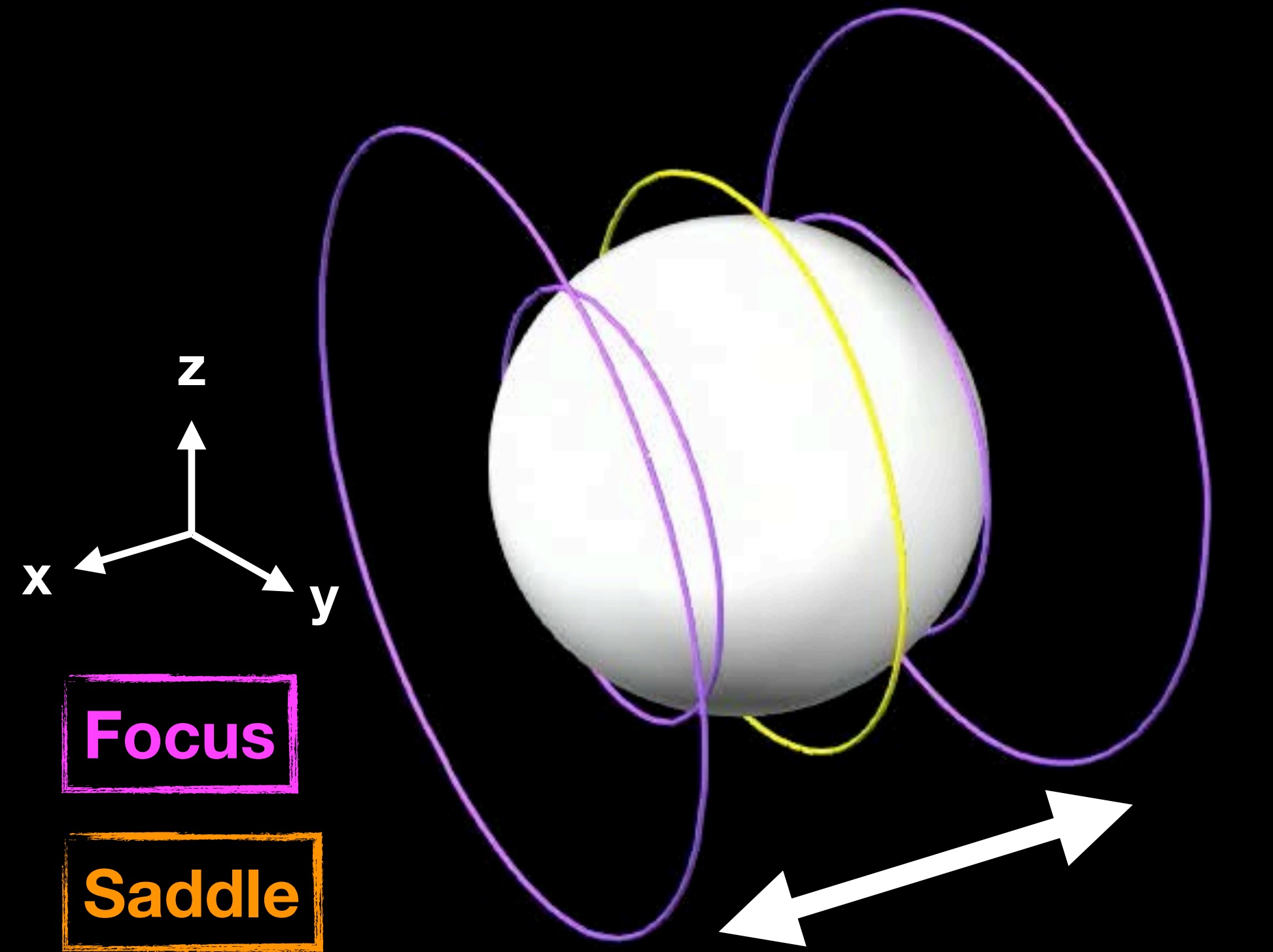


**Focus**

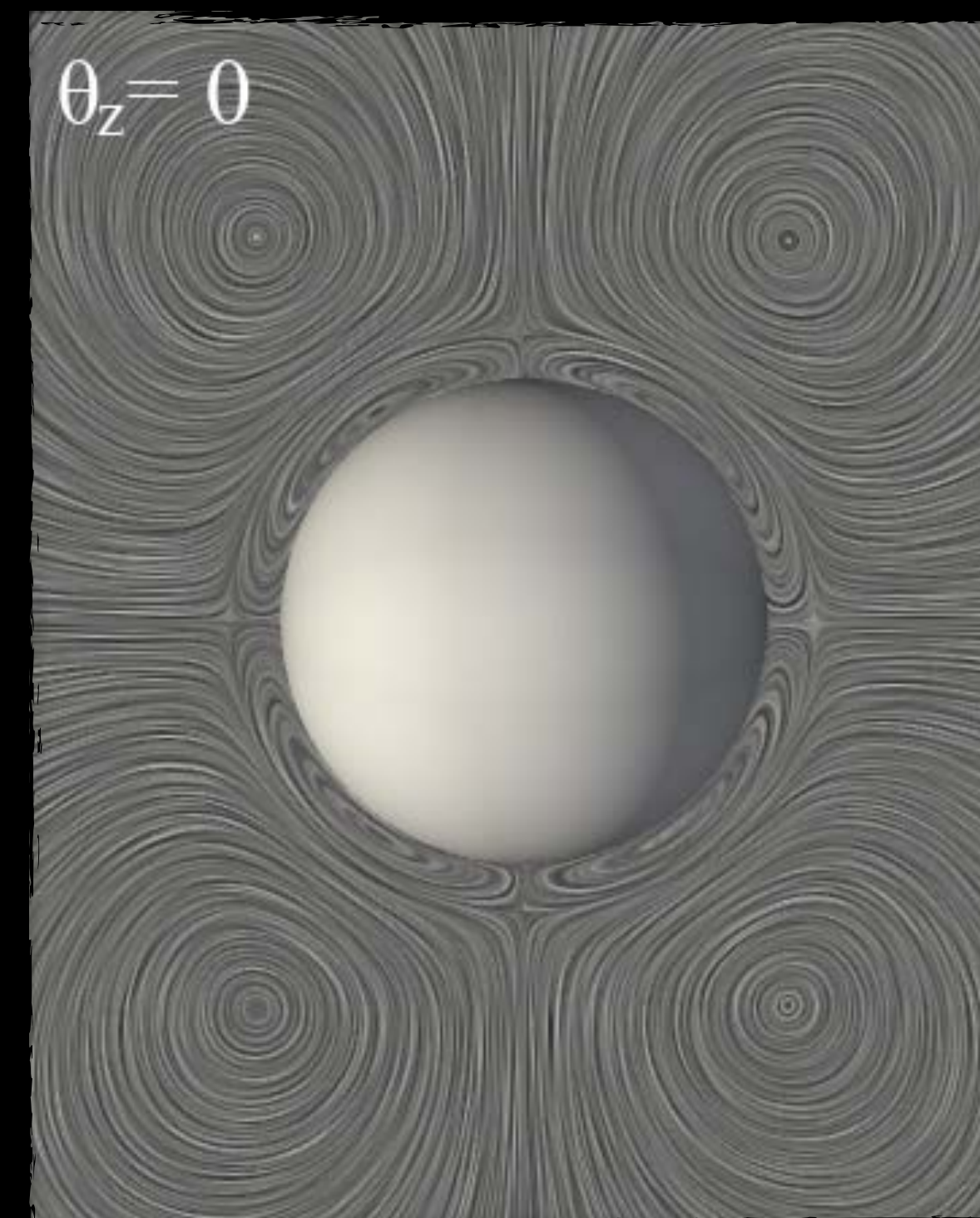
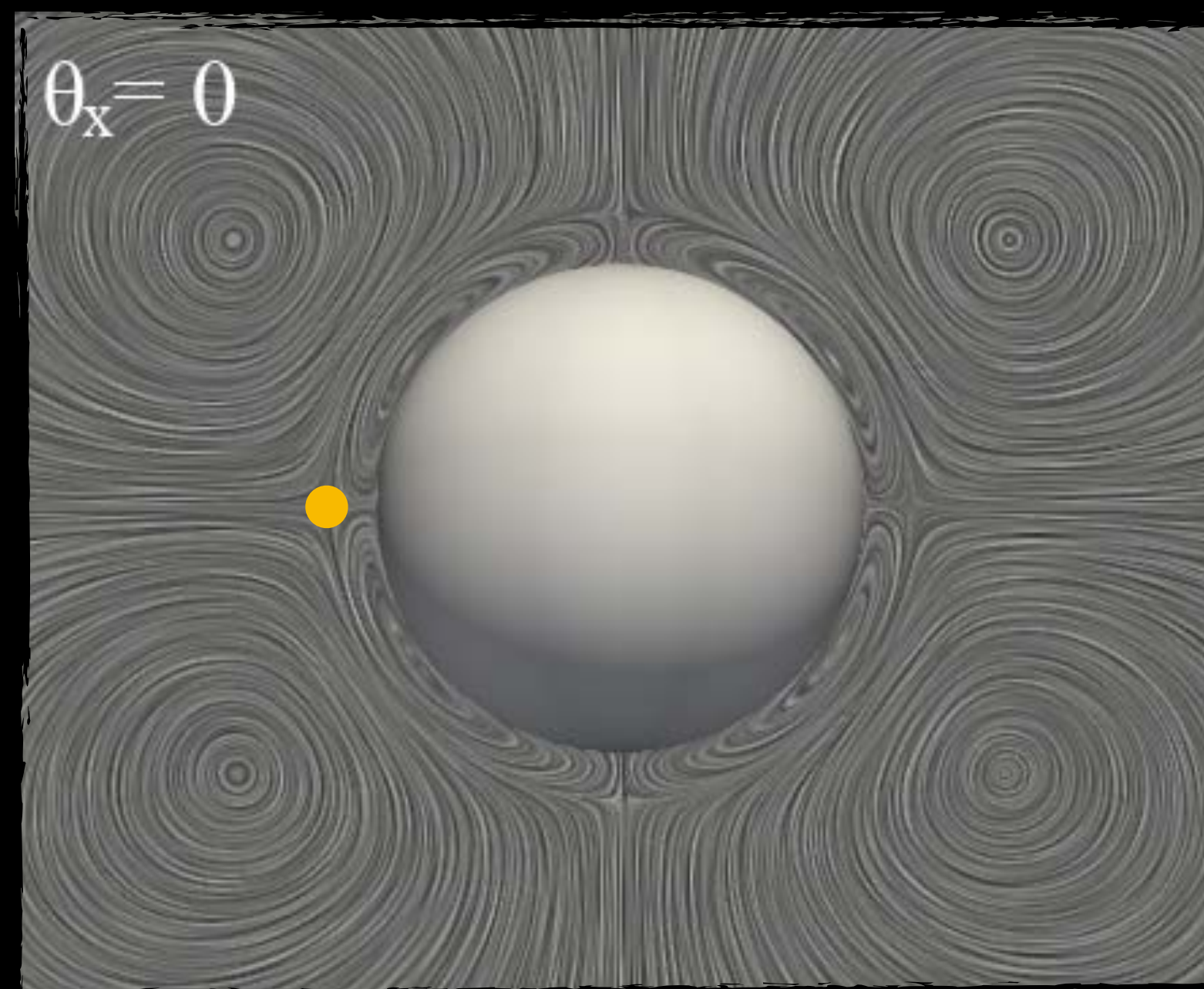
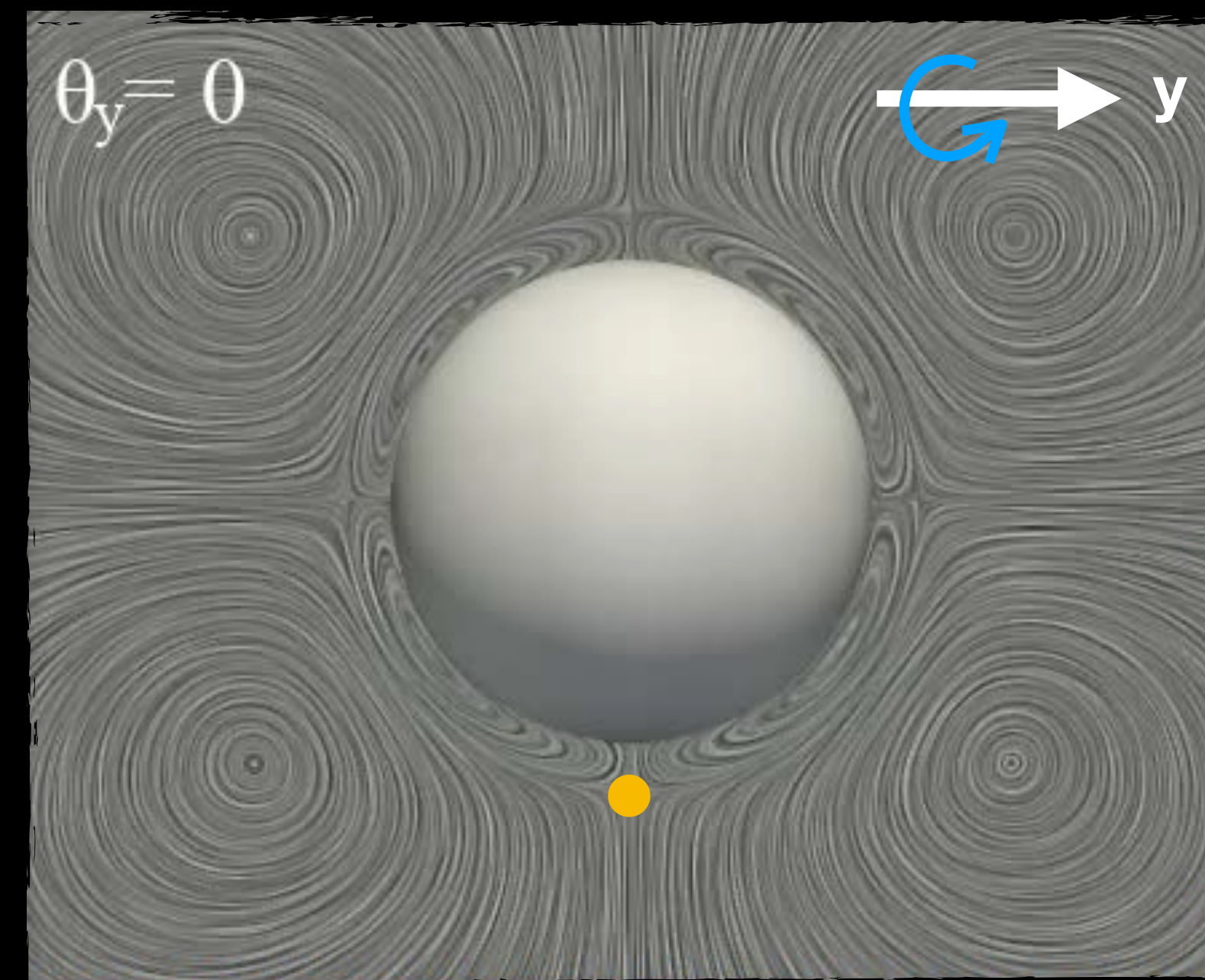
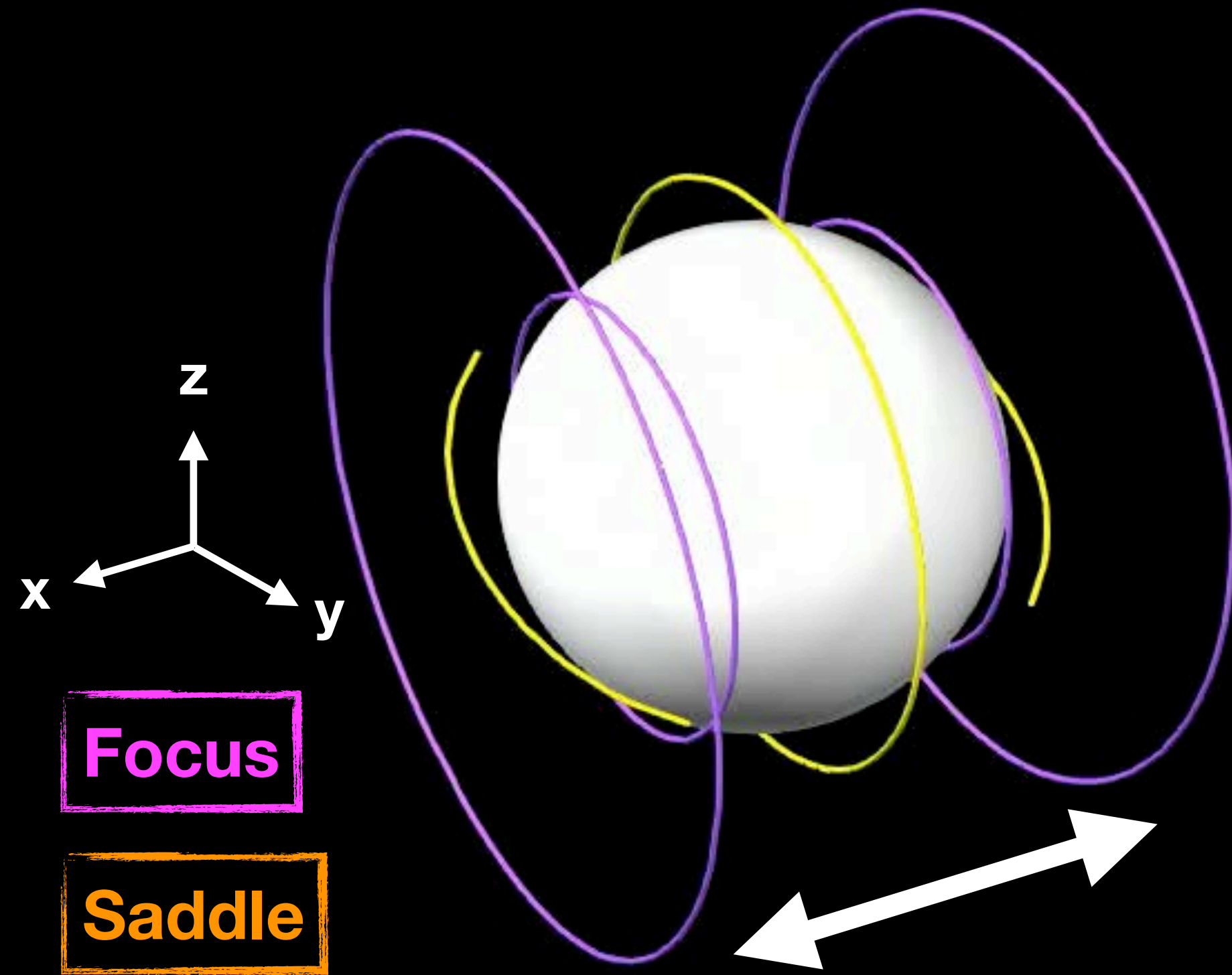
**Saddle**



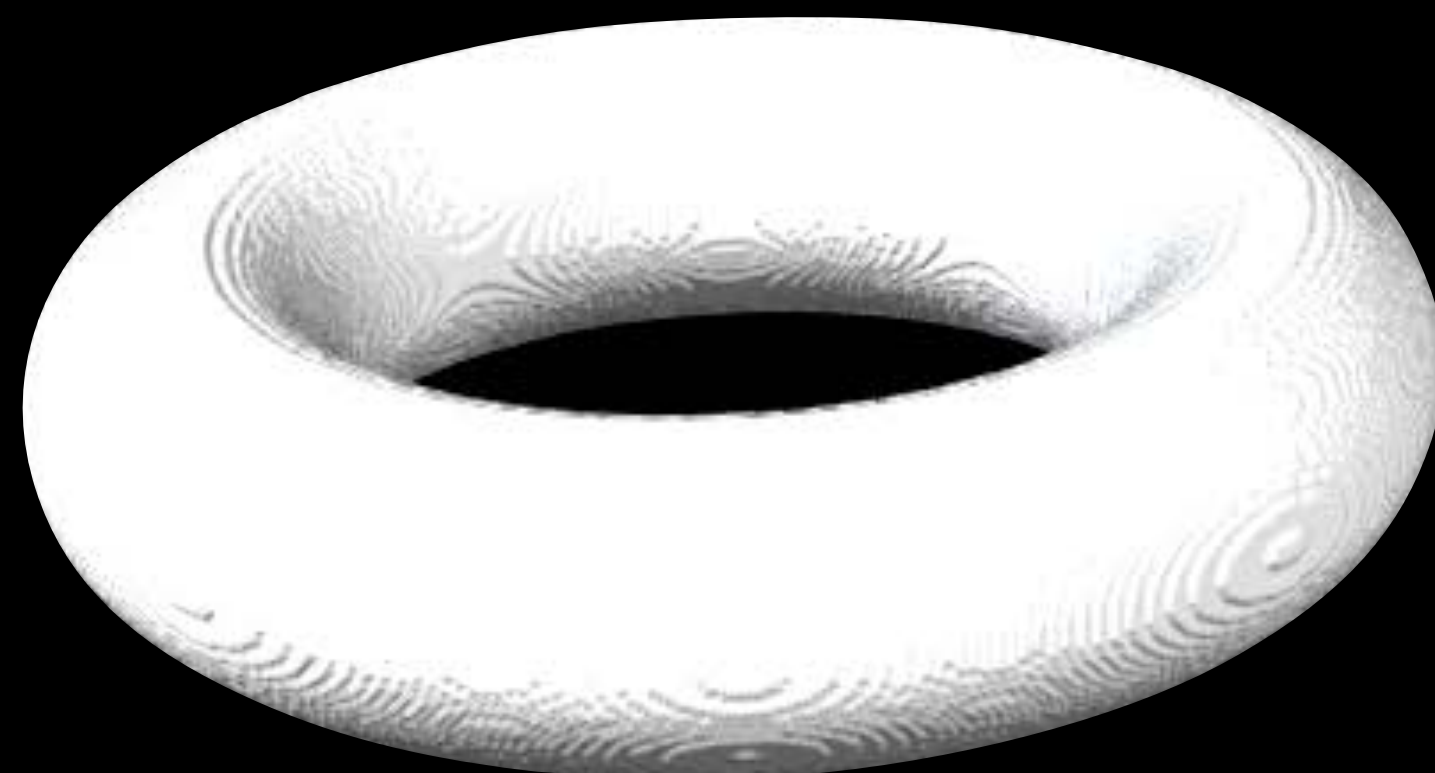
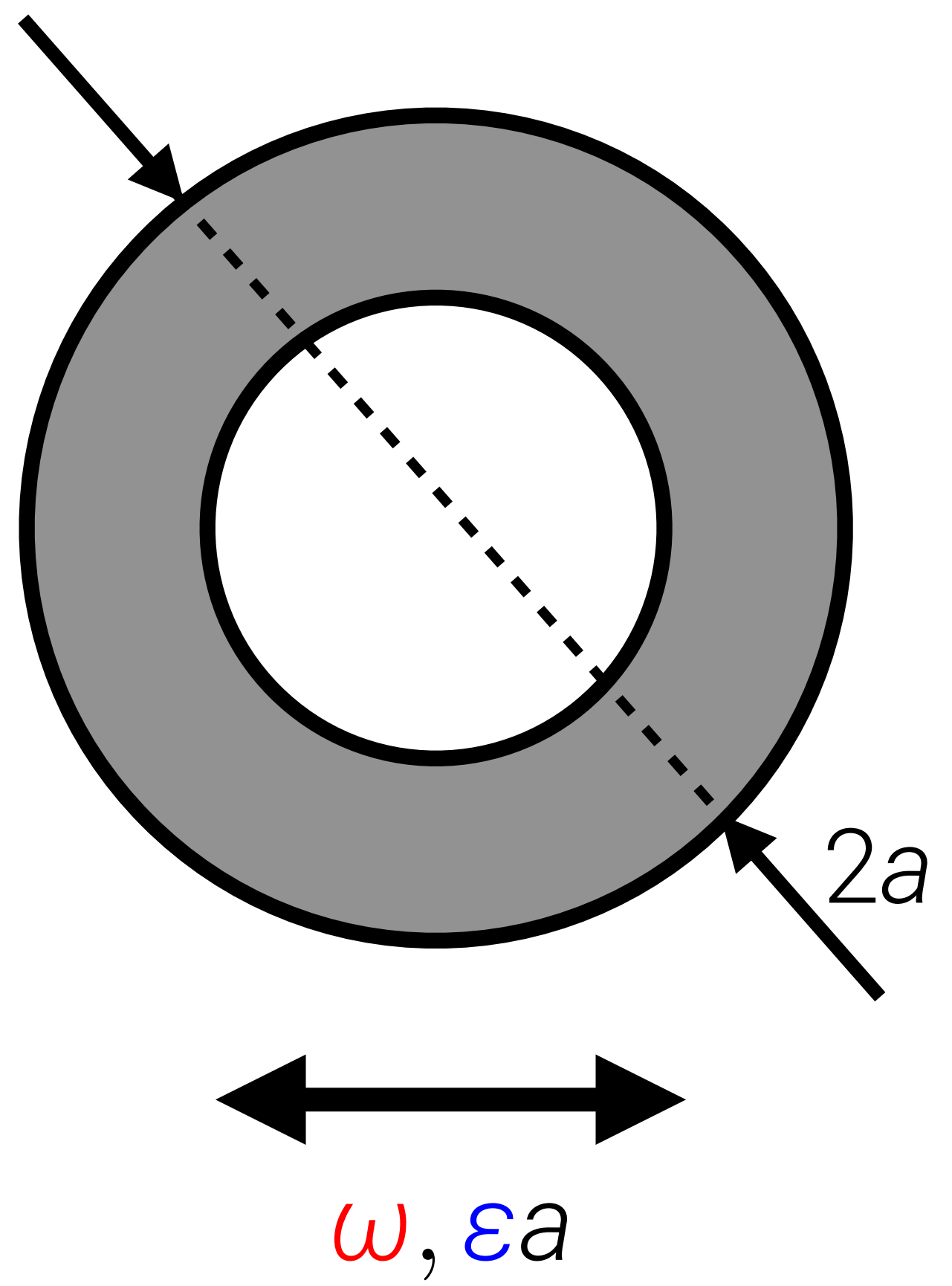




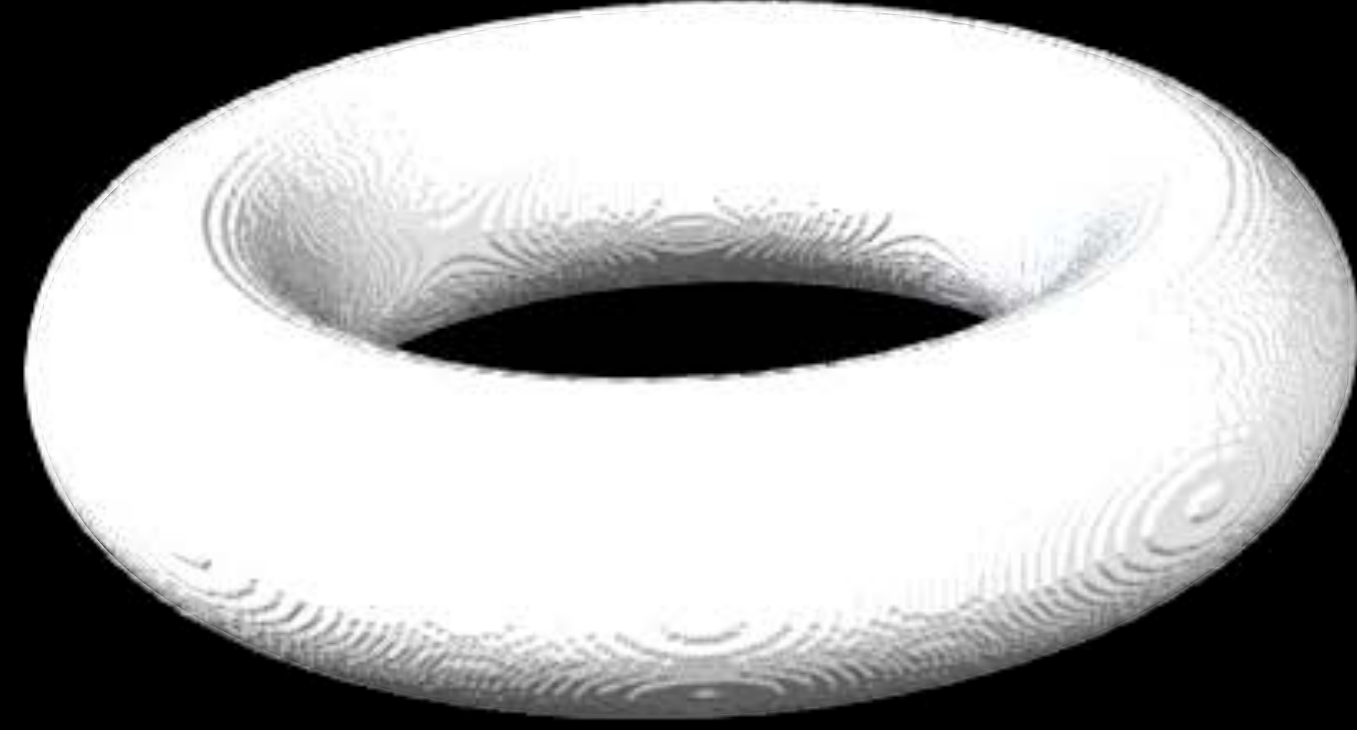






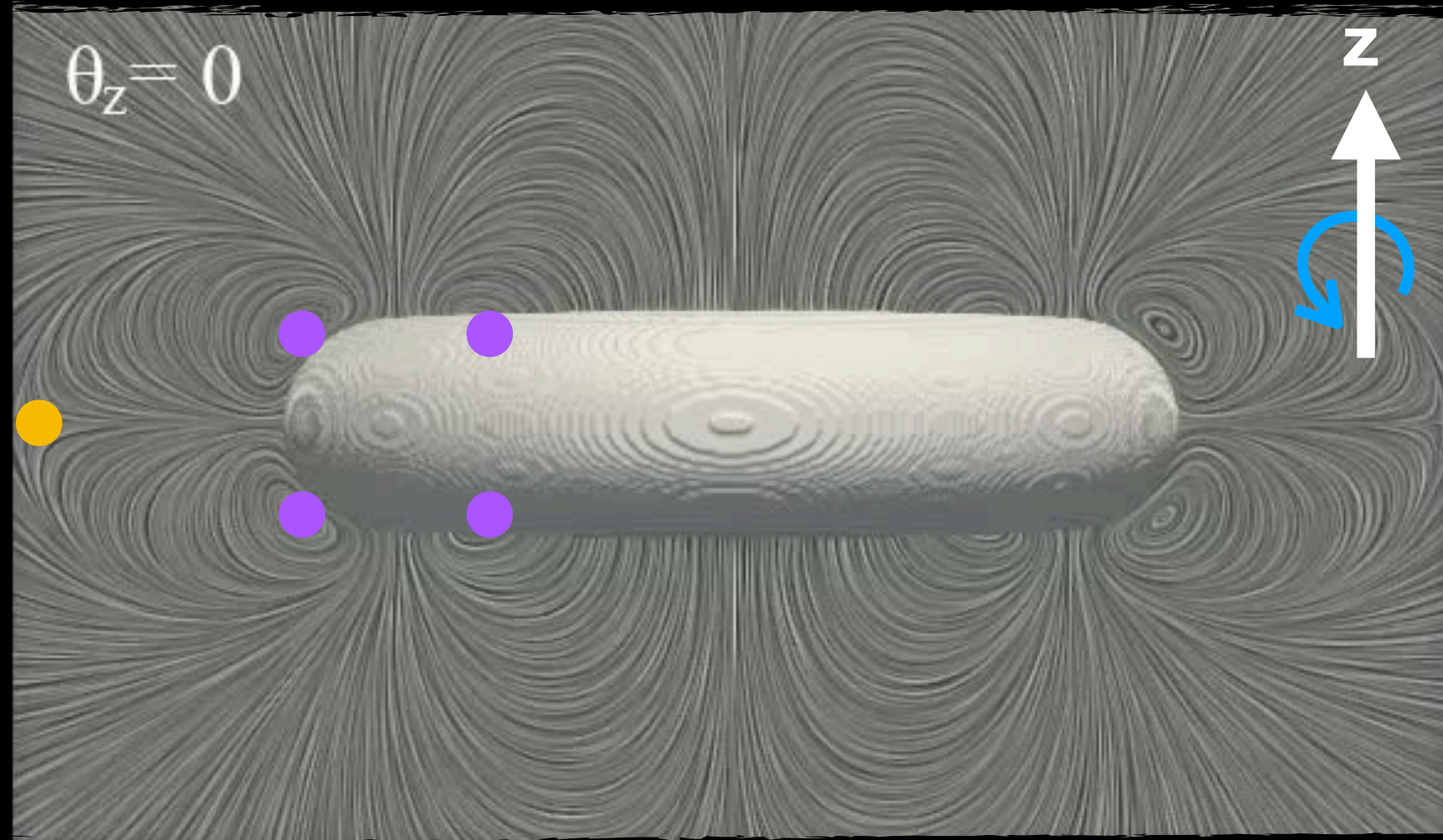
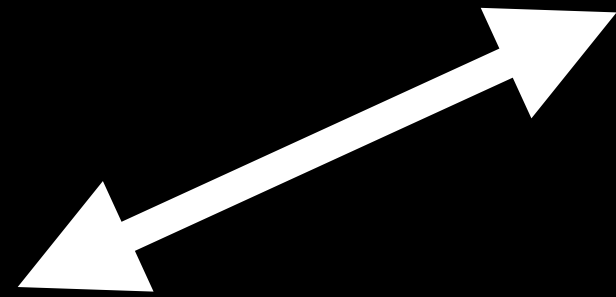
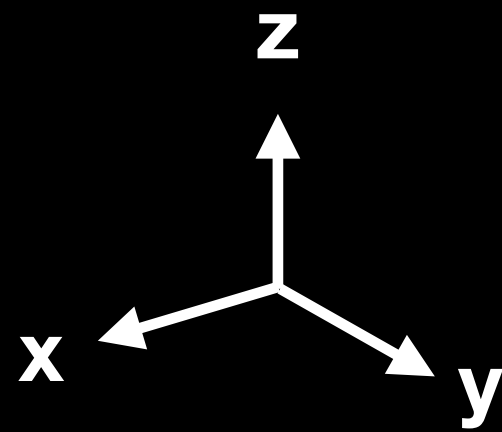




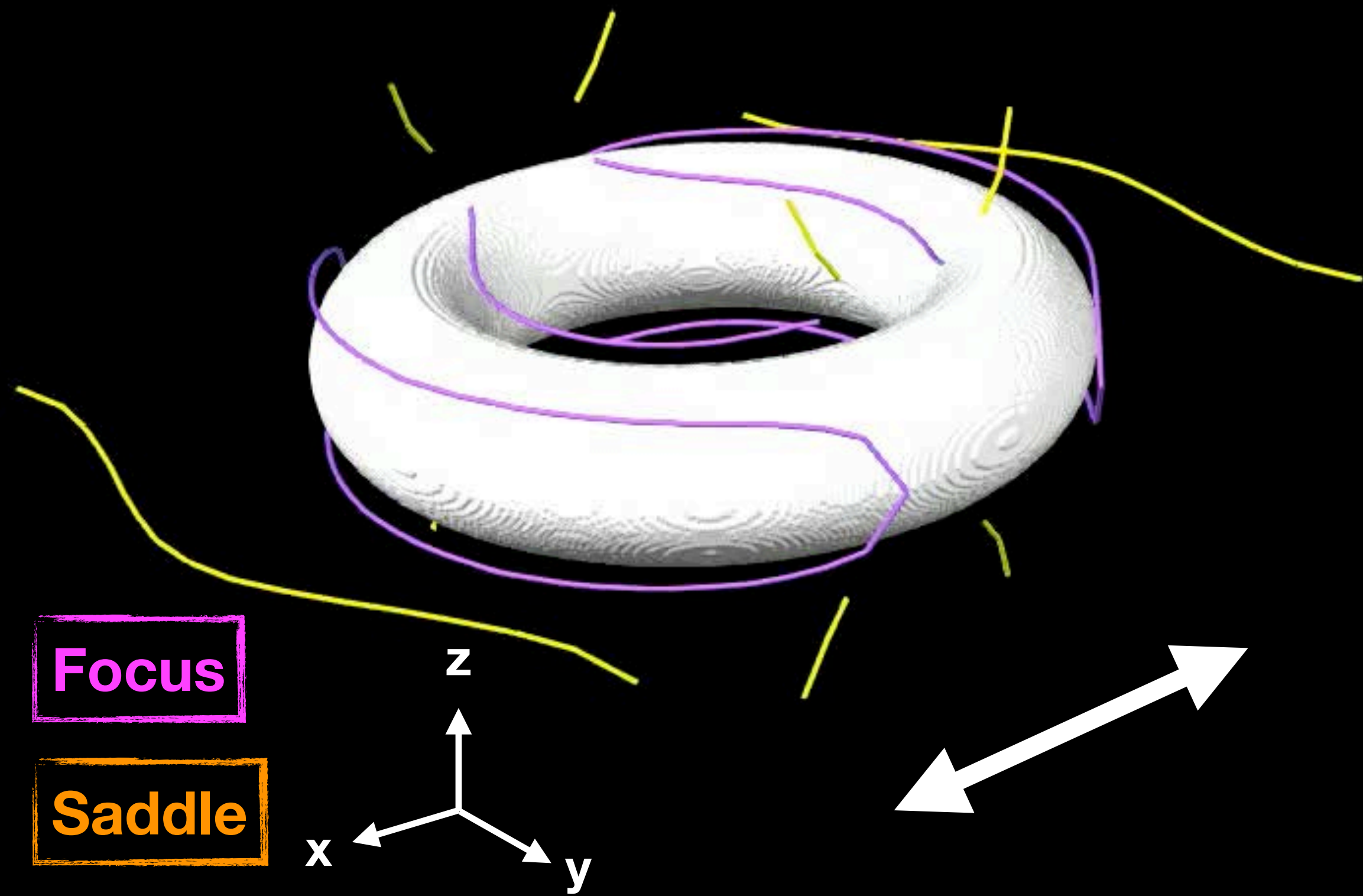


Focus

Saddle

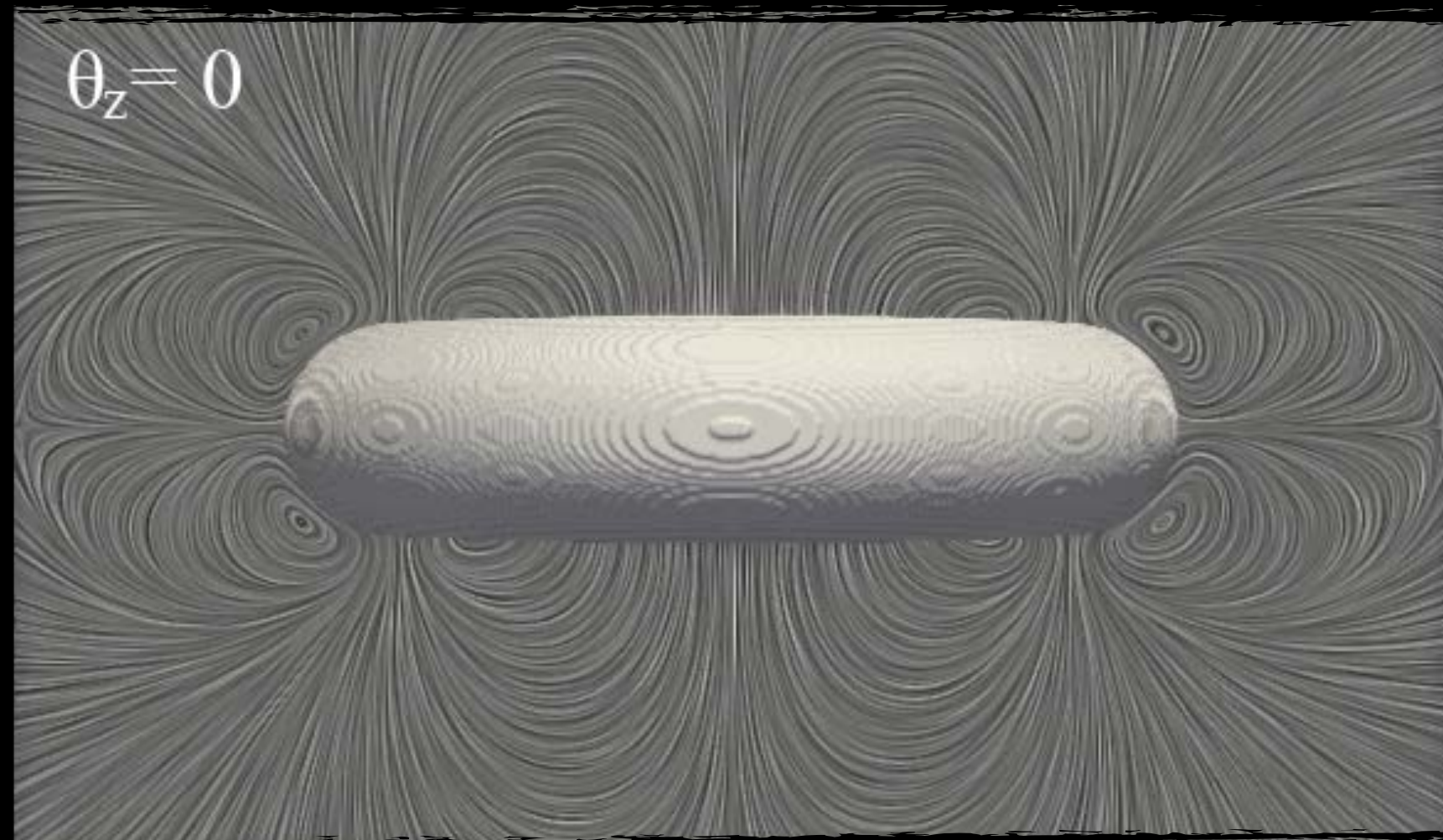




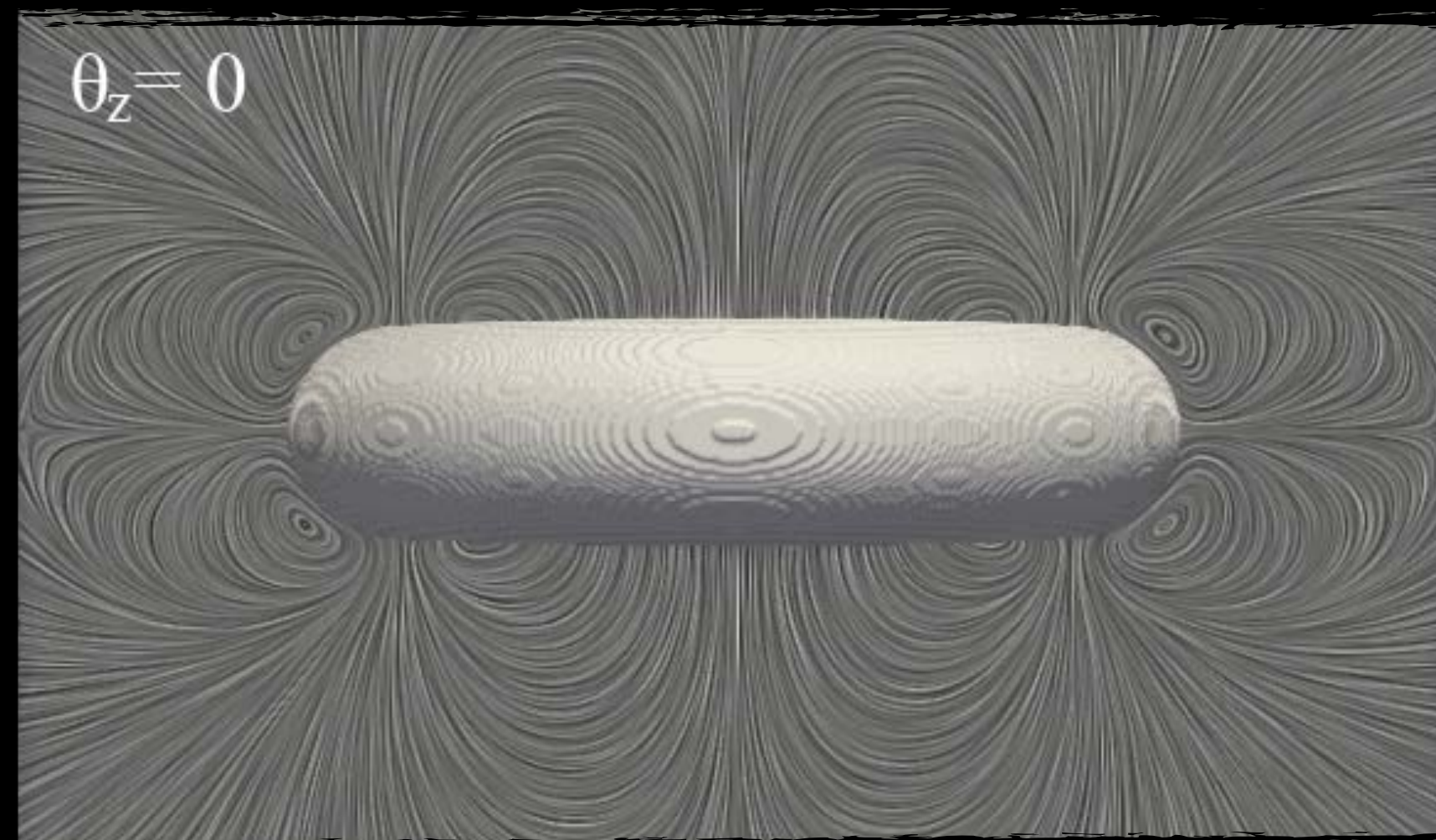
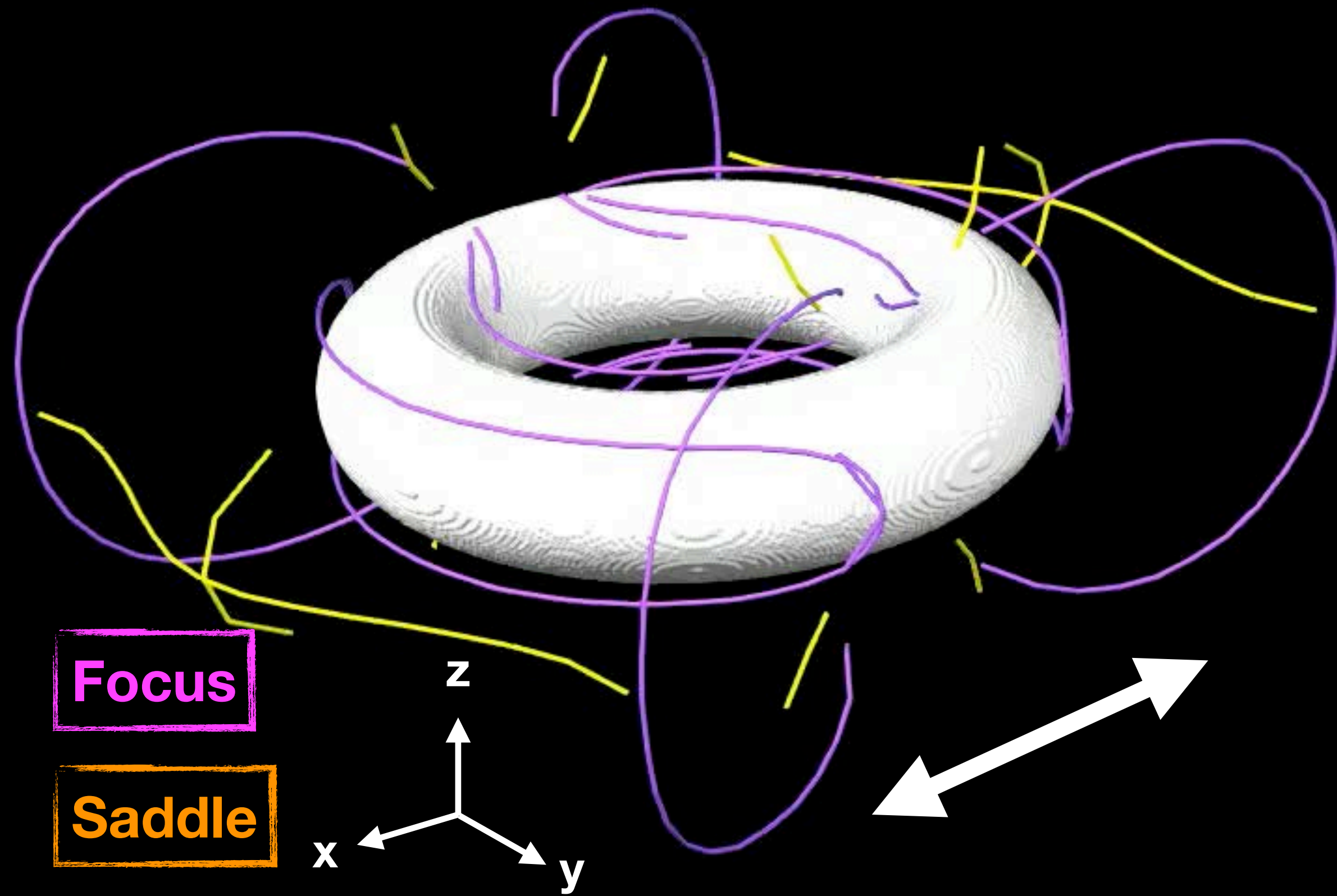


**Focus**

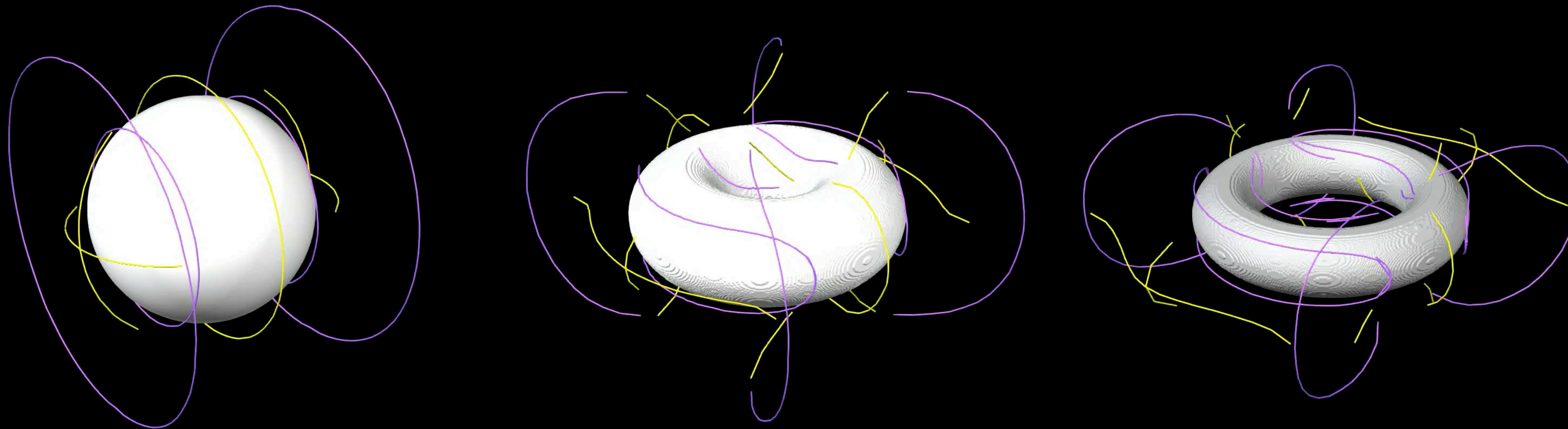
**Saddle**















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